

Часть 1

Олимпиада: **Физика, 11 класс (1 часть)**

Шифр: **21200897**

ID профиля: **368957**

Вариант 3

(502)

Условие

ν, T_0

$$c(T) = 3R \frac{T}{T_0}$$

1) Q_1 ($Q_1 > 0$) - ?
 T_0 до $\frac{3}{5}T_0$

2) $T(A_{\min})$ - ?

3) A_{\min} - ?

1) $\delta Q(T) = c \nu \Delta T$

$$\delta Q(T) = 3R \frac{\nu}{T_0} \nu \Delta T \quad (*)$$

Прогрессивным соот. (*) от $T = T_0$ до $T = \frac{3}{5}T_0$

$$\sum \delta Q = \sum 3R \nu \frac{T \Delta T}{T_0}$$

$$Q = \frac{3R\nu}{T_0} \sum T \Delta T = \frac{3R\nu}{T_0} \cdot \left(\frac{(\frac{3}{5}T_0)^2}{2} - \frac{T_0^2}{2} \right)$$

$$Q = \frac{3R\nu}{T_0} \left(\frac{9T_0^2}{50} - \frac{25T_0^2}{50} \right) = \frac{-48\nu R T_0}{50} = \frac{-24\nu R T_0}{25}$$

$$Q_1 = -Q$$

$$Q_1 = \frac{24\nu R T_0}{25}$$

2) $Q = A(T) + \Delta U$

$$A(T) = Q - \Delta U$$

$$Q = \sum 3R\nu \frac{T \Delta T}{T_0} = \frac{3R\nu}{T_0} \left(\frac{T^2}{2} - \frac{T_0^2}{2} \right)$$

$$\Delta U = \frac{3}{2}\nu R (T - T_0)$$

$$A(T) = \frac{3R\nu}{T_0} \left(\frac{T^2 - T_0^2}{2} \right) - \frac{3}{2}\nu R (T - T_0)$$

$$A(T) = 3\nu R \left(\frac{T^2 - T_0^2}{2T_0} - \frac{T - T_0}{2} \right) = 3\nu R \left(\frac{T^2 - T_0^2 - TT_0 + T_0^2}{2T_0} \right)$$

$$A(T) = \frac{3\nu R}{2T_0} (T^2 - TT_0)$$

$$A = A_{\min} \text{ при } T = \frac{T_0}{2} \quad (y = -\frac{b}{2a})$$

$$T(A_{\min}) = \frac{T_0}{2}$$

$$3) A_{\min} = \frac{3\nu R}{2T_0} \cdot \left(\left(\frac{T_0}{2} \right)^2 - \frac{T_0 \cdot T_0}{2} \right) = \frac{3\nu R}{2T_0} \cdot \left(-\frac{T_0^2}{4} \right) = \frac{-3\nu R T_0}{8}$$

ОТВЕТ: 1) $Q_1 = \frac{24\nu R T_0}{25}$

2) $T = \frac{T_0}{2}$

3) $A_{\min} = \frac{-3\nu R T_0}{8}$

(1)

Nº1 Mecânica

$$\cos \alpha = \frac{5}{13}$$

H.

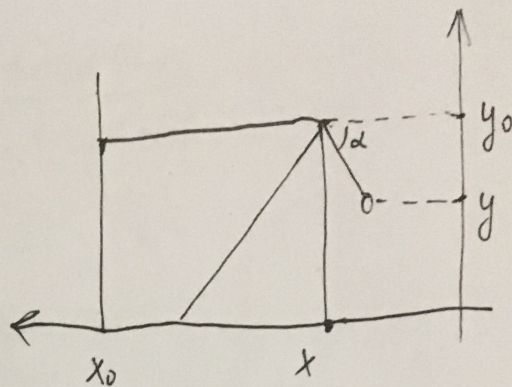
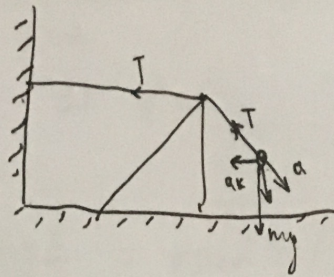
1) β - ?

2) a_k - ?

3) $\frac{m m}{m k}$ - ?

4) r - ?

1)



$$L'' = x_0'' - x'' + \frac{y_0'' - y''}{\sin \alpha}$$

$$0 = -a_k x + \frac{1}{\sin \alpha} \cdot (-a m x)$$

$$a_k = \frac{a m}{\sin \alpha} \quad (1)$$

23H: $mg \sin \alpha - T = m a$

$$T \cos \alpha = m a_k \Rightarrow T = \frac{m a_k}{\cos \alpha}$$

$$g \sin \alpha - \frac{a_k}{\cos \alpha} = a$$

$$a = g \sin \alpha \cos \alpha - a_k \quad (3)$$

$$a \sin \alpha = a_m \sin \beta \quad (4)$$

$$a \cos \alpha = a_k + a_m \cos \beta \quad (2) \quad \Leftarrow$$

$$(1) \Rightarrow (2) \quad a \cos \alpha = \frac{a_m}{\sin \alpha} + a_m \cos \beta$$

$$\frac{a}{a_m} = \frac{1 + \sin \alpha \cos \beta}{\sin \alpha \cos \alpha}$$

$$\frac{a}{a_m} = \frac{\sin \beta}{\sin \alpha}$$

$$\frac{\sin \beta}{\sin \alpha} = \frac{1 + \sin \alpha \cos \beta}{\sin \alpha \cos \alpha}$$

$$\sin \beta \cos \alpha = 1 + \sin \alpha \cos \beta$$

$$\sin(\beta - \alpha) = 1 \Rightarrow \beta - \alpha = \frac{\pi}{2} \Rightarrow \beta = \frac{\pi}{2} + \alpha \Rightarrow \text{incógnita } \gamma = 180^\circ - \alpha = \frac{\pi}{2} - \alpha$$

2) $a_m \rightarrow$ (3) $\Rightarrow a = g \sin \alpha \cos \alpha - a_k$

$$a_k = \frac{a m}{\sin \alpha}$$

$$a \cos \alpha = \frac{a m}{\sin \alpha} + a_m \cos \beta \quad \Rightarrow$$

2

Умова

$$a = g \sin \alpha \cos \alpha - \frac{a_m}{\sin \alpha} \quad (5)$$

$$a \cos \alpha = a_m \left(\frac{1 + \sin \alpha \cos \alpha}{\sin \alpha} \right) \Rightarrow a_m = \frac{a \cos \alpha \sin \alpha}{1 + \sin \alpha \cos \alpha}$$

$$(4) \Rightarrow \frac{a}{a_m} = \frac{\sin \beta}{\sin \alpha} \Rightarrow a = a_m \frac{\sin \beta}{\sin \alpha} \quad (6)$$

$$a_k = \frac{a_m}{\sin \alpha}$$

$$(6) \Rightarrow (5) : a_m \frac{\sin \beta}{\sin \alpha} = g \sin \alpha \cos \alpha - \frac{a_m}{\sin \alpha}$$

$$\sin \beta = \sin \left(\frac{\pi}{2} + \alpha \right) = \cos \alpha$$

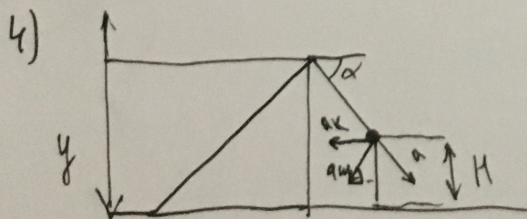
$$a_m \left(\frac{\cos \alpha}{\sin \alpha} + \frac{1}{\sin \alpha} \right) = g \sin \alpha \cos \alpha$$

$$a_m = \frac{g \sin^2 \alpha \cos \alpha}{\cos \alpha + 1}$$

$$a_k = \frac{g \sin \alpha \cos \alpha}{\cos \alpha + 1}$$

$$3) \quad 23H: \begin{cases} T = m_k \cdot a_k \\ T \cos \alpha = m \cdot a_k \end{cases}, \text{ где } m = m_m$$

$$\frac{m_k}{m_m} = \frac{1}{\cos \alpha} \Rightarrow \frac{m_m}{m_k} = \cos \alpha$$



$$H = \frac{(a_m) \cdot t^2}{2}$$

$$2H = a_{my} \cdot t^2 \Rightarrow t^2 = \frac{2H}{a_{my}}$$

$$a_{my} = a_m \cdot \sin \left(\frac{\pi}{2} - \alpha \right) = a_m \cdot \cos \alpha = \frac{g \sin^2 \alpha \cos^2 \alpha}{\cos \alpha + 1}$$

$$t = \sqrt{\frac{2H \cdot (\cos \alpha + 1)}{g \sin^2 \alpha \cos^2 \alpha}} = \sqrt{\frac{2H (\cos \alpha + 1)}{g \sin^2 \alpha \cos^2 \alpha}}$$

ОТВЕТ: 1) $\beta = \frac{\pi}{2} - \alpha$; 2) $a_k = \frac{g \sin \alpha \cos \alpha}{\cos \alpha + 1}$; 3) $\frac{m_m}{m_k} = \cos \alpha$; 4) $t = \sqrt{\frac{2H (\cos \alpha + 1)}{g \sin^2 \alpha \cos^2 \alpha}}$ (3)

① $\sqrt{3}$

$\cos \alpha = \frac{5}{13}$

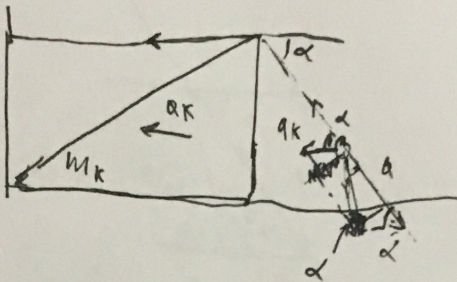
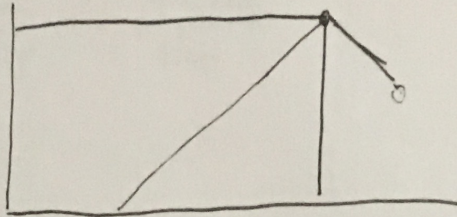
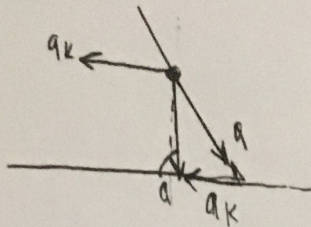
H.

1) β (am)

2) a_k - ?

3) $\frac{m_m}{m_k}$

4) τ



$\sin \beta =$

mg

$mg \sin \alpha - T = m a_k$

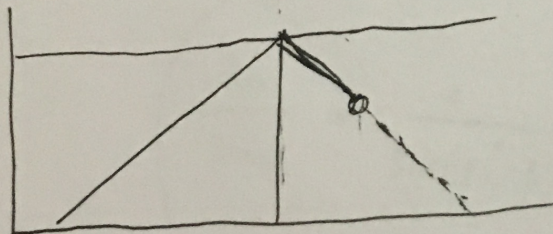
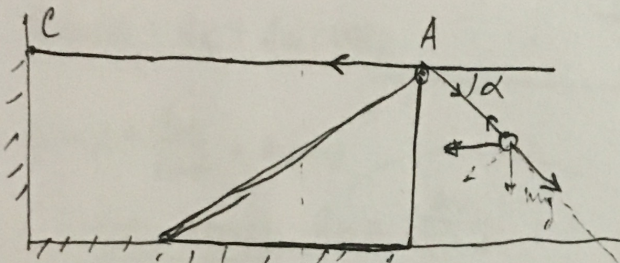
$T \cos \alpha = m a_k$

$T = \frac{m a_k}{\cos \alpha}$

$g \sin \alpha - \frac{a_k}{\cos \alpha} = a$

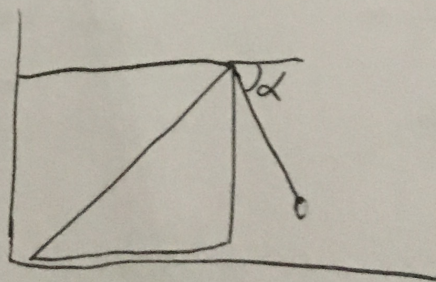
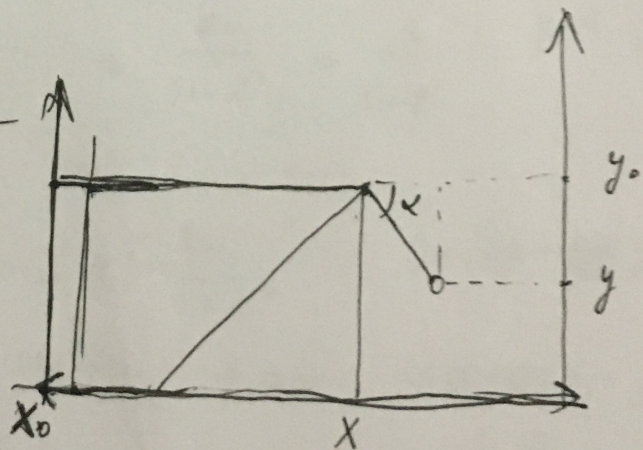
$g \sin \alpha \cos \alpha - a_k = a \cos \alpha$

$g \sin \alpha \cos \alpha = a \cos \alpha + a_k$



$\sin \alpha =$

$(y_0'' - y'') \frac{1}{\sin \alpha}$



$\frac{1}{4} - \frac{1}{2} = -\frac{1}{4}$

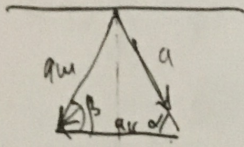
$L'' = x_0'' - x'' + \frac{y_0'' - y''}{\sin \alpha}$

$0 = -a_k + \frac{1}{\sin \alpha} (-g a_m)$

$|a_k| = \frac{g a_m}{\sin \alpha}$

~~q_K = a sin δ~~

$$\frac{1}{\sin \alpha} + \frac{\sin \delta \cos \alpha}{\sin \delta}$$



$$\frac{\sin \beta}{\sin \delta} = \frac{a}{a_m}$$

$$q_K = a \cos \alpha + a_m \cos \beta$$

$$a \sin \delta = a_m \cdot \sin \beta$$

$$a_m \cos \alpha = q_K$$

$$q \cos \alpha = q_K + a_m \cdot \cos \beta$$

$$q \cos \alpha = \frac{a_m}{\sin \delta} + a_m \cos \beta$$

$$\frac{a}{a_m} = \frac{(\frac{1}{\sin \delta} + \cos \beta)}{\cos \alpha} \quad q_K = \frac{a_m}{\sin \delta}$$

$$q \sin \delta \cos \alpha = a \cos \alpha + q_K$$

$$\frac{a_m}{\sin \delta} = \frac{a}{\sin(180^\circ - \beta)} = \frac{a_m}{\sin \delta} = \frac{a}{\sin \beta} \quad \beta = \frac{\pi}{2} + \alpha$$

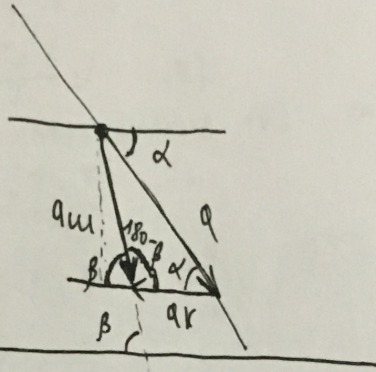
$$q \sin \delta \cos \alpha = a \cos \alpha + \frac{a_m}{\sin \delta}$$

$$q \sin^2 \delta \cos \alpha = a \cos \alpha \cdot \sin \delta + a_m$$

$$a_m = q \sin \delta \cos \alpha (\sin \delta - 1)$$

$$a_m = \sin \delta \cos \alpha (q \sin \delta - a)$$

$$a \cos \alpha = \frac{a_m}{\sin \delta} + a_m \cos \beta$$



$$\frac{\sin \beta}{\sin \delta} = \frac{\cos \beta + \sin \delta \cos \alpha}{\sin \delta \cos \alpha}$$

$$\frac{\sin \beta}{\sin \delta} = \frac{1 + \sin \delta \cos \alpha}{\sin \delta \cos \alpha}$$

$$\sin \beta \cos \alpha = 1 + \sin \delta \cos \alpha$$

$$\sin \beta \cos \alpha - \sin \delta \cos \alpha = 1$$

$$\sin(\beta - \alpha) = 1$$

$$\beta - \alpha = \frac{\pi}{2}$$

$$\beta = \frac{\pi}{2} + \alpha$$

$$\sin(60^\circ - 30^\circ)$$

$$\sin 60^\circ \cos 30^\circ - \sin 30^\circ \cos 60^\circ =$$

$$= \frac{\sqrt{3}}{2} \cdot \frac{\sqrt{3}}{2} - \frac{1}{4}$$

$$= \frac{3}{4} - \frac{1}{4} = \frac{1}{2}$$

№ 2

$$V, T_0$$

$$C(T) = 3R \frac{T}{T_0}$$

1) Q_1 ($Q_1 > 0$)
 T_0 до $\frac{3}{5}T_0$

2) T (A_{min})

3) $A_{min} - ?$

$$1) \delta Q = \delta A + \Delta U$$

$$\Delta U = \frac{3}{2} \nu R \Delta T$$

$$\delta A = p \delta V$$

$$pV = \nu RT$$

$$\delta Q(T) = C \nu \Delta T$$

$$\delta Q(T) = 3R \frac{T}{T_0} \nu (T - T_0)$$

$$\delta Q = 3R \frac{T \Delta T}{T_0} \nu \quad (*)$$

Програничим соотношением (*) от $T = T_0$ до $T = \frac{3}{5}T_0$.

$$\sum \delta Q = \sum 3R \nu \frac{T \Delta T}{T_0}$$

$$Q = \frac{3R}{T_0} \sum T \Delta T = \frac{3R}{T_0} \nu \left(\frac{(\frac{3}{5}T_0)^2}{2} - \frac{(T_0)^2}{2} \right)$$

$$Q = \frac{3R}{T_0} \nu \left(\frac{9T_0^2}{50} - \frac{T_0^2}{2} \right)$$

$$Q = \frac{3R}{T_0} \nu \left(\frac{9T_0^2}{50} - \frac{25T_0^2}{50} \right) = -\frac{3R}{T_0} \nu \cdot \frac{16T_0^2}{50} = -\frac{48 \nu R T_0}{50}$$

$$Q_1 = -Q = \frac{24 \nu R T_0}{25} \quad Q = \frac{-24 \nu R T_0}{25}$$

2) $Q = A_{min} + \Delta U$

$$A_{min} = Q - \Delta U = \sum 3R \nu \frac{T \Delta T}{T_0} - \frac{3}{2} \nu R \Delta T$$

$$A_{min} = \frac{3R \nu}{T_0} \cdot \left(\frac{T^2}{2} - \frac{T_0^2}{2} \right) - \frac{3}{2} \nu R (T - T_0)$$

$$A(T) = 3R \nu \left(\frac{T^2 - T_0^2}{2} - \frac{T - T_0}{2} \right) = 3R \nu \left(\frac{(T - T_0)(T + T_0) - (T - T_0)}{2} \right)$$

$$A(T) = \frac{3R \nu}{2} (T - T_0)(T + T_0 - 1)$$

$$\left((T - T_0)(T + T_0 - 1) \right)'_T = 0$$

$$(T - T_0)'(T + T_0 - 1) + (T - T_0)(T + T_0 - 1)' = 0$$

$$(1 - 0)(T + T_0 - 1) + (T - T_0) \cdot 1 = 0$$

$$T + T_0 - 1 + T - T_0 = 0$$

Часть 2

Олимпиада: **Физика, 11 класс (2 часть)**

Шифр: **21200897**

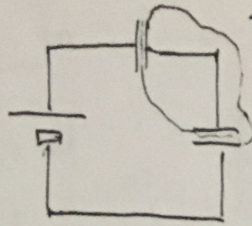
ID профиля: **368957**

Вариант 3

$C_2 = C$
 $C_1 = 4C$

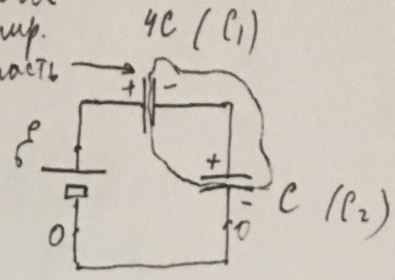
- 1) I_R - ?
- 2) Q - ?
- 3) U - ?
 ($I_0 = I_{C1}$)

1) Расчет цепи до замыкания



нат. момент.

Клота изолир. область



$t = t_{уст}$

$$\begin{cases} 0 = -4\mathcal{E} \cdot U_1 + \mathcal{E} U_2 \\ \mathcal{E} = U_1 + U_2 \end{cases}$$

$$4C_1 = U_2$$

$$\mathcal{E} = 5U_1 \Rightarrow \begin{cases} U_1 = \frac{\mathcal{E}}{5} \\ U_2 = \frac{4\mathcal{E}}{5} \end{cases}$$

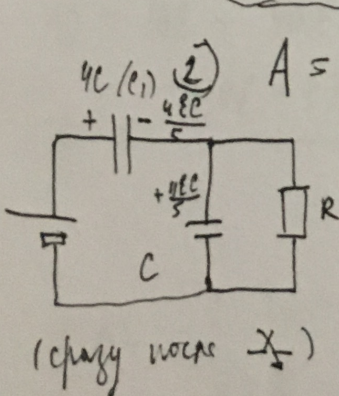
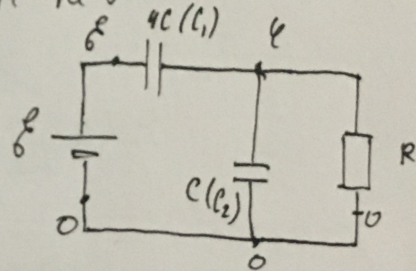
Расчет цепи после замыкания Клота. Напряж. на конд. эквивалент не изменился

$$I_R = \frac{\mathcal{E}}{R}$$

$$\mathcal{E} - \varphi = U_1 = \frac{\mathcal{E}}{5}$$

$$\varphi = \frac{4\mathcal{E}}{5}$$

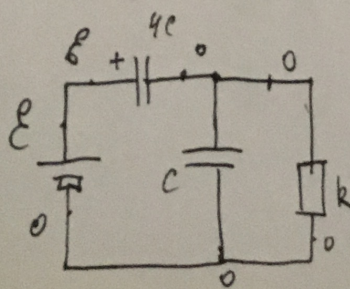
$$I_R = \frac{4\mathcal{E}}{5R}$$



(сразу после x_2)

$A = Q + \Delta W \Rightarrow Q = A - \Delta W$

$$\begin{cases} q_1(0) = (4C \cdot U_1) = \frac{-4\mathcal{E}C}{5} \\ W_{20} = \frac{4C U_1^2}{2} = \frac{4C \cdot \mathcal{E}^2}{50} = \frac{2C\mathcal{E}^2}{25} \\ W_{20} = \frac{C U_2^2}{2} = \frac{10C \cdot 16\mathcal{E}^2}{50} = \frac{8C\mathcal{E}^2}{25} \end{cases}$$



(уст. р.)

$$\begin{cases} W_1 = \frac{4C \cdot \mathcal{E}^2}{2} = 2C\mathcal{E}^2 \\ W_2 = 0 \\ q_1^* = 4C \cdot \mathcal{E} \end{cases}$$

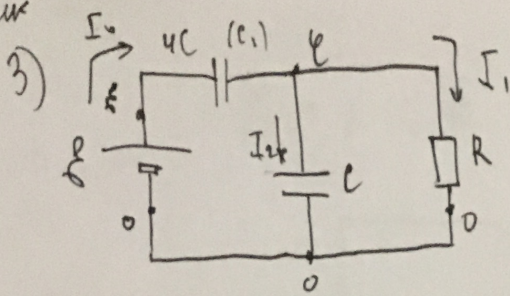
$$Q = \mathcal{E} \cdot q_1^* - (W_1 + W_2 - (W_{10} + W_{20}))$$

$$\Rightarrow Q = 4C\mathcal{E}^2 - (2C\mathcal{E}^2 - \frac{10C\mathcal{E}^2}{25})$$

$$Q = 4C\mathcal{E}^2 - \frac{40C\mathcal{E}^2}{25} = \frac{60C\mathcal{E}^2}{25}$$

$$Q = \frac{12C\mathcal{E}^2}{5}$$

структура



$$q_1 = 4C \cdot (\varepsilon - \varphi) = I_0 \cdot \Delta t \quad \Rightarrow \quad \frac{I_0}{I_2} = \frac{4(\varepsilon - \varphi)}{\varphi}$$

$$q_2 = C \cdot \varphi = I_2 \cdot \Delta t$$

$$I_2 = I_0 - I_1 \quad \Rightarrow \quad I_2 = I_0 - \frac{\varphi}{R}$$

$$I_1 = \frac{\varphi}{R}$$

$$\frac{I_0}{I_0 - \frac{\varphi}{R}} = \frac{4(\varepsilon - \varphi)}{\varphi}$$

$$I_0 \cdot \varphi = 4(\varepsilon - \varphi) \left(I_0 - \frac{\varphi}{R} \right)$$

$$I_0 \cdot \varphi = 4 \left(\varepsilon I_0 - \varphi I_0 - \varepsilon \frac{\varphi}{R} + \frac{\varphi^2}{R} \right)$$

$$I_0 \cdot \varphi = 4 \varepsilon I_0 - 4 \varphi I_0 - 4 \varepsilon \frac{\varphi}{R} + 4 \frac{\varphi^2}{R}$$

$$4\varphi^2 - 4\varepsilon\varphi - 4\varphi I_0 R + 4\varepsilon I_0 R - \underline{I_0 \varphi R} = 0$$

$$4\varphi^2 - 4\varepsilon\varphi +$$

$$4\varphi^2 - \varphi(4\varepsilon + 5I_0 R) + 4\varepsilon I_0 R = 0$$

$$D = 16\varepsilon^2 + 40\varepsilon I_0 R + 25I_0^2 R^2 - 64\varepsilon I_0 R = 16\varepsilon^2 - 24\varepsilon I_0 R + 25I_0^2 R^2$$

$$\varphi = \frac{4\varepsilon + 5I_0 R \pm \sqrt{16\varepsilon^2 - 24\varepsilon I_0 R + 25I_0^2 R^2}}{8}$$

ОТВЕТ: 1) $I_R = \frac{4\varepsilon}{5R}$

2) $Q = \frac{12C\varepsilon^2}{5}$

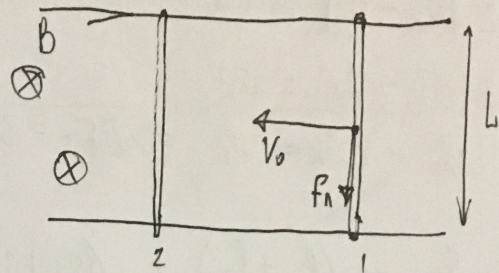
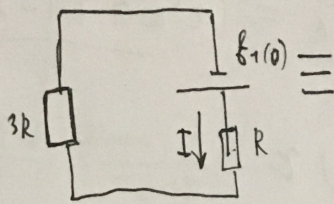
3) $\varphi = \frac{4\varepsilon + 5I_0 R \pm \sqrt{16\varepsilon^2 - 24\varepsilon I_0 R + 25I_0^2 R^2}}{8}$

4) Ускорит

L, S_0
 $2m, R, v_0$
 $m, 3R$

- 1) $a_{10} - ?$
- 2) $v - ?$
- 3) $S - ?$

1) $\mathcal{E}_1(t) = B \cdot v_0 \cdot L$



Скорость 2 пренебрежим в нач. момент = 0, т.к она скачком не меняется $\Rightarrow F_A$

т.к $F_{A1}(0) = B v_0 q = E \cdot q = \frac{\mathcal{E}_1}{L} \cdot q$

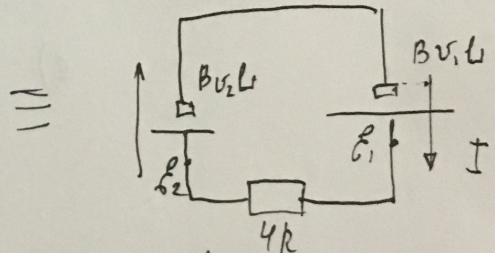
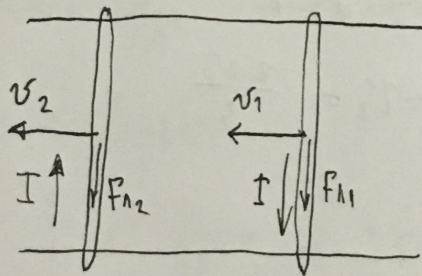
$\mathcal{E}_1(0) = B v_0 L$

$I = \frac{\mathcal{E}_1(0)}{4R} = \frac{B v_0 L}{4R}$

$F_A = B I L = \frac{B^2 L^2 \cdot v_0}{4R}$

23H: $F_A = 2 \text{ мА} \Rightarrow a = \frac{F_A}{2m} = \frac{B^2 L^2 \cdot v_0}{8mR}$

2)



Через продолжительный промежуток времени ск-ти ~~перемещ~~ станут постоянными

В какой-то момент ск-ти пренебрежительно

тогда $\mathcal{E}_2 = \mathcal{E}_1 \Rightarrow I = 0 \Rightarrow F = 0 \Rightarrow a = 0$

$F_1 = 2 \text{ мА} = 2m \frac{\Delta v}{\Delta t}$

$F_1 = B I L ; I = \frac{\mathcal{E}_1 - \mathcal{E}_2}{4R} = \frac{B v_1 L - B v_2 L}{4R} = \frac{B L}{4R} (v_1 - v_2)$

$F_2 = m \cdot a_2 = B I L = \frac{B L}{4R} (v_1 - v_2)$

$F_1 = F_2$

$2|a_1| = |a_2|$

$2 \frac{\Delta v_1}{\Delta t} = \frac{\Delta v_2}{\Delta t} \Rightarrow 2 \Delta v_1 = \Delta v_2 \quad (*)$

(3)

Продифференцируем (*) учитывая

$$2(v_k - v_0) = v_k$$

$$2(v_0 - v_k) = v_k$$

$$2v_0 - 2v_k = v_k \Rightarrow 2v_0 = 3v_k \Rightarrow v_k = v_1 = v_2 = \frac{2v_0}{3}$$

$$3) S = S_0 + (l_1 + l_2) + (v_1 + v_2) \tau$$

$$\frac{\Delta v_1}{\Delta t} = \frac{B^2 l^2 (v_1 - v_2)}{8mR}$$

$$|\Delta v_1| = B^2 l^2 (v_1 - v_2) / 8mR \cdot \Delta t = B^2 l^2 / 8mR (S_1 - S_2) \quad (**)$$

$$\Delta v_2 = B^2 l^2 (v_1 - v_2) / 4mR \cdot \Delta t = \frac{B^2 l^2}{4mR} (S_1 - S_2) \quad (***)$$

Продифференцируем (**) и (***)

$$\frac{2v_0}{3} = B^2 l^2 mR (S_1 - S_2)$$

$$\text{ОТВЕТ: 1) } a = \frac{B^2 l^2 v_0}{8mR}$$

$$2) v_1 = v_2 = \frac{2v_0}{3}$$

№5 Умова

$$F = 18 \text{ см}$$

$$H = 9 \text{ см}$$

$$d = 72 \text{ см}$$

$$l = 24 \text{ см}$$

1) x

2) D_M

3) r

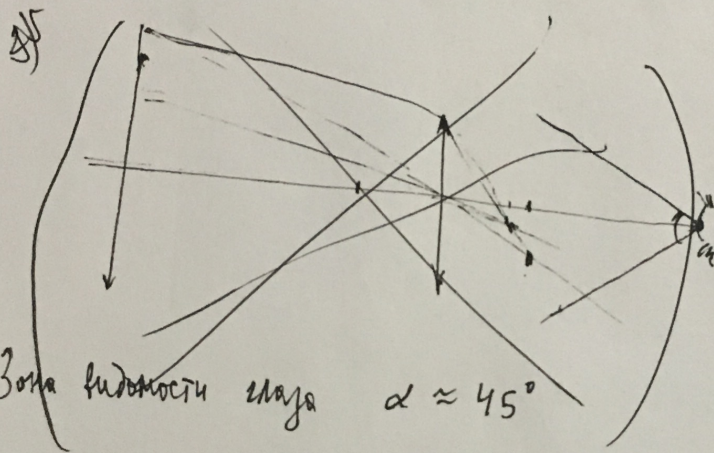
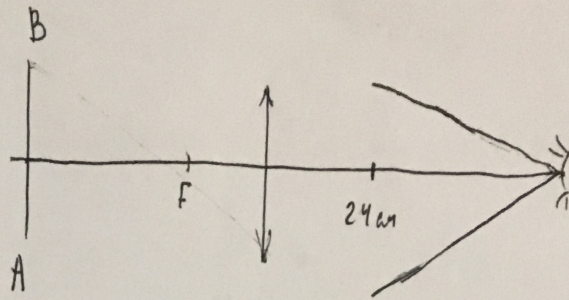
$$\frac{1}{F} = \frac{1}{d} + \frac{1}{f}$$

$$\frac{d-F}{Fd} = \frac{1}{f}$$

$$f = \frac{F \cdot d}{d-F} = \frac{18 \cdot 72}{72-18}$$

$$f = \frac{18 \cdot 72}{354} = 24 \text{ см}$$

$$x = l + f = 48 \text{ см}$$



Зона видимости глаза $\alpha \approx 45^\circ$

2) $D_M \geq D_{\text{разр}}$

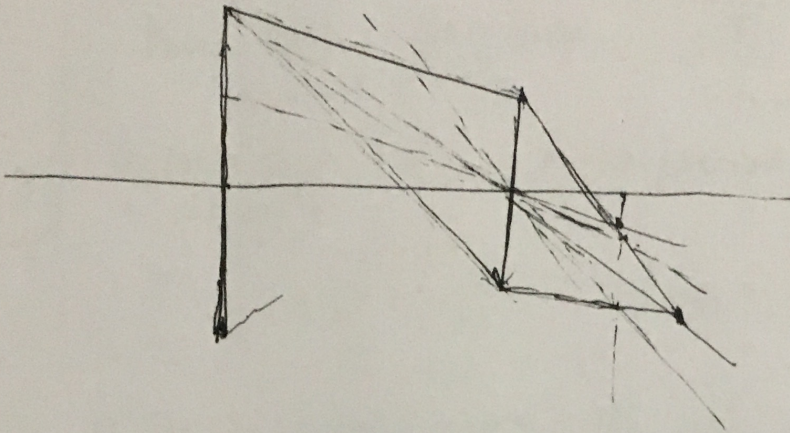
$$\Gamma = \frac{f}{d} = \frac{24}{72} = \frac{3}{9} = \frac{1}{3}$$

$$D_{\text{разр}} = AB \cdot \Gamma = D_{\text{мин}} = 9 \cdot \frac{1}{3} = 3 \text{ см}$$

ОТВЕТ: 1) $x = 48 \text{ см}$

2) $D_{\text{мин}} = 3 \text{ см}$

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$$v_k = 200$$

$$F = B q v$$

$F \rightarrow$

$\rightarrow F$

$$f = \frac{F}{q}$$

$$F = E \cdot I$$

$$E = \frac{F}{I}$$

$$B q v = \frac{q}{I} \frac{F}{I} =$$

$$\frac{72}{18} = 54$$

№3

$C_2 = C$
 $C_1 = 4C$

1) $I_{R} - ?$

2) $Q - ?$

3) $U - ?$

$(I_0 = I_C, \dots)$

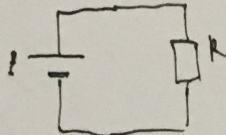
1) Рассчитать ток до замыкания

$U_{C1} = U_{C2} = 0$, т.к. $q = 0$

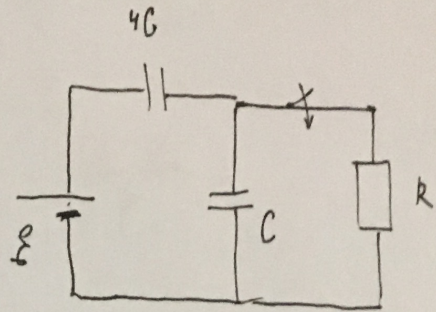
Рассчитать момент сразу после замыкания

$U_{C1}(0) = U_{C2}(0) = 0$, т.к. напряжение на конденсаторах не меняется.

\Rightarrow



$I_R(0) = \frac{\varepsilon}{R}$



2) До замыкания ключа $W_{C1} = W_{C2} = 0$

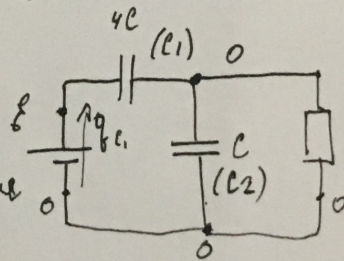
Сразу после $W_{C1}(0) = W_{C2}(0) = 0$, т.к. $U(0) = 0$

$A = Q + \Delta W \Rightarrow Q = A - \Delta W$

Рассчитать энергию в уст. режиме

Исп. метод узловых потенциалов;

Ток через резистор не течёт т.к. уст. состояние



$\Rightarrow U_R = 0$

$W_{C2}(\text{уст}) = \frac{C U_2^2}{2} = 0$

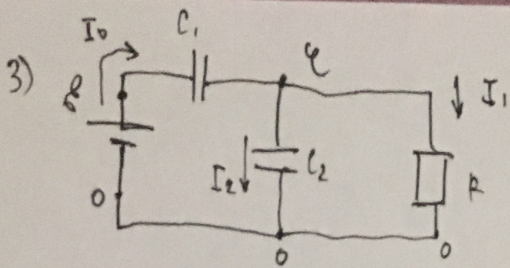
$W_{C1}(\text{уст}) = \frac{4C \varepsilon^2}{2} = 2C \varepsilon^2$

$q_{C1} = C U_1 = 4C \cdot \varepsilon$

$\Rightarrow A = \varepsilon \cdot q_{C1}$

$q_{C2} = C_2 \cdot U_2 = C_2 \cdot 0 = 0$

$Q = A - (W_{C1} + W_{C2} - 0) =$



$$q_1 = C_1 \cdot (\xi - \varphi)$$

$$q_2 = C_2 \cdot \varphi$$

$$q_1 = I_0 \cdot dt$$

$$q_2 = I_2 \cdot dt$$

$$\Rightarrow \frac{I_0}{I_2} = \frac{\xi - \varphi}{\varphi}$$

$$\left. \begin{array}{l} I_2 = I_0 - I_1 \\ I_1 = \frac{\varphi}{R} \end{array} \right\} \Rightarrow I_2 = I_0 - \frac{\varphi}{R}$$

$$\frac{I_0}{I_0 - \frac{\varphi}{R}} = \frac{\xi - \varphi}{\varphi}$$

$$I_0 \cdot \varphi = (\xi - \varphi) \left(I_0 - \frac{\varphi}{R} \right)$$

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$$I_0 \varphi = I_2 \varphi (\xi - \varphi)$$

$$I_2 = \frac{I_0 \varphi}{\xi - \varphi}$$

$$\frac{I_0 \varphi}{\xi - \varphi} = I_0 - \frac{\varphi}{R}$$

$$I_0 \varphi R = I_0 \varphi R - I_0 \varphi R + \varphi^2 + \varphi^2$$