

# Часть 1

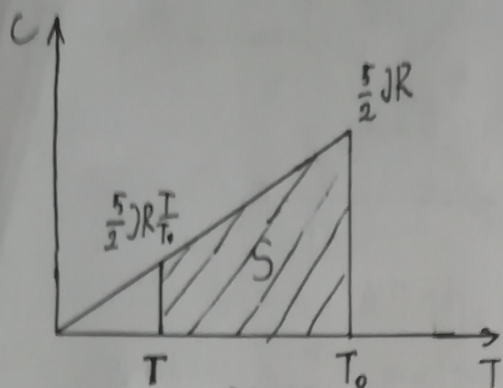
Олимпиада: **Физика, 11 класс (1 часть)**

Шифр: **21202178**

ID профиля: **282696**

Вариант 2

Найти зависимость  $Q$  от  $T$ , го конного охлаждения цепи:



$$Q = -S = -\left[ (T_0 - T) \cdot \frac{5}{2} JR \frac{T}{T_0} + (T_0 - T) \cdot \frac{\frac{5}{2} JR - \frac{5}{2} JR \frac{T}{T_0}}{2} \right]$$

$$= (T - T_0) \cdot \frac{5}{2} JR \left( \frac{T}{T_0} + \frac{1}{2} - \frac{T}{2T_0} \right) =$$

$$= (T - T_0) \frac{5}{2} JR \left( \frac{1}{2} + \frac{T}{2T_0} \right) = (T - T_0) \frac{5}{4} JR \left( 1 + \frac{T}{T_0} \right)$$

1. Найти  $Q_i$ :

$$Q_i = -Q\left(\frac{T_0}{2}\right) = (T_0 - \frac{T_0}{2}) \frac{5}{4} JR \left( 1 + \frac{1}{2} \right) = \frac{15}{16} JR T_0$$

2. Пусть  $T = T_0 k$ , тогда

$$Q = (T_0 k - T_0) \frac{5}{4} JR (1 + k) = (1+k)(k-1) \frac{5}{4} JR T_0$$

3. По 3(9):

$$Q = \Delta U + A \Rightarrow A = Q - \Delta U = (1+k)(k-1) \frac{5}{4} JR T_0 - \frac{3}{2} JR (T - T_0) =$$

$$= (1+k)(k-1) \frac{5}{4} JR T_0 - \frac{3}{2} JR T_0 (k-1) = JR T_0 (k-1) \left( \frac{5}{4}(k+1) - \frac{3}{2} \right) =$$

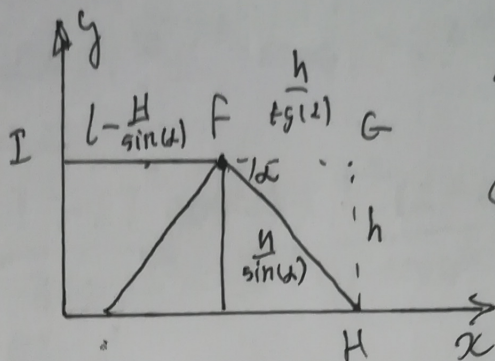
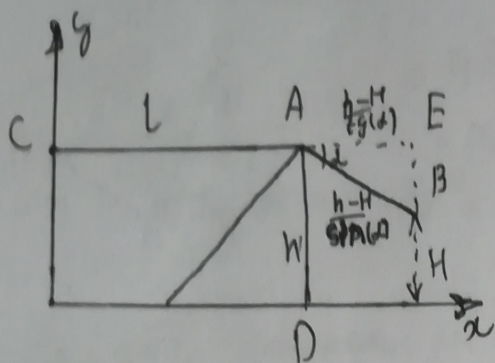
$$= JR T_0 (k-1) \left( \frac{5}{4}k + \frac{5}{4} - \frac{6}{4} \right) = JR T_0 (k-1) \left( \frac{5}{4}k - \frac{1}{4} \right) = \frac{1}{4} JR T_0 (k-1)(5k-1)$$

4.  $(k-1)(5k-1)$  - парабола, корни  $k_1 = 1, k_2 = \frac{1}{5} \Rightarrow k_{\min} = \frac{k_1 + k_2}{2} = \frac{(\frac{6}{5})}{2} = \frac{3}{5}$

$$5. A_{\min} = \frac{1}{4} JR T_0 \left( \frac{3}{5} - 1 \right) (3 - 1) = \frac{1}{4} \cdot \left( -\frac{2}{5} \right) \cdot 2 JR T_0 = -\frac{1}{5} JR T_0$$

$$\text{Ответ: } \frac{15}{16} JR T_0; \frac{3}{5} T_0; -\frac{1}{5} JR T_0$$

Условие  
N1.



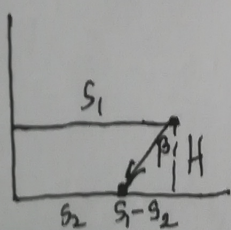
$$\begin{aligned} \cos(\alpha) &= \frac{4}{5} \Rightarrow \\ \sin(\alpha) &= \frac{3}{5} \\ \operatorname{tg}(\alpha) &= \frac{3}{4} \\ \operatorname{ctg}(\alpha) &= \frac{4}{3} \end{aligned}$$

1. Пусть  $AC=L$ ,  $AD=h$ , тогда  $EB=h-H \Rightarrow$   
 $\Rightarrow AB = \frac{h-H}{\sin(\alpha)}$ , тогда гипотенуза  $L + \frac{h-H}{\sin(\alpha)}$ ;  $AE = \frac{h-H}{\operatorname{tg}(\alpha)}$

2. Попробуем, как шар укат:

$$\begin{aligned} GH=h \Rightarrow FH &= \frac{h}{\sin(\alpha)}, \text{ но } CA+AB = IF+FH \Rightarrow IF = CA+AB - FH = \\ &= L + \frac{h-H}{\sin(\alpha)} - \frac{h}{\sin(\alpha)} = L - \frac{H}{\sin(\alpha)}; FG = \frac{h}{\operatorname{tg}(\alpha)} \end{aligned}$$

3. Изобразим караванное и конечное положение шара:



$$s_1 = CA + AE = L + \frac{h}{\operatorname{tg}(\alpha)} - \frac{H}{\operatorname{tg}(\alpha)}$$

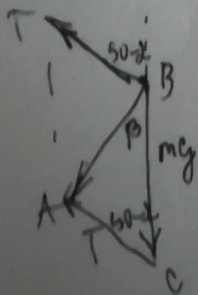
$$s_2 = IF + FG = L - \frac{H}{\sin(\alpha)} + \frac{h}{\operatorname{tg}(\alpha)}$$

$$s_1 - s_2 = \frac{H}{\sin(\alpha)} - \frac{H}{\operatorname{tg}(\alpha)} = H \left( \frac{1}{\sin(\alpha)} - \frac{1}{\operatorname{tg}(\alpha)} \right)$$

$$\operatorname{tg}(\beta) = \frac{s_1 - s_2}{H} = \frac{1}{\sin(\alpha)} - \frac{1}{\operatorname{tg}(\alpha)} = \frac{5}{3} - \frac{4}{3} = \frac{1}{3} \Rightarrow \boxed{\operatorname{tg}(\beta) = \frac{1}{3}}, \beta - \text{угол}$$

между ускорением шара и вертикалью

4. Рассмотрим силы, действующие на шар:

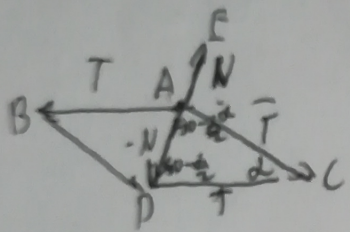


$$\Delta BAC = 180 - \beta - 90 + \alpha = 90 - \beta + \alpha$$

$$\frac{mg}{\sin(90 - (\beta - \alpha))} = \frac{T}{\sin(\beta)} \quad T = \frac{\sin(\beta)}{\cos(\beta - \alpha)} mg$$

Условие

5. Рассмотрим силы, действующие на A.



$$\angle BAD = \angle DAC = \frac{180 - \alpha}{2} = 90 - \frac{\alpha}{2} \Rightarrow \angle ADC = \angle DAC = 90 - \frac{\alpha}{2} \Rightarrow$$

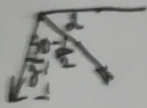
$$\Rightarrow \angle C = \alpha$$

$$N^2 = T^2 + T^2 - 2T^2 \cos(\alpha) = T^2(2 - 2\cos(\alpha)) \Rightarrow$$

$$\Rightarrow N = T \sqrt{2 - 2\cos(\alpha)} = \sqrt{2} T \sqrt{1 - \cos(\alpha)} = 2T \sin\left(\frac{\alpha}{2}\right)$$

6. Найдем проекцию N на OX:

$$\varphi = \left(90 - \frac{\alpha}{2} + \alpha\right) - 90 = \frac{\alpha}{2} \Rightarrow N_x = 2T \sin\left(\frac{\alpha}{2}\right) \cdot \sin\left(\frac{\alpha}{2}\right) = 2T \sin^2\left(\frac{\alpha}{2}\right)$$

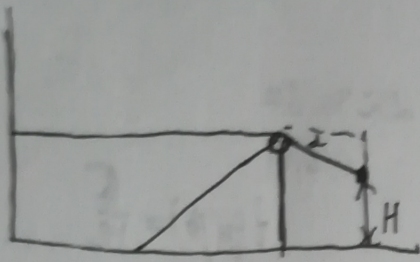


7. По 3CЭ:  $mgH = \frac{M V_k^2}{2} + \frac{m V_{kn}^2}{2}$

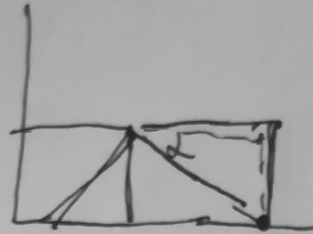
Ответ: 1)  $\arctg\left(\frac{1}{3}\right)$

reprodukt

$$1. \frac{5}{12}$$

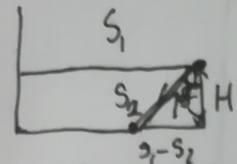
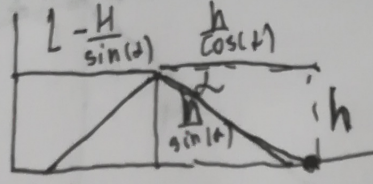
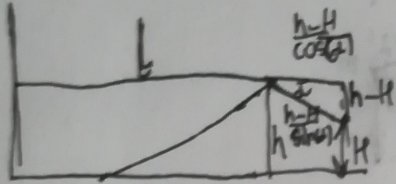


=>



$$\cos(\alpha) = \frac{4}{5}$$

$$\sin(\alpha) = \frac{3}{5}$$



$$L + \frac{h-H}{\sin(\alpha)} - \text{ganzes Kraus}$$

$$L + \frac{h}{\sin(\alpha)} - \frac{H}{\sin(\alpha)}$$

$$S_1 = L + \frac{h-H}{\cos(\alpha)}$$

$$S_2 = L - \frac{H}{\sin(\alpha)} + \frac{h}{\cos(\alpha)}$$

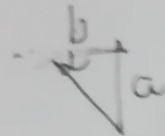
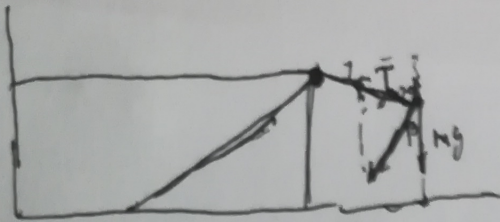
$$\text{tg}(\beta) = \frac{H(\frac{1}{\sin(\alpha)} - \frac{1}{\cos(\alpha)})}{H(\frac{1}{\sin(\alpha)} - \frac{1}{\cos(\alpha)})}$$

$$= \frac{1}{\sin(\alpha)} - \frac{1}{\cos(\alpha)} =$$

$$= \frac{5}{3} - \frac{5}{4} = \frac{20}{12} - \frac{15}{12} = \frac{5}{12}$$

$$S_1 - S_2 = \left( L + \frac{h-H}{\cos(\alpha)} \right) - \left( L - \frac{H}{\sin(\alpha)} + \frac{h}{\cos(\alpha)} \right) = \frac{H}{\sin(\alpha)} - \frac{h}{\cos(\alpha)}$$

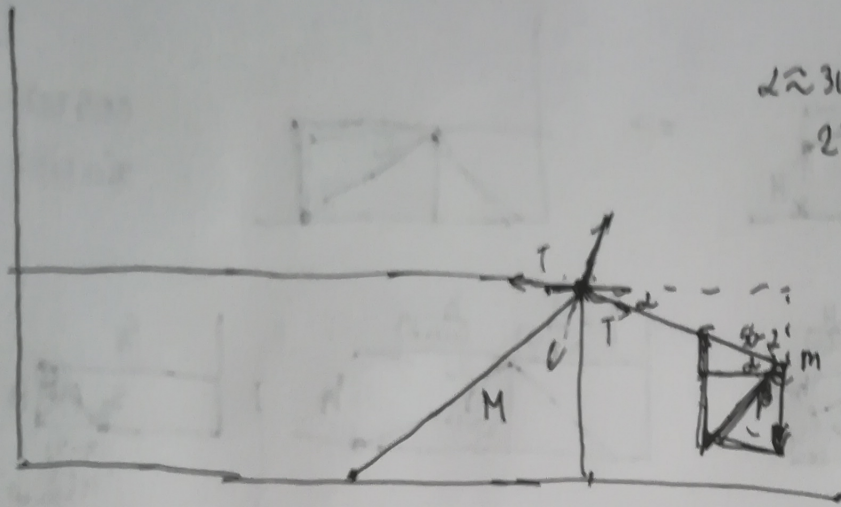
$$\frac{1}{\sin(\alpha)} - \frac{1}{\cos(\alpha)} = \frac{\cos(\alpha) - \sin(\alpha)}{\sin(\alpha)\cos(\alpha)} \quad \text{tg}(\beta) = \frac{5}{12}$$



$$\frac{a}{b} = \frac{5}{12}$$

$$b = \frac{a}{\frac{5}{12}}$$

Кепробла



$$\alpha \approx 36.87^\circ$$

$$22,61$$

$$\tan(\beta) = \frac{5}{12}$$

чернобук

$$A = (T_0 - T) \frac{5}{4} JR \left(1 + \frac{T}{T_0}\right) - \frac{3}{2} JR (T_0 - T)$$

$$T = k T_0$$

$$A = (T_0 - k T_0) \frac{5}{4} JR k - \frac{3}{2} JR (T_0 - T)$$

$$(Q \leq 0) = (T - T_0) \frac{5}{4} JR \left(1 + \frac{T}{T_0}\right)$$

$$\Delta \mathcal{K} = \frac{3}{2} JR (T - T_0)$$

$$A = (T - T_0) \frac{5}{4} JR \left(1 + \frac{T}{T_0}\right) - \frac{3}{2} JR (T - T_0)$$

$$A = (k T_0 - T_0) \frac{5}{4} JR (1+k) - \frac{3}{2} JR (k T_0 - T_0) = JR T_0 (k-1) \left(\frac{5}{4} - \frac{3}{2}\right) =$$

$$= JR T_0 (k-1) \left(\frac{5}{4} (k+1) - \frac{3}{2}\right) =$$

$$= JR T_0 (k-1) \left(\frac{5}{4} k + \frac{5}{4} - \frac{6}{4}\right) =$$

$$= JR T_0 (k-1) \left(\frac{5}{4} k - \frac{1}{4}\right) =$$

$$= \frac{1}{4} JR T_0 (k-1) (5k-1)$$

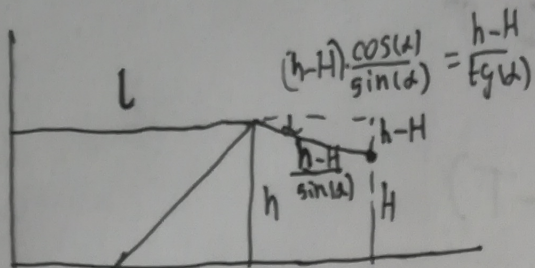
$$A_{\min} = \frac{1}{4} JR T_0 \left(\frac{3}{5} - 1\right) (3-1) =$$

$$= \frac{1}{4} JR T_0 \left(-\frac{2}{5}\right) (2) = -\frac{1}{5} JR T_0$$

$$k_1 = 1 \quad k_{\min} = \frac{1 + \frac{1}{5}}{2} = \frac{3}{5}$$

$$= \frac{3}{5}$$

Копировка



$$L_{\text{св}} = l + \frac{h-H}{\sin(\alpha)}$$

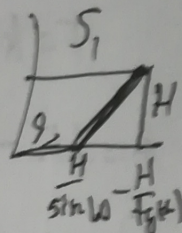
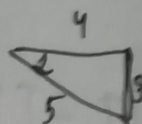
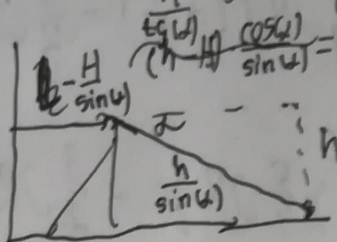
$$S_1 = l + \frac{h-H}{\text{tg}(\alpha)}$$

$$\text{tg}(\alpha) = \frac{1}{3}$$

$$S_1 - S_2 = l + \frac{h}{\text{tg}(\alpha)} - \frac{H}{\text{tg}(\alpha)} + \frac{H}{\sin(\alpha)}$$

$$\sin(\alpha) = \frac{3}{5}$$

$$h \text{ tg}(\alpha) = \frac{3}{4}$$



$$S_2 = l - \frac{H}{\sin(\alpha)} + \frac{h}{\text{tg}(\alpha)}$$

$$\text{tg}(\beta) = \frac{1}{\sin(\alpha)} - \frac{1}{\text{tg}(\alpha)}$$

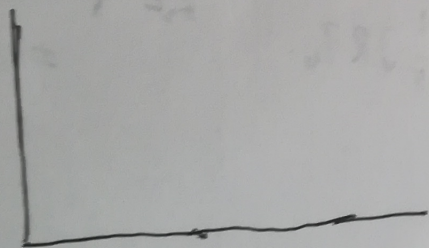
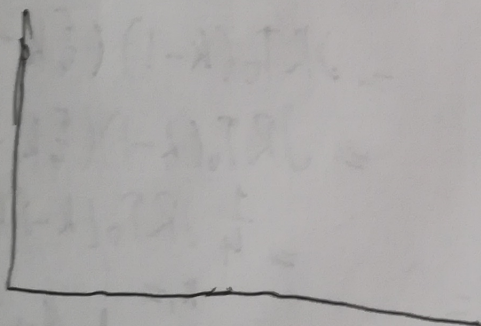
$$= \frac{5}{3} - \frac{4}{3} = \frac{1}{3}$$

$$\frac{h}{\text{tg}(\alpha)} = \frac{H}{\sin(\alpha)} - \frac{H}{\text{tg}(\alpha)}$$

$$E_1 = mgh$$

$$E_2 = 0$$

$$\Rightarrow mgh = \frac{MV^2}{2}$$

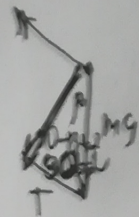
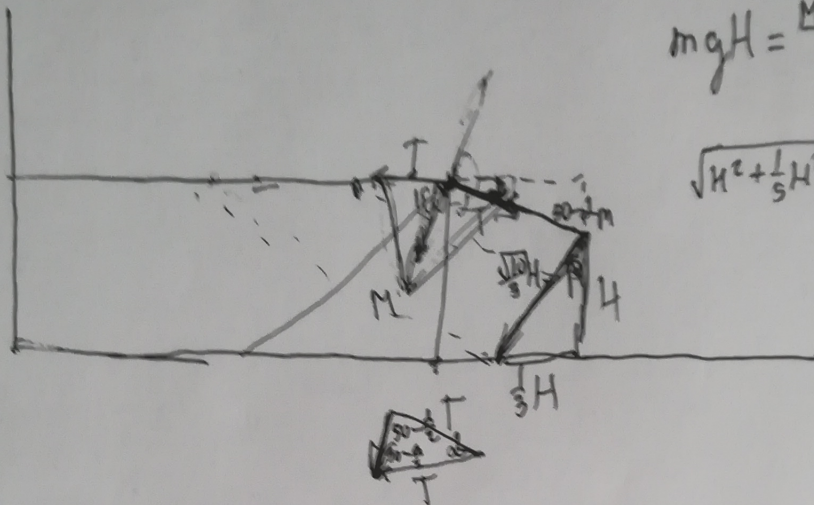




неравна

$$mgH = \frac{Mv^2}{2}$$

$$\sqrt{H^2 + \frac{1}{5}H^2} = H \sqrt{\frac{10}{5}} = \frac{\sqrt{10}}{3} H$$



$$\frac{T}{\sin(\alpha)} = \frac{mg}{\sin(\beta - \alpha)}$$



$$T = \frac{\sin(\beta)}{\cos(\beta - \alpha)} mg$$



Черновик

1.  $J$  мал  $T_0$   $C(T) = \frac{5}{2} R \frac{T}{T_0}$

$c_m = \frac{\Delta Q}{J \Delta T} = C(T) = \frac{5}{2} R \frac{T}{T_0}$

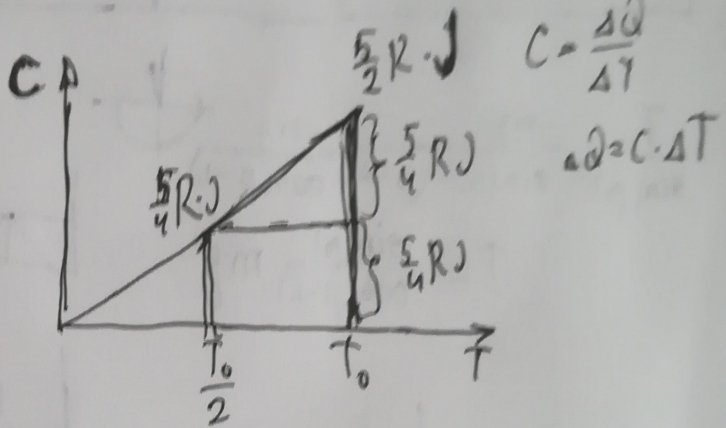
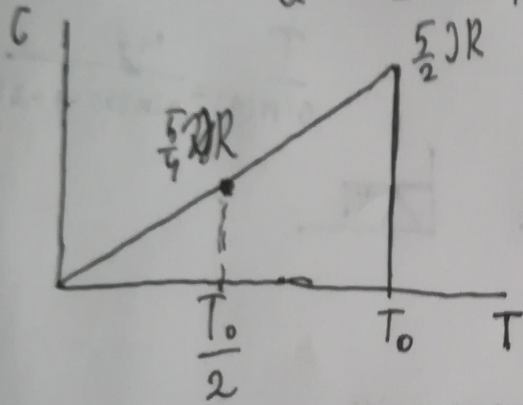
$C = \frac{\Delta Q}{\Delta T}$

$\Delta Q = C \cdot \Delta T = J$

$C = \frac{\Delta Q}{\Delta T}$

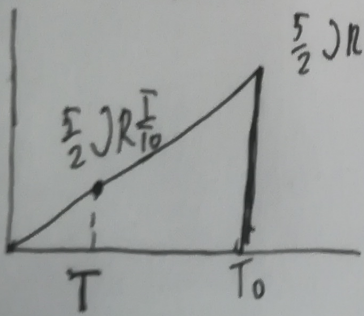
$\Delta Q$   
 $\frac{Q'}{J} = \frac{5}{2} R \frac{T}{T_0}$   
 $Q' = \frac{5}{2} J R \frac{T}{T_0}$

$u = E \sim RT$



$\frac{T_0}{2} \cdot \frac{5}{4} J R + \frac{1}{2} \left( \frac{T_0}{2} \cdot \frac{5}{4} J R \right) = \frac{3}{2} \cdot \frac{T_0}{2} \cdot \frac{5}{4} J R = \frac{15}{16} J R T_0$

$Q = \frac{3}{2} J R T + A =$



$Q = (T_0 - T) \cdot \frac{5}{2} J R \frac{T}{T_0} + (T_0 - T) \left( \frac{5}{2} J R - \frac{5}{2} J R \frac{T}{T_0} \right) =$

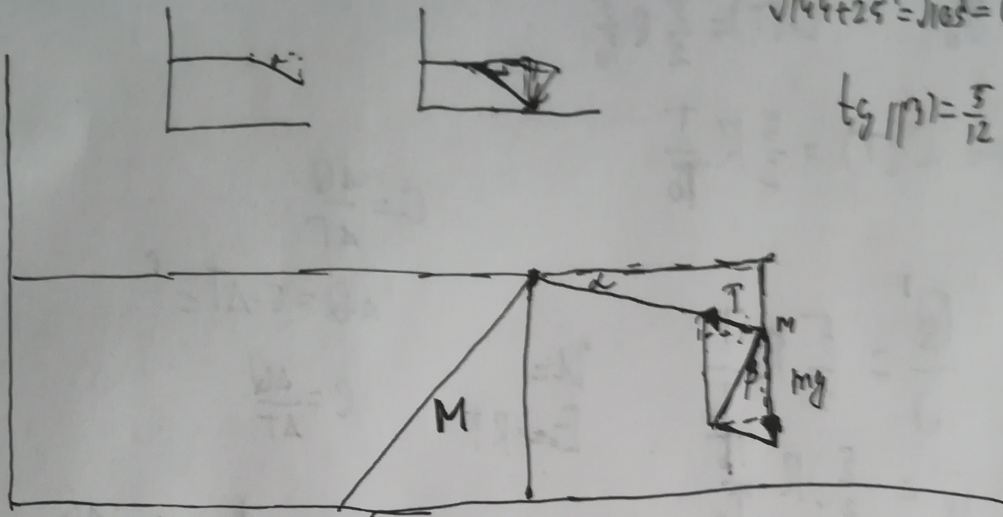
$= (T_0 - T) \left( \frac{5}{2} J R \frac{T}{T_0} + \frac{\frac{5}{2} J R (1 - \frac{T}{T_0})}{2} \right) =$

$= (T_0 - T) \cdot \frac{5}{2} J R \left( \frac{T}{T_0} + \frac{1}{2} - \frac{T}{2T_0} \right) =$

$= (T_0 - T) \cdot \frac{5}{2} J R \left( \frac{1}{2} + \frac{T}{2T_0} \right)$

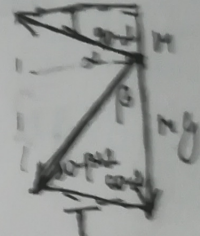
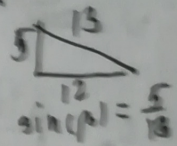
$A = (T_0 - T) \frac{5}{2} J R \left( \frac{1}{2} + \frac{T}{2T_0} \right) - \frac{3}{2} J R T \quad T = \frac{T_0}{2} \quad \frac{T_0}{2} \cdot \frac{5}{2} J R \left( \frac{2}{2} + \frac{1}{2} \right) = J R T_0 \frac{15}{16}$

Угол наклона



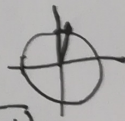
$$\sqrt{144+25} = \sqrt{169} = 13$$

$$\operatorname{tg}(\alpha) = \frac{5}{12}$$



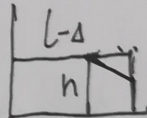
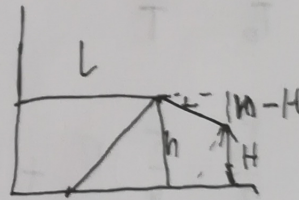
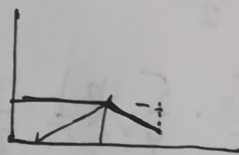
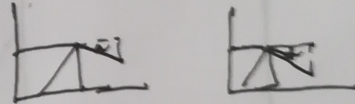
$$180 - 90 + \alpha - \beta = 90 - \beta + \alpha$$

$$\frac{T}{\sin(\beta)} = \frac{mg}{\sin(90 - (\beta + \alpha))} = \frac{mg}{\cos(\beta + \alpha)}$$



$$T = \frac{\sin(\alpha)}{\cos(\beta + \alpha)} mg$$

$$\frac{T}{\sin(\alpha)} = \frac{mg}{\sin(90 - \beta + \alpha)}$$



# Часть 2

Олимпиада: **Физика, 11 класс (2 часть)**

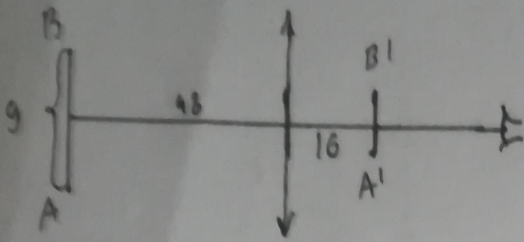
Шифр: **21202178**

ID профиля: **282696**

Вариант 2

Чистовик  
N5

$F = 12 \text{ см}$



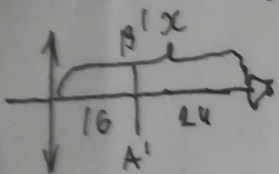
Найдём расстояние от линзы до изображения циферблата:

$$\frac{1}{f} + \frac{1}{d} = \frac{1}{F}$$

$$\frac{1}{f} = \frac{1}{F} - \frac{1}{d} \Rightarrow f = \frac{dF}{d-F} = \frac{48 \cdot 12}{48-12} = \frac{48}{3} = 16 \text{ см}$$

$$\Gamma = \frac{f}{d} = \frac{16}{48} = \frac{1}{3} \Rightarrow h = \frac{1}{3}H = 3 \text{ см} = A'B'$$

Известно, что глаз accommodation на 24 см  $\Rightarrow$  расстояние от глаза до изображения 24 см:

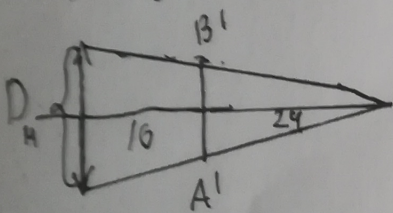


Соответственно глаз удалён от линзы на  $x = 16 + 24 = 40 \text{ см}$

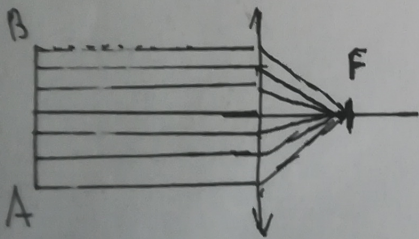
Найдём  $D_m$

из подобия:

$$\frac{D_m}{A'B'} = \frac{16+24}{24} \Rightarrow D_m = 3 \cdot \frac{40}{24} = \frac{40}{8} = 5 \text{ см}$$

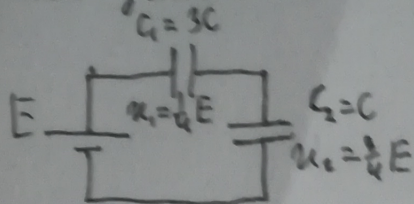


Чтобы не видеть ни одной детали цифр. достаточно поместить небольшой экран в фокусе линзы, т.е. справа на расстоянии 12 см



Ответ: 40 см; 5 см; справа от линзы на расстоянии 12 см от неё

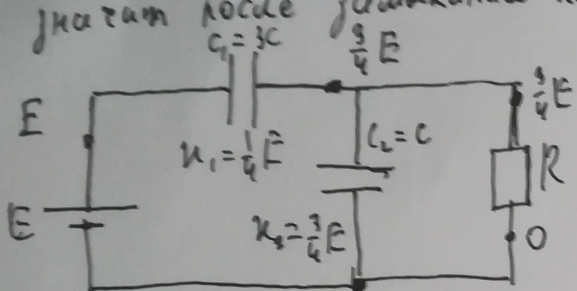
До замыкания ключа цепь выглядит таким образом:



$$C_{\text{общ}} = \frac{C_1 C_2}{C_1 + C_2} = \frac{3}{4} C \Rightarrow q = C_{\text{общ}} \cdot E = \frac{3}{4} CE \Rightarrow U_1 = \frac{q}{C_1} = \frac{\frac{3}{4} CE}{3C} = \frac{1}{4} E; U_2 = \frac{q}{C_2} = \frac{3}{4} E$$

Напряжения на конденсаторах не могут измениться скачкообразно,

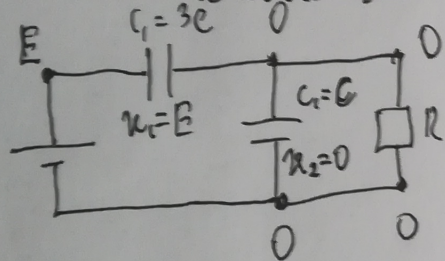
значит после замыкания ключа  $U_1$  и  $U_2$  останутся прежними:



Рассмотрим потенциалы,  $U_R = \frac{3}{4} E \Rightarrow$

$$I_R = \frac{U_R}{R} = \boxed{\frac{3E}{4R}}$$

Установившаяся цепь:



Используем 3СЭ

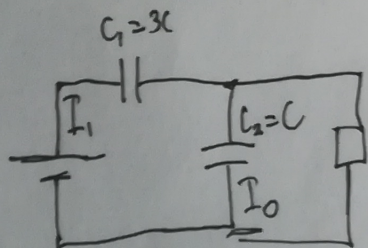
$$E_1 = \frac{3C(\frac{1}{4}E)^2}{2} + \frac{C(\frac{3}{4}E)^2}{2} = \frac{3CE^2}{32} + \frac{9CE^2}{32} = \frac{12CE^2}{32} = \frac{3CE^2}{8}$$

$$E_2 = \frac{3CE^2}{2} + Q$$

$$E_2 - E_1 = A_E = E \Delta q$$

$$\Delta q = 3CE - \frac{3}{4}CE \Rightarrow \frac{3CE^2}{2} + Q = \frac{3CE^2}{8} = E(3CE - \frac{3}{4}CE)$$

$$Q = \frac{3CE^2}{8} - \frac{3CE^2}{2} + E(3CE - \frac{3}{4}CE) = CE^2 \cdot \frac{9}{4} - \frac{9}{8}CE^2 = \boxed{\frac{9}{8}CE^2}$$



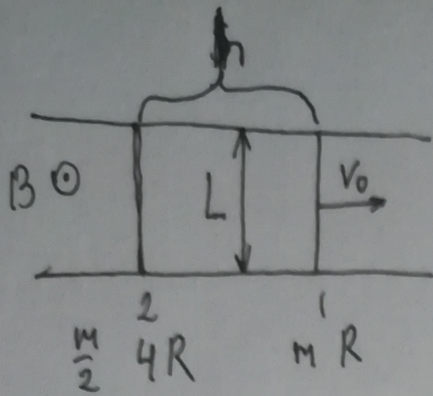
$$I_0 = C_2 U_2' \Rightarrow U_2' = \frac{I_0}{C}$$

$$U_2' = U_1' = \frac{I_1}{C_1} = \frac{I_1}{3C} \Rightarrow \frac{I_1}{3C} = \frac{I_0}{C} \Rightarrow I_1 = 3I_0$$

$$I_R = I_0 + I_1 = 4I_0; U_R = I_R \cdot R = \boxed{4I_0 R}$$

Ответ:  $\frac{3E}{4R}; \frac{9}{8}CE^2; 4I_0 R$

Число Вук  
N4



$$1) \Phi = BS = BLh$$

$$2) \mathcal{U} = \Phi' = BLv_0$$

$$3) I = \frac{\mathcal{U}}{4R + R} = \frac{BLv_0}{5R}$$

$$4) F = BIL = B \cdot \frac{BLv_0}{5R} \cdot L = \frac{B^2 L^2 v_0}{5R}$$

$$5) a_2 = \frac{F}{m_2} = \frac{2B^2 L^2 v_0}{5mR}$$

7) Через продолжительный промежуток времени скорость перемычек станет равной  $v_1 = v_2 = V$

По ЗСЭ:

$$E_1 = E_2$$

$$E_1 = \frac{mv_0^2}{2}$$

$$E_2 = \frac{(\frac{m}{2})V^2}{2} + \frac{mV^2}{2}$$

$$\Rightarrow \frac{mv_0^2}{2} = \left(\frac{m}{2}\right)\frac{V^2}{2} + \frac{mV^2}{2}$$

$$mv_0^2 = \frac{m}{2}V^2 + mV^2 \Rightarrow v_0^2 = \frac{3}{2}V^2 \Rightarrow V^2 = \frac{2}{3}v_0^2 \Rightarrow V = \sqrt{\frac{2}{3}}v_0$$

$$8. a_2 = a_2' = \frac{2B^2 L^2 (v_1 - v_2)}{5mR}$$

$$a_1 = a_1' = -\frac{B^2 L^2 (v_1 - v_2)}{5mR}$$

$$v_1' - v_2' = -\frac{3B^2 L^2 (v_1 - v_2)}{5mR}$$

$$v_1 - v_2 = V$$

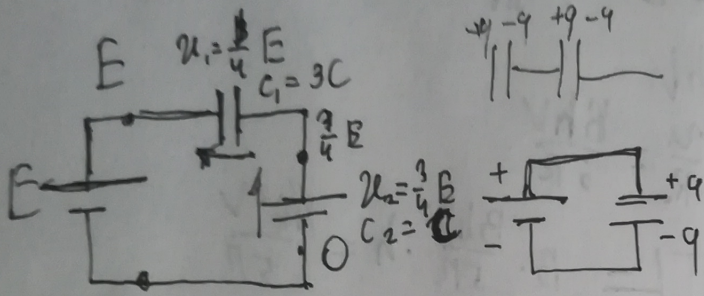
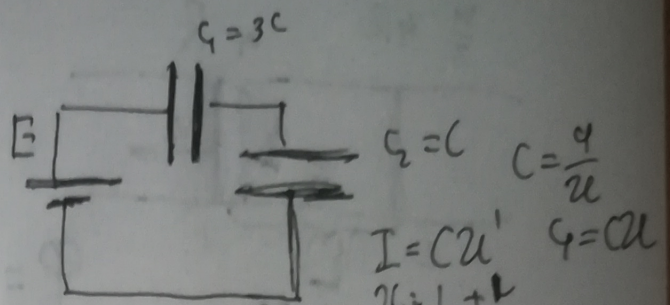
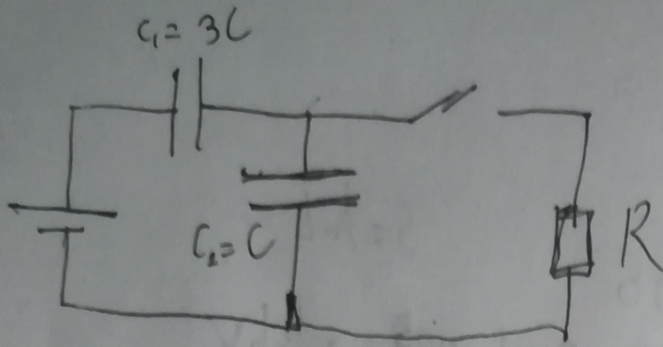
$$V' = -\frac{3B^2 L^2}{5mR} V \Rightarrow V = e^{-\frac{3B^2 L^2}{5mR} t} = v_1 - v_2$$

$$V(0) = v_0$$

$$V(t) \rightarrow 0 \text{ при } t \rightarrow \infty$$

$$\text{Ответ: } \frac{2B^2 L^2 v_0}{5mR}; \sqrt{\frac{2}{3}} v_0$$

Черновик



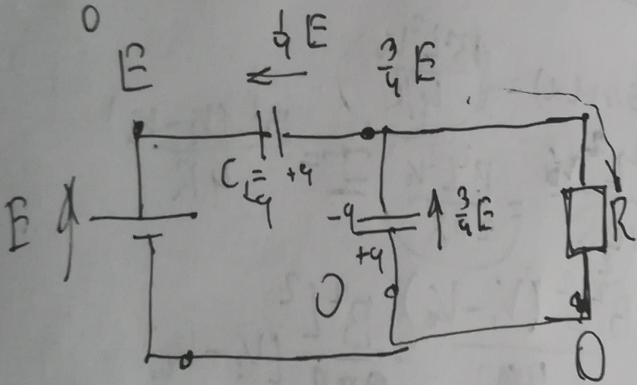
$$C_{\text{общ}} = C + 3C = \frac{3}{4}C$$

$$U = E$$

$$q = \frac{3}{4}CE$$

$$U_1 = \frac{q}{C_1} = \frac{\frac{3}{4}CE}{3C} = \frac{1}{4}E$$

$$U_2 = \frac{q}{C_2} = \frac{3}{4}E$$

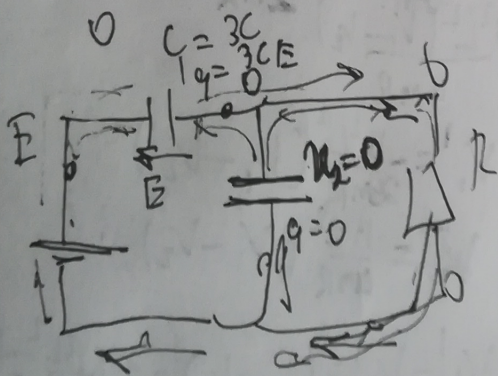


$$U_R = \frac{3}{4}E$$

$$I_R = \frac{U_R}{R} = \frac{3E}{4R}$$

$$A = Eq$$

$$Q = I^2 R t = \frac{q^2}{t} = (q')^2 R t$$



$$E_0 = \frac{3C \left(\frac{1}{4}E\right)^2}{2} + \frac{C \left(\frac{3}{4}E\right)^2}{2}$$

$$E_k = Q + \frac{3CE^2}{2} +$$

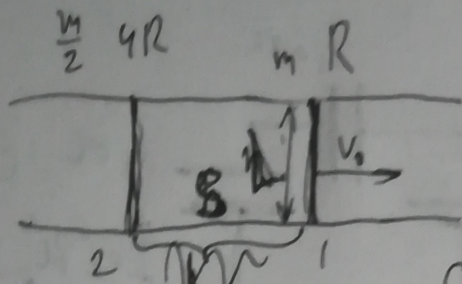
$$E_k - E_0 = A = (3CE - \frac{3}{2}CE)E$$

$$Q + \frac{3CB^2}{2} - \frac{3C\left(\frac{1}{4}E\right)^2}{2} + \frac{C\left(\frac{3}{4}E\right)^2}{2} = 3E^2 \frac{3}{4}E$$

$$\frac{3CB^2}{3L} + \frac{5CE^2}{32}$$



Упробун



$$S = hL$$

$$\Phi = BS$$

$$S = hL$$

$$\Phi' = \mathcal{U} = BS' = B \frac{\Delta S}{\Delta t} = 2 Bhv$$

$$\mathcal{U} = Bhv$$

$$\Phi = BS \cos(\alpha)$$

$$\Phi' = -\mathcal{U}$$

$$h \frac{\Delta L}{\Delta t} = hv$$

$$I = \frac{\mathcal{U}}{R} = \frac{Bhv}{5R}$$

$$\mathcal{E} = 4BS' = Bhv_0$$

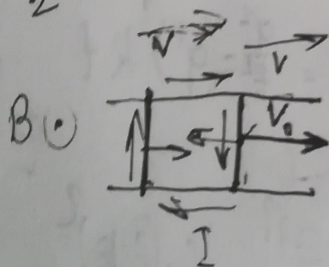
$$I = \frac{Bhv_0}{4R}$$

$$F = BIL = B \cdot \frac{Bhv}{5R} \cdot h = \frac{B^2 h^2 v}{5R}$$

$$F = BIL \sin(\alpha) = \frac{B^2 L^2 v_0}{4R}$$

$$E_0 = \frac{mv_0^2}{2}$$

$$a = \frac{F}{m} = \frac{B^2 L^2 v_0}{4mR} = \frac{B^2 L^2 v_0}{2mR} \quad I = \frac{BL(v_1 - v_2)}{4R}$$



$$a_2 = \frac{B^2 L^2 (v_1 - v_2)}{2mR} = \frac{B^2 L^2}{2mR} (v_1 - v_2)$$

$$a_1 = \frac{B^2 L^2 (v_1 - v_2)}{4mR}$$

$$v_1' = -\frac{B^2 L^2}{2mR} (v_1 - v_2)$$

$$v_2' = \frac{B^2 L^2}{4mR} (v_1 - v_2)$$

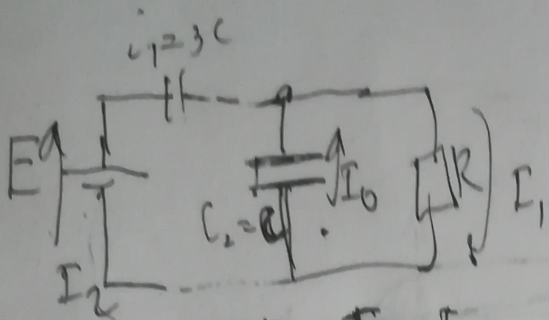
$$v_1' - v_2' = (v_1 - v_2)' = -\left(\frac{B^2 L^2}{2mR} - \frac{B^2 L^2}{4mR}\right) (v_1 - v_2)$$

$$= -\left(\frac{B^2 L^2}{2mR} (v_1 - v_2) + \frac{B^2 L^2}{4mR} (v_1 - v_2)\right) =$$

=

$$S' = V = v_1 + v_2$$

Черновик



$$I = C U'$$

$$U_2' = \frac{I_0}{C} = U_1' = \frac{I}{3C}$$

$$I = 3I_0$$

$$I_2 = 3I_0$$

$$3I_0 + I_0 = 4I_0$$

$$I_2 + I_0 = I_1$$

$$I_1 = I_0 + I_2$$

$$I_2 + I_0 = I_1$$

$$I_1 = I_0 + I_2$$

$$I_0 = I_1 - I_2$$

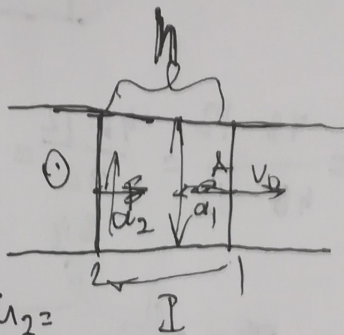
$$I_0 = I_1$$

$$R = 2U$$

$$I = \frac{U}{R}$$

$$I = \frac{U}{R}$$

$$u = IR = 4I_0 R$$



$$(e^{ka})^t = e^{ka} \cdot k$$

$$a_2 = \frac{2B^2 L^2 (V_1 - V_2)}{5mR} = \frac{2B^2 L^2}{5mR} (V_1 - V_2) = V_1'$$

$$-V_2' = \frac{B^2 L^2}{5mR} (V_1 - V_2) \Rightarrow V_2' = -\frac{B^2 L^2}{5mR} (V_1 - V_2)$$

$$a_2 = 2a_1$$

$$V_1' - V_2' = (V_1 - V_2) \left( \frac{2B^2 L^2}{5mR} - \frac{B^2 L^2}{5mR} \right)$$

$$= +\frac{B^2 L^2}{5mR} (V_1 - V_2)$$

$$V_2' = a_2 = \frac{2B^2 L^2 (V_1 - V_2)}{5mR}$$

$$V_1' = -\frac{B^2 L^2 (V_1 - V_2)}{5mR}$$

$$V_1' - V_2' = \frac{3B^2 L^2 (V_1 - V_2)}{5mR} = \frac{3B^2 L^2}{5mR} (V_1 - V_2)$$

$$V_1 - V_2 = e^{-\frac{3B^2 L^2}{5mR} t}$$

$$= -\frac{3B^2 L^2 (V_1 - V_2)}{5mR}$$

$$V_1 - V_2 = V$$

$$V_1 - V_2 = V_0$$

$$V_0' = +V_0 \frac{B^2 L^2}{5mR}$$

$$\frac{3B^2 L^2}{5mR} = \ln(a) \quad a_2 = e$$

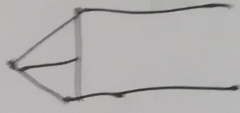
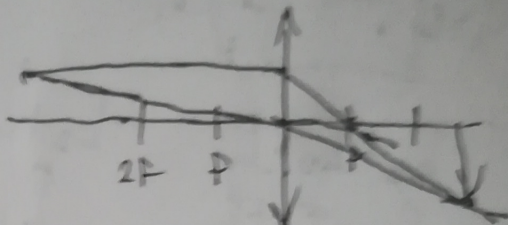
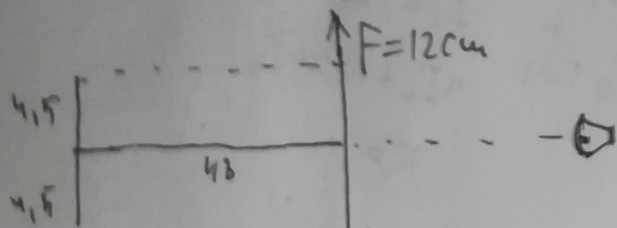
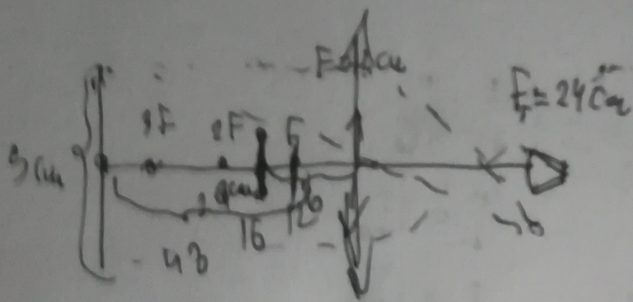
$$(e^x)' = e^x$$

$$(a^x)' = \ln(a) \cdot a^x$$

$$V_1' = -\frac{3B^2 L^2}{5mR} V$$

$$V_2 = e^{-\frac{3B^2 L^2}{5mR} t}$$

кернобус

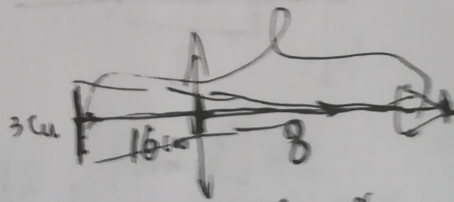


$$\frac{1}{f} + \frac{1}{d} = \frac{1}{F}$$

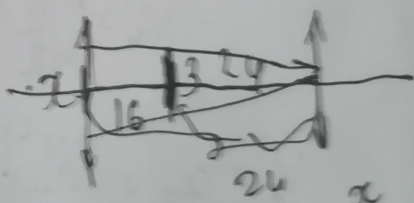
$$\frac{1}{f} = \frac{1}{F} - \frac{1}{d}$$

$$f = \frac{dF}{d-F} = \frac{48 \cdot 12}{48-12} = \frac{48 \cdot 12}{36} = \frac{48}{3} = 16 \text{ cm}$$

$$\Gamma = \frac{f}{d} = \frac{16}{48} = \frac{1}{3}$$



$$\frac{3}{24} = \frac{x}{3} \Rightarrow x = \frac{24}{24} = 1 \text{ cm}$$



1) 40

$$\frac{x}{40} = \frac{3}{24}$$

$$x = \frac{120}{24} = 5 \text{ cm}$$

