

# Часть 1

Олимпиада: **Физика, 11 класс (1 часть)**

Шифр: **21203175**

ID профиля: **357559**

Вариант 2

Угол наклона

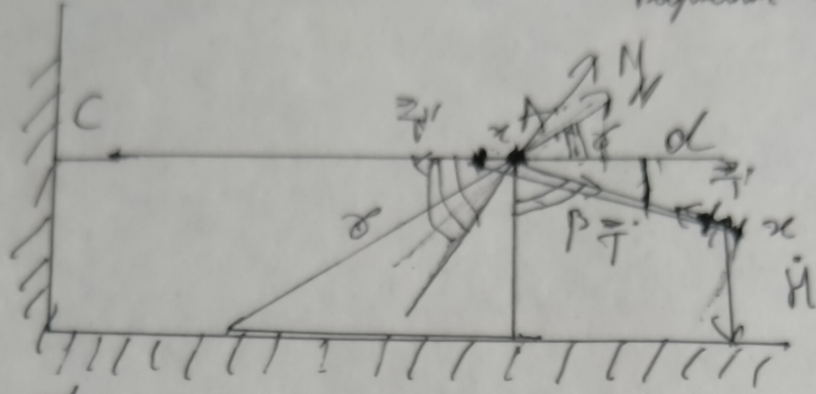
Вопросник 11-02

1)  $\cos \alpha = \frac{4}{5}$   
H

$\beta = ?$   
 $d_{rel} = ?$

$\frac{m}{M} = ?$

$t = ?$



1)  $\alpha = \text{const}$

Если кинка сместится под нагрузкой  $\mu - e \kappa$ , то кинка сместится под нагрузкой  $\mu - e \kappa$ , т.е.  $\alpha = \text{const}$ , но ускорение маятника будет направлено вправо кинка маятника  $\beta = 90^\circ - \alpha$  к вертикали

$\cos \alpha = \sin \beta = \frac{4}{5}$

2)  $x_{нагрузка} = x_{кинка}$

$\downarrow$   
 $d_{rel} = d_m$

~~$\alpha = \frac{180 - \alpha}{2} = 90 - \frac{\alpha}{2}$~~

~~$N = 2T \cos \delta$~~

~~$T \sin \alpha = N \sin \delta$~~

~~$N = \frac{T \sin \alpha}{\sin \delta}$~~

~~$\frac{T \sin \alpha}{\sin \delta} = 2T \cos \delta$~~

~~$\sin \alpha = \sin 2\delta$~~

~~$N \sin \delta = T \sin \alpha$~~

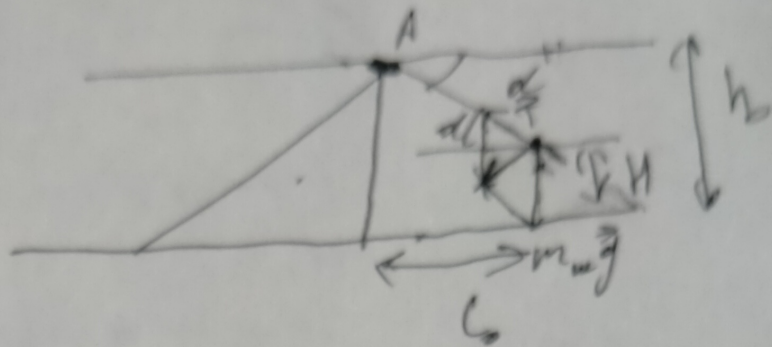
~~$N = \frac{T \sin \alpha}{\sin \delta}$~~

~~$\sin(90 - \frac{\alpha}{2}) = \cos \frac{\alpha}{2}$~~

~~$T - T \cos \alpha - N \cos \delta = m a_m$~~

~~$T - T \cos \alpha - T \sin \alpha \cot \delta = m a_m$~~

~~$T = T(\cos \alpha + \cot \delta \sin \alpha)$~~



$$\tan \alpha = \frac{h_0 - H}{l_0}$$

$$\tan \alpha = \frac{h_0 - H + x_0}{l_0 + x_2}$$

$$\frac{h_0 - H}{l_0} = \frac{h_0 - H + x_0}{l_0 + x_2}$$

$$\frac{l_0}{h_0 - H} = \cot \alpha$$

$$\frac{l_0 + x_2}{l_0} = \frac{h_0 - H + x_0}{h_0 - H}$$

$$x_2 = x_0 \cot \alpha$$

Значит:

$$1 + \frac{x_2}{l_0} = 1 + \frac{x_0}{h_0 - H}$$

$$x_2 = \frac{l_0}{h_0 - H} x_0$$

$$x_2^2 + x_0^2 = x_{\text{min}}^2$$

$$x_0^2 \left( 1 + \left( \frac{l_0}{h_0 - H} \right)^2 \right) = x_{\text{min}}^2$$

$$x_0^2 \left( 1 + \frac{\cos^2 \alpha}{\sin^2 \alpha} \right) = x_{\text{min}}^2$$

$$\frac{x_0}{\sin \alpha} = x_{\text{min}}$$

2) Kacmazlık hesapları

$$C(T) = \frac{5}{2} R \frac{T}{T_0}$$

$v, T_0$

1)  $dQ = -Cv dT$

$$dQ = -\frac{5vR}{2} \frac{T}{T_0} dT$$

$$Q = \int_{T_0}^{T_1} -\frac{5vR}{2} \frac{T}{T_0} dT = -\frac{5}{2} \frac{vR}{T_0} \int_{T_0}^{T_1} T dT = -\frac{5}{4} \frac{vR}{T_0} (T_1^2 - T_0^2)$$

$$= -\frac{5vR}{4} \cdot \left(-\frac{3}{4}\right) T_0^2 = \frac{15}{2} vRT_0$$

$Q_1 - ?$   
 $T_{min} - ?$   
 $A_{min} - ?$

2)  $Q = aK + A$

$$\frac{5vR}{2} \int_{T_0}^{T_{min}} T dT = \frac{3}{2} vR(T_{min} - T_0) + A$$

$$A = -\frac{3}{2} vR(T_{min} - T_0) + \frac{5}{2} \frac{vR}{T_0} \left( \frac{T_{min}^2}{2} - \frac{T_0^2}{2} \right) =$$

$$= \frac{5}{4} \frac{vR}{T_0} (T_{min}^2 - T_0^2) - \frac{3}{2} vR(T_{min} - T_0) = \frac{5}{4} \frac{vR}{T_0} T_{min}^2 - \frac{5}{4} \frac{vR}{T_0} T_0^2 -$$

$$- \frac{3}{2} vR T_{min} + \frac{3}{2} vR T_0 = \frac{5}{4} \frac{vR}{T_0} T_{min}^2 - \frac{3}{2} vR T_{min} + \left( \frac{3}{2} vR T_0 - \frac{5}{4} \frac{vR}{T_0} T_0^2 \right)$$

$$A' = \frac{5}{2} \frac{vR}{T_0} T_{min} - \frac{3}{2} vR = 0$$

$$\frac{5}{2} \frac{T_{min}}{T_0} = \frac{3}{2}$$

$$\frac{T_{min}}{T_0} = \frac{3}{5}$$

$$T_{min} = \frac{3}{5} T_0$$

$$A = -\frac{3}{2} vR \left( \frac{3}{5} - 1 \right) + \frac{5}{4} vR T_0 \left( \left( \frac{3}{5} \right)^2 - 1 \right) =$$

$$= vR T_0 \left( +\frac{3}{8} \cdot \frac{18}{5} \right) + \frac{5}{4} \cdot \left( -\frac{16}{25} \right) = vR T_0 \left( \frac{3}{5} - \frac{4}{5} \right) =$$

$$= -\frac{1}{5} vR T_0$$

2) *режим*

13.11.02

$$\rightarrow dQ = VC(T) dT$$

$$Q_1 = \int_{T_0}^{T_0/2} \frac{5}{2} VR \frac{T}{T_0} dT = \frac{5VR}{2T_0} \int_{T_0}^{T_0/2} T dT = -\frac{5VR}{4T_0} (T_0^2 - T_0^2) = -\frac{5VR}{4T_0} \cdot \left(-\frac{3}{4}T_0^2\right)$$

$$= -\frac{15}{16} VR T_0$$

$$Q = A + \Delta U$$

$$Q = \int_{T_0}^{T_{min}} \frac{5}{2} VR \frac{T}{T_0} dT = \frac{5VR}{2T_0} \int_{T_0}^{T_{min}} T dT = \frac{5VR}{2T_0} \left( \frac{T^2}{2} - \frac{T_0^2}{2} \right) = \frac{5VR}{4T_0} (T^2 - T_0^2)$$

$$\Delta U = \frac{3}{2} VR (T - T_0)$$

$$A = Q - \Delta U = \frac{5}{4} \frac{VR}{T_0} (T^2 - T_0^2) - \frac{3}{2} VR (T - T_0) = \frac{5}{4} VR \frac{T^2}{T_0} - \frac{5}{4} VR T_0 - \frac{3}{2} VR T + \frac{3}{2} VR T_0$$

$$+ \frac{3}{2} VR T_0 = \frac{5}{4} VR \frac{T^2}{T_0} - \frac{3}{2} VR T + \frac{1}{4} VR T_0$$

$$\frac{5}{4} VR T_0 \left( \left(\frac{3}{5}\right)^2 - 1 \right) - \frac{3}{2} VR \left( \frac{3}{5} - 1 \right)$$

$$= \frac{5}{4} VR T_0 \left( -\frac{16}{25} \right) + \frac{3}{2} \cdot \frac{2}{5} VR T_0$$

$$= -\frac{4}{5} VR T_0 + \frac{3}{5} VR T_0 = -\frac{1}{5} VR T_0$$

$$A' = \frac{5}{2} VR \frac{T_{min}}{T_0} - \frac{3}{2} VR = 0$$

$$\frac{5}{2} \frac{T_{min}}{T_0} = \frac{3}{2}$$

$$T_{min} = \frac{3}{5} T_0$$

$$A = \frac{5}{4} VR \frac{T_0}{T_0} \cdot \left(\frac{3}{5}\right)^2 - \frac{3}{2} VR \cdot \frac{3}{5} T_0 + \frac{1}{4} VR T_0 = VR T_0 \left( \frac{5}{4} \cdot \frac{9}{25} - \frac{9}{10} + \frac{1}{4} \right)$$

$$= VR T_0 \left( \frac{9}{20} - \frac{18}{20} + \frac{5}{20} \right) = VR T_0 \cdot \frac{4}{20} = -\frac{1}{5} VR T_0$$

2) Turbinotuk

13.11.02

$C(T) = \frac{5}{2} R \frac{T}{T_0}$   
 $T_0, v$   
 $Q_1 - ?$   
 $T_{min} - ?$   
 $A_{min} - ?$

$$1) \Delta Q = -v C(T) \Delta T = -\frac{5}{2} \frac{vR}{T_0} T \Delta T$$

$$Q_1 = -\frac{5}{2} \frac{vR}{T_0} \int_{T_0}^T T dT = -\frac{5}{2} \frac{vR}{T_0} \left( \frac{T^2}{2} - \frac{T_0^2}{2} \right) =$$

$$= -\frac{5}{4} vRT_0 \left( \frac{T^2}{T_0^2} - 1 \right) = \boxed{-\frac{15}{16} vRT_0}$$

2) turbinada m-kun:

$$Q = A + \Delta U$$

$$Q = \frac{5}{2} \frac{vR}{T_0} \int_{T_0}^T T dT = \frac{5}{4} \frac{vR}{T_0} (T^2 - T_0^2)$$

$$\Delta U = \frac{3}{2} vR (T - T_0)$$

$$A = Q - \Delta U$$

$$A = \frac{5}{4} vR \left( \frac{T^2}{T_0} - T_0 \right) - \frac{3}{2} vR (T - T_0) = \frac{5}{4} vR \frac{T^2}{T_0} - \frac{5}{4} vRT_0 -$$

$$- \frac{3}{2} vRT + \frac{3}{2} vRT_0 = \frac{5}{4} \frac{vR}{T_0} T^2 - \frac{3}{2} vRT + \frac{1}{4} vRT_0$$

$$A' = \frac{5}{2} vR \frac{T}{T_0} - \frac{3}{2} vR$$

$A_{min}$  nuqa  $A' = 0$   $T$  nuqa  $A' = 0 = T_{min}$

$$\frac{5}{2} vR \frac{T_{min}}{T_0} - \frac{3}{2} vR = 0$$

$$\frac{5}{2} \frac{T_{min}}{T_0} = \frac{3}{2}$$

$$\boxed{T_{min} = \frac{3}{5} T_0}$$

$$3) A = \frac{5}{4} \frac{vR}{T_0} \left( \left( \frac{3}{5} T_0 \right)^2 - T_0^2 \right) - \frac{3}{2} vR \left( \frac{3}{5} T_0 - T_0 \right) =$$

$$= \frac{5}{4} \frac{vR}{T_0} \left( \frac{9}{25} T_0^2 - T_0^2 \right) + \frac{3}{2} vRT_0 \cdot \frac{2}{5} = -\frac{5}{4} \frac{vR}{T_0} \cdot \frac{16}{25} T_0^2 + \frac{3}{5} vRT_0 =$$

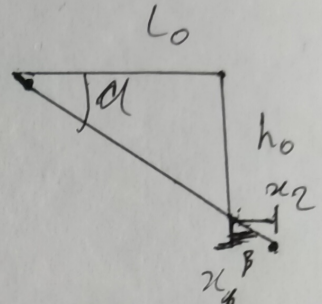
$$= vRT_0 \left( \frac{3}{5} - \frac{4}{5} \right) = \boxed{-\frac{1}{5} vRT_0}$$

① Javab:  $Q_1 = \frac{15}{16} vRT_0$ ;  $T_{min} = \frac{3}{5} T_0$ ;  $A_{min} = -\frac{1}{5} vRT_0$

1) "участок"

1)  $\cos \alpha = \frac{4}{5}$   $\sin \alpha = \frac{3}{5}$   $\operatorname{tg} \alpha = \frac{3}{4}$

- $\beta$  - ?
- $d_{kl}$  - ?
- $m_{kl}$  - ?
- $m_{kl}$  - ?
- $t$  - ?



мыслим мысленно соединим  $x_2$  и  $x_0$

$x_{kl}^2 = x_0^2 + x_2^2$

$d_{kl} \parallel x_{kl}$

1)  $d = \text{const}$

$\operatorname{tg} \alpha = \frac{h_0}{l_0}$

$\operatorname{tg} \alpha = \frac{h_0 + x_0}{x_2 + l_0}$

$\frac{h_0 + x_0}{x_2 + l_0} = \frac{h_0}{l_0}$

$\frac{x_2 + l_0}{l_0} = \frac{h_0 + x_0}{h_0}$

$\frac{x_2}{l_0} + 1 = 1 + \frac{x_0}{h_0}$

$x_2 = \frac{l_0}{h_0} x_0$   $x_0 = \frac{x_2 h_0}{l_0}$

$\operatorname{tg} \beta = \frac{x_0}{x_2} = \frac{x_0}{\frac{l_0}{h_0} x_0} = \frac{h_0}{l_0}$

$\operatorname{ctg} \alpha = \frac{4}{3} \Rightarrow \beta + \alpha = 90^\circ$

Ответ:  $\operatorname{tg} \beta = \frac{4}{3}$ ;  $\frac{m_{kl}}{m_{kl}} = \frac{4}{5}$

2) Пусть соединим  $x_0$  и  $x_2$   $x_{kl} = x_{kl}$

$x_{kl}^2 = x_0^2 + x_2^2 = x_0^2 \left( 1 + \frac{1}{\sin^2 \alpha} \right) = x_0^2 \cdot \frac{1}{\sin^2 \alpha}$

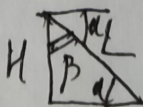
$x_{kl} = \frac{x_0}{\sin \alpha} = \frac{5}{3} x_0$

$d_{kl} = \frac{5}{3} d_0 = \frac{3}{4} \cdot \frac{5}{3} d_2 = \frac{5}{4} d_2 = d_{kl}$

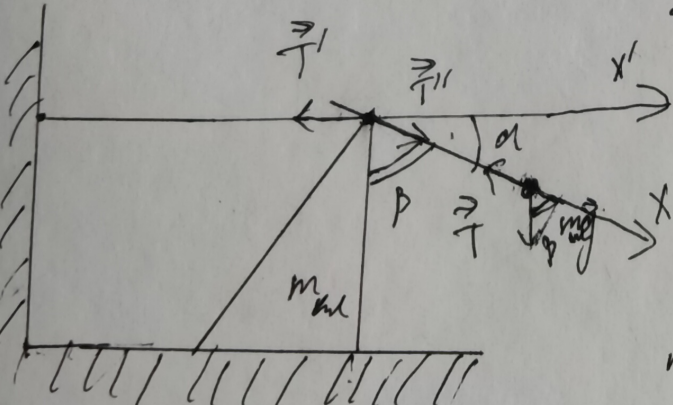
2)  $H$  на ось  $x$ :  $m_{kl} d_{kl} = m_{kl} d_2 = T$

3)  $t^2 = \frac{2L}{d_{kl}}$

$t = \sqrt{\frac{2L}{d_{kl}}} = \sqrt{\frac{10}{3}} \frac{H}{d_{kl}}$



$L = \frac{H}{\sin \alpha} = \frac{5}{3} H$



3) на ось  $x'$  нет проекций сил, следовательно ускорения равно нулю

$\frac{m_{kl} d_{kl}}{m_{kl}} = \frac{d_2}{d_{kl}} = \frac{4}{5}$

2

# Часть 2

Олимпиада: **Физика, 11 класс (2 часть)**

Шифр: **21203175**

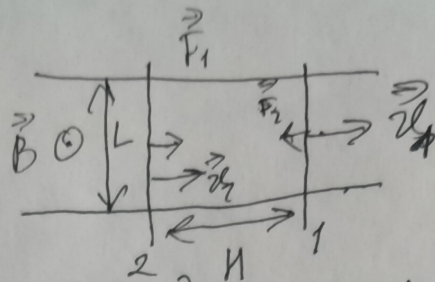
ID профиля: **357559**

Вариант 2



variabel  
1)  $B, L, m, R, \frac{m}{2}, 4R, 2l$

$a_{\text{ao}} - ?$   
 $v_1, v_2 - ?$   
 $\Delta H$



$$1) \mathcal{E} = \frac{d\Phi}{dt} = \frac{d}{dt}(BLH) = \frac{d}{dt}H \cdot BL = BL \cdot (v_1 - v_2)$$

$$I = \frac{\mathcal{E}}{4R + R} = \frac{\mathcal{E}}{5R} = \frac{BL}{5R} (v_1 - v_2)$$

$$F_1 = IBL = \frac{B^2 L^2}{5R} (v_1 - v_2)$$

$$F_2 = F_1 - \frac{B^2 L^2}{5R} (v_1 - v_2)$$

$$a_2 = \frac{F_1}{\frac{m}{2}} = \frac{2}{5} \frac{B^2 L^2}{R} (v_1 - v_2)$$

$$a_1 = \frac{F_2}{m} = \frac{1}{5} \frac{B^2 L^2}{R} (v_1 - v_2)$$

$$v_2(0) = 0 \quad v_1(0) = v_0$$

$$a_{20} = \frac{2}{5} \frac{B^2 L^2}{R} v_0$$

$$2) a_1 = a_2 = 0 \quad a_2 = 2a_1$$

$$v_1 - v_2 = 0$$

$$dv_2 = 2dv_1$$

$$v_1 = v_2$$

$$v_2 = 2(v_1 - v_1)$$

$$\Rightarrow v_1 = v_2 = \frac{2}{3} v_0$$

$$3) \frac{dv_2}{dt} = \frac{2}{5} \frac{B^2 L^2}{R} (v_1 - v_2)$$

$$\frac{dv_1}{dt} = \frac{1}{5} \frac{B^2 L^2}{R} (v_1 - v_2)$$

$$dv_2 = \frac{2}{5} \frac{B^2 L^2}{R} (v_1 dt - v_2 dt)$$

$$v_2 = \frac{2}{5} \frac{B^2 L^2}{R} (x_1 - x_2) = \frac{2}{5} \frac{B^2 L^2}{R} \Delta H$$

$$\Delta H = \frac{5}{2} \frac{R}{B^2 L^2} \cdot \frac{2}{3} v_0 = \frac{5}{3} \frac{R}{B^2 L^2} v_0$$

Jawab:  $a_{20} = \frac{2}{5} \frac{B^2 L^2}{R} v_0$ ;  $v_1 = v_2 = \frac{2}{3} v_0$ ;  $\Delta H = \frac{5}{3} \frac{R}{B^2 L^2} v_0$

(5)

4) Керновок

B 11-02

$L, m, R, \frac{m}{2}, v_0, \mathcal{L}_0$

$a_0 - ?$   
 $v_1, v_2 - ?$   
 $\mathcal{L} - ?$

$$\mathcal{E}_0 = \frac{d\Phi}{dt} = \frac{d}{dt}(BL \cdot v) = BL \frac{dv}{dt} = BL v_0$$

$$I = \frac{\mathcal{E}_0}{R+R} = \frac{\mathcal{E}_0}{5R} = \frac{BLv_0}{5R}$$

$$F_A = IBL = \frac{v_0}{5R} B^2 L^2$$

$$F_{ac} = \frac{m}{2} a_0$$

$$a_0 = \frac{2}{m} F_{ac} = \frac{2}{5} \frac{v_0}{mR} B^2 L^2$$

$$F_{ac} = m a_0'$$

$$a_0' = \frac{F_{ac}}{m} = \frac{1}{5} \frac{v_0}{mR} B^2 L^2$$

$$a(v) = \frac{2}{5} \frac{B^2 L^2}{mR} v \quad a'(v) = \frac{1}{5} \frac{B^2 L^2}{mR} v$$

$$\frac{dv}{dt} = \frac{2}{5} \frac{B^2 L^2}{mR} v$$

$$dv = \frac{2}{5} \frac{B^2 L^2}{mR} dx$$

$$v_2 = \frac{2}{5} \frac{B^2 L^2}{mR} x_2$$

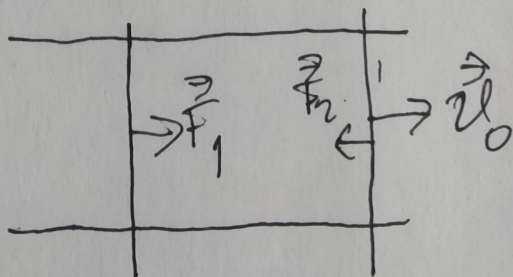
$$v_2 = \frac{2}{5} \frac{B^2 L^2}{mR} x_2$$

$$dv' = \frac{1}{5} \frac{B^2 L^2}{mR} dx'$$

$$v_1 - v_0 = \frac{1}{5} \frac{B^2 L^2}{mR} x_1$$

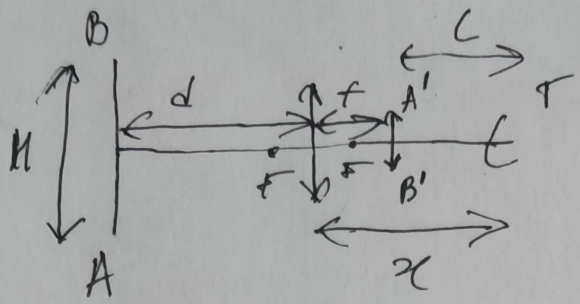
$$v_1 = 0$$

$$v_0 = \frac{1}{5} \frac{B^2 L^2}{mR} x_1$$



5) Числовые

- $H = 2 \text{ см}$
- $d = 48 \text{ см}$
- $L = 24 \text{ см}$
- $F = 12 \text{ см}$



- $x = ?$
- $D_m = ?$
- $L_{\text{г}} = ?$

1)  $\frac{1}{F} = \frac{1}{f} + \frac{1}{d}$  - формула тонкой линзы

$f = \left(\frac{1}{F} - \frac{1}{d}\right)^{-1} = 16 \text{ см}$      $T = \frac{f}{d} = \frac{1}{3}$      $x = f + L = 40 \text{ см}$

2)  $D > h_{\text{об}} = T H = 3 \text{ см}$

$D_{\text{min}} = T H = 3 \text{ см}$

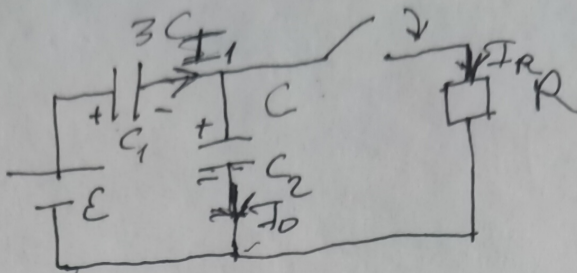
3)  $L_{\text{г}} = F = 12 \text{ см}$  нужно расположить экран в фокусе линзы

Ответ:  $x = 40 \text{ см}$ ;  
 $D_m = 3 \text{ см}$ ,  $L_{\text{г}} = 12 \text{ см}$

3) Memotok

$C, 3C, I_0, R, \mathcal{E}$

$I_1 - ?$   
 $Q - ?$   
 $U_0 - ?$



$$U_{3C} + U_C = \mathcal{E}$$

$$\frac{q_{3C}}{3C} + \frac{q_C}{C} = \mathcal{E}$$

$$q_{3C} = q_C$$

$$\frac{q_C}{C} \left(1 + \frac{1}{3}\right) = \mathcal{E}$$

$$q_C = \frac{3}{4} \frac{\mathcal{E}}{C} = \frac{3}{4} C \mathcal{E}$$

$$U_C = \frac{3}{4} \mathcal{E}$$

$$U_{3C} = \frac{1}{4} \mathcal{E}$$

$$1) I_1 R = \mathcal{E} - U_{3C} = \frac{3}{4} \mathcal{E}$$

$$I_1 = \frac{3\mathcal{E}}{4R}$$

$$2) A_u = \Delta W_C + \Delta W_{3C} + Q - 3C \mathcal{E} \quad U_{3C} = \mathcal{E} \quad U_{3C} = 0$$

$$\Delta W_C = 0 - \frac{C \mathcal{E}^2}{4^2} = -\frac{9}{16} C \mathcal{E}^2 \text{ - work done by } C$$

$$\Delta W_{3C} = \left( \frac{C \mathcal{E}^2}{2} - \frac{1}{16} C \mathcal{E}^2 \right) = 3C \mathcal{E}^2 \frac{8-1}{16} = \frac{21}{16} C \mathcal{E}^2 \text{ - work done by } 3C$$

$$A_u = \mathcal{E} (3C \mathcal{E} - \frac{3}{4} C \mathcal{E} \cdot 2) = \frac{3}{2} C \mathcal{E}^2 \text{ - work done by } \mathcal{E}$$

$$\frac{3}{2} C \mathcal{E}^2 + \frac{9}{16} C \mathcal{E}^2 - \frac{21}{16} C \mathcal{E}^2 = Q$$

$$C \mathcal{E}^2 \frac{24 - 21 + 9}{16} = Q$$

$$Q = \frac{3}{4} C \mathcal{E}^2$$

$$3) \mathcal{E} = U_1 + U_2 = \frac{q_1}{3C} + \frac{q_2}{C}$$

$$\mathcal{E} = \left( \frac{q_1}{3C} + \frac{q_2}{C} \right)$$

$$0 = \frac{I_1}{3C} - \frac{I_2}{C}$$

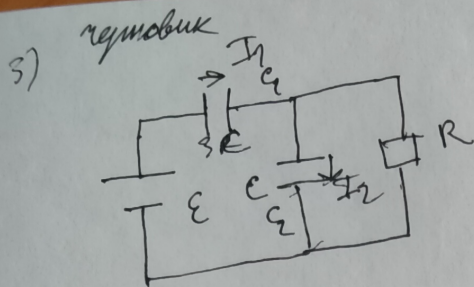
$$I_1 = 3I_2 \quad I_2 = I_0$$

$$3I_0 = I_0 \mathcal{E} I_2 R \quad I_2 R = 2I_0 R \quad U_0 = I_2 R = 2I_0 R$$

$I_1$  - max rezeg  
 $I_2$  - max rezeg  
 $I_R$  - max rezeg

Answer:  $I_1 = \frac{3\mathcal{E}}{4R}$ ,  $Q = \frac{3}{4} C \mathcal{E}^2$ ,  $U_0 = 2I_0 R$

(1)



$$\varepsilon = U_1 + U_2 = \frac{q_1}{3C} + \frac{q_2}{C}$$

$$U_1 = \frac{q_1}{3C}$$

$$\varepsilon = \frac{q_1}{3C} + \frac{q_2}{C}$$

$$\varepsilon' = 0$$

$$\left(\frac{q_1}{3C} + \frac{q_2}{C}\right)' = \frac{I_1}{3C} + \frac{I_2}{C}$$

$$I_2 = I_0$$

$$\frac{I_0}{C} = \frac{I_1}{3C}$$

$$I_1 = 3I_0$$

$$I_R = I_0 + I_1$$

$$I_R = I_1 - I_0 = 2I_0$$

$$U_0 = I_R R = 2I_0 R$$

