

Часть 1

Олимпиада: **Физика, 11 класс (1 часть)**

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Вариант 3

(N2)

1) $Q_1 = -\delta Q(T) = -\nu \cdot c(T) \cdot \Delta T =$ $i=3$

$= -3\nu R \frac{T \Delta T}{T_0}$ (*) ΔT - изменение температуры от T_0 до T .

Суммируем (**):

$$-\sum \delta Q = Q_1 = -\frac{3\nu R}{T_0} \sum T \Delta T = -\frac{3\nu R}{T_0} \left(\frac{T_{\max}^2}{2} - \frac{T_{\min}^2}{2} \right) =$$

$$= \frac{3\nu R}{2T_0} \left(T_0^2 - \frac{9}{25} T_0^2 \right) = \frac{3}{2} \cdot \frac{16}{25} \nu R T_0 = \frac{48}{50} \nu R T_0 = 0,96 \nu R T_0$$

2) $Q = \Delta U + A$

$A = Q - \Delta U$

$A = A(T) = 3\nu R \frac{T \Delta T}{T_0} - \frac{3}{2} \nu R \Delta T = 3\nu R (T_0 - T) \left(\frac{T}{T_0} - \frac{1}{2} \right) = \frac{3\nu R}{T_0} (-2T^2 + 3T_0 T - T_0^2)$
 $\Delta T = T_0 - T \rightarrow$

3) $A_{\min} = A(T_{\min}) = A\left(\frac{3T_0}{4}\right) =$

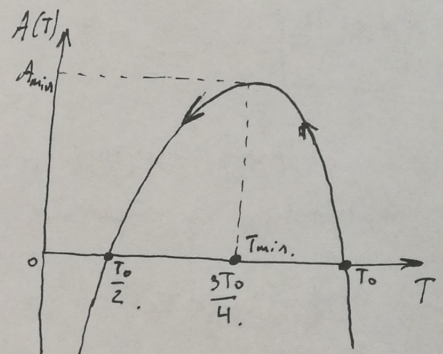
$= \frac{3\nu R}{T_0} \left(-2 \cdot \frac{9}{16} T_0^2 + 3 \cdot \frac{3T_0^2}{4} - T_0^2 \right) =$

$= \frac{3\nu R}{T_0} \left(-\frac{9}{8} T_0^2 + \frac{9}{4} T_0^2 - T_0^2 \right) =$

$= 3\nu R T_0 \left(\frac{9}{4} - \frac{9}{8} - 1 \right) =$

$= 3\nu R T_0 \left(\frac{9}{8} - 1 \right) = 3\nu R T_0 \left(\frac{1}{8} \right) =$

$= \frac{3}{8} \nu R T_0$



В силу симметрии

$T_{\min} = \frac{T_0 + \frac{T_0}{2}}{2} = \frac{3T_0}{4}$

① Ответ: $0,96 \nu R T_0$; ② $\frac{3T_0}{4}$; ③ $\frac{3}{8} \nu R T_0$.

$$3DR / (2 - 2 - 2 \dots)$$

реповем.

$$-Q_1 =$$

$$Q = \Delta U + A$$

$$A = Q - \Delta U$$

$$A = 3DR \frac{T \Delta T}{T_0} - \frac{1}{2} DR \Delta T =$$

$$= 3DR \left(\frac{T \Delta T}{T_0} - \frac{\Delta T}{2} \right) \geq 0$$

$$\frac{T \Delta T}{T_0} - \frac{\Delta T}{2} > 0$$

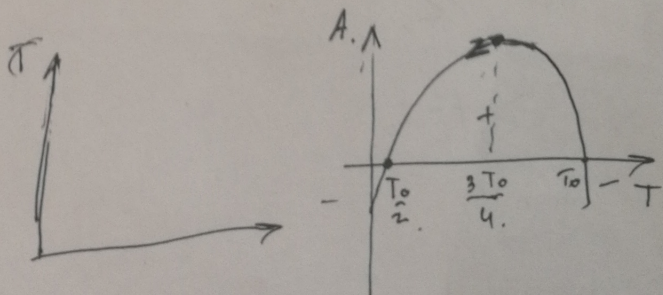
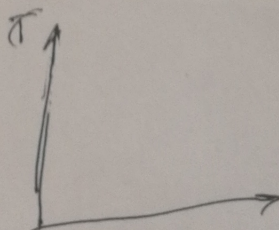
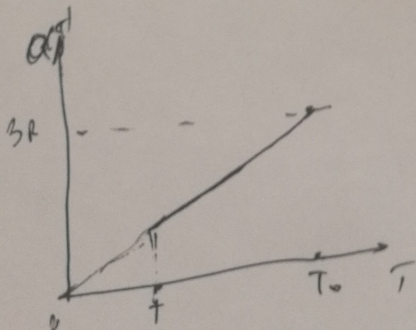
$$\frac{T}{T_0} - \frac{1}{2} < 0$$

$$\frac{T}{T_0} < \frac{1}{2}$$

$$T \leq \frac{T_0}{2}$$

$$A_r = 3DR$$

$A(T)$



$$D = 9T_0^2 - 8T_0^2 = T_0$$

$$T_{1,2} = \frac{-3T_0 \pm T_0}{-4} = \left[\begin{array}{l} T_0 \text{ и } \\ \frac{T_0}{2} \end{array} \right]$$

$$A_{min} = 3DR \left(\frac{\frac{T_0}{2} \cdot \left(\frac{T_0}{2} - T_0 \right)}{T_0} - \frac{T_0 - T_0}{2} \right) =$$

$$= 3DR \left(\frac{T_0}{2} - T_0 \right) \cdot \left(\frac{\frac{T_0}{2}}{T_0} - \frac{1}{2} \right) =$$

$$= 3DR \cdot -\frac{1}{2} T_0 \cdot \left(\frac{1}{2} - \frac{1}{2} \right) = 0$$

$$A = 3DR \Delta T \left(\frac{T}{T_0} - \frac{1}{2} \right) \geq 0$$

$A \geq 0$

$$A \geq 3DR (T_0 - T) \left(\frac{T}{T_0} - \frac{1}{2} \right) \geq 0$$

$$T_0 - T \left(\frac{T}{T_0} - \frac{1}{2} \right) \geq 0$$

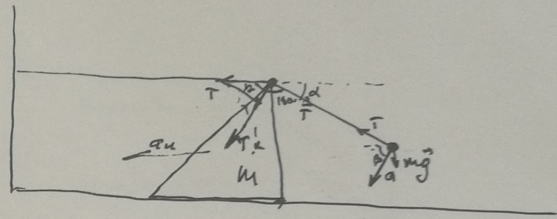
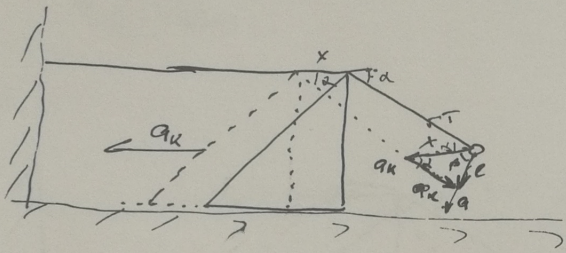
$$\frac{T \cdot T_0}{T_0} - \frac{T^2}{T_0} - \frac{T_0}{2} + \frac{T}{2} \geq 0$$

$$T - \frac{T^2}{T_0} - \frac{T_0}{2} + \frac{T}{2} \geq 0$$

$$-\frac{T^2}{T_0} + \frac{3T}{2} - \frac{T_0}{2} \geq 0$$

$$-2T^2 + 3T_0T - T_0^2 \geq 0$$

реповек.



$$a = a_k \cdot \sqrt{2(1 - \cos \alpha)} = \frac{4}{\sqrt{15}} a_k$$

$$T_k = \frac{4}{\sqrt{15}} T$$

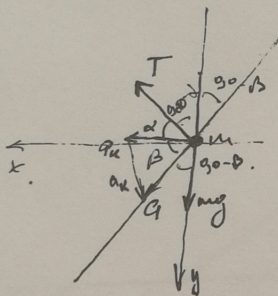
$$T_x = T_k \cdot \cos \beta$$

$$T - T \cdot \cos \alpha =$$

$$M a_k =$$

$$\frac{T_x \cdot T(1 - \cos \alpha)}{M}$$

1)

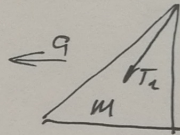


$$m a = m g \cdot \sin \beta - T \cdot \cos(90^\circ - \beta - \alpha)$$

$$a = g \sin \beta - T \cos(90^\circ - (\alpha + \beta))$$

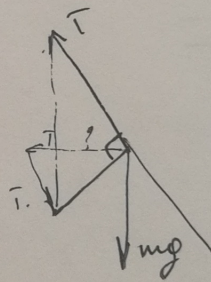
$$m g (H - l \cdot \cos \beta)$$

2)

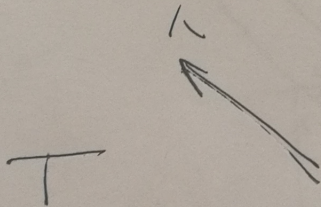


$$M a_k = T_x$$

$$a_k = \frac{T_x}{M}$$



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674
~~100~~



21202318 (U372996 M1268518) $\left(\frac{12}{4} = \frac{6}{2} \right)$

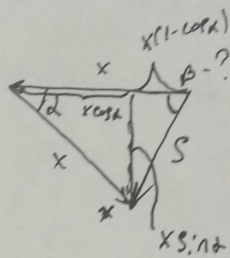
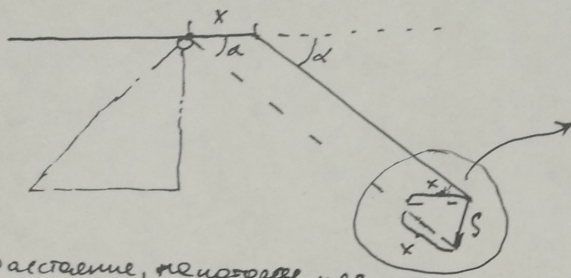
$\frac{1}{2} \beta = \frac{1}{2}$

(M1)

Рассмотрим митб:

$$\cos \alpha = \frac{5}{13} \Rightarrow S \sin \alpha = \frac{12}{13}$$

~~x - часть митба, которая~~



x - расстояние, которое шарик перемещается или за время tau

$$\tan \beta = \frac{x \sin \alpha}{x(1 - \cos \alpha)} = \frac{S \sin \alpha}{1 - \cos \alpha} =$$

$$= \frac{\frac{5}{13}}{1 - \frac{12}{13}} = \frac{5}{13 - 12} = 5$$

$$= \frac{\frac{12}{13}}{1 - \frac{5}{13}} = \frac{12}{13 - 5} = \frac{12}{8} = \frac{3}{2}$$

$$\tan \beta = \frac{3}{2}$$

Т.т. 4

(это заданную ауграню)

2. S - перемещение шарика за время tau

$$S = \sqrt{2x^2 - 2x^2 \cos \beta} =$$

$$= x \sqrt{2(1 - \cos \alpha)} =$$

$$= x \frac{4}{\sqrt{15}}$$

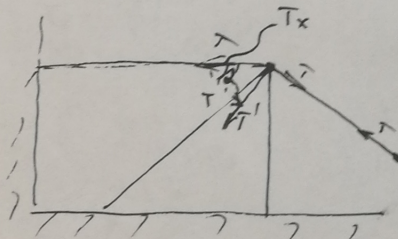
Дифференцируя получим ускорение z раз меньше, что

$$a_m = \frac{4}{\sqrt{15}} a_k$$

Qm - ускорение шарика

Qk - ускорение митба,

ускорение шарика направлено вертикально по T



$$T_x = T(1 - \cos \alpha) = \frac{4}{\sqrt{15}}$$

решение.

$$-Q_1 = \Delta U_1 + A_1$$

$$-2C\Delta T = \frac{3}{2}DR\Delta T +$$

$$\int Q_1 = -2C\Delta T = -2 \cdot 3R \frac{T\Delta T}{T_0}$$

$$\oint \int Q_1 = -\int \frac{3DR}{T_0} \int T\Delta T$$

$$Q_1 = -\frac{3DR}{T_0} \left(\frac{3}{25}T_0^2 - T_0^2 \right)$$

$$Q_1 = 3DR \left(\frac{16}{25}T_0 \right)$$

$$Q_1 = -\frac{3DR}{2T_0} \cdot -\frac{16}{25}T_0^2 = \frac{3}{2} \cdot \frac{16}{25} \cdot DR T_0 = \frac{48}{50} DR T_0 = 0,96 DR T_0$$

$$+Q_1 = \Delta U + A$$

$$A = -\frac{3}{2}DR\Delta T + 3DR \frac{T\Delta T}{T_0} = 3DR \left(\frac{\Delta T}{2} + \frac{T\Delta T}{T_0} \right) > 0$$

$$\frac{\Delta T}{2} + \frac{T\Delta T}{T_0} > 0 \quad A = \frac{3}{2}DR \left(\frac{T_0 - T_0}{T_0 - \frac{T_0}{2}} \right)$$

$$\frac{1}{2} + \frac{T}{T_0} > 0$$

$$A = \frac{3}{2}DR \frac{T_0 - T_0}{\frac{T_0}{2} - T_0}$$

$$\frac{T}{T_0} > -\frac{1}{2}$$

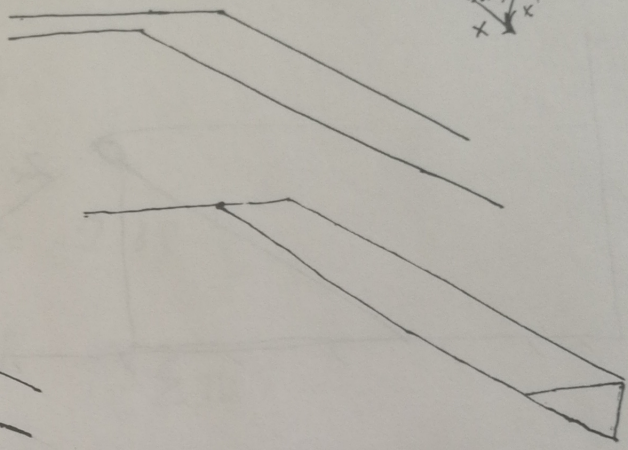
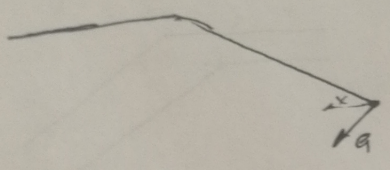
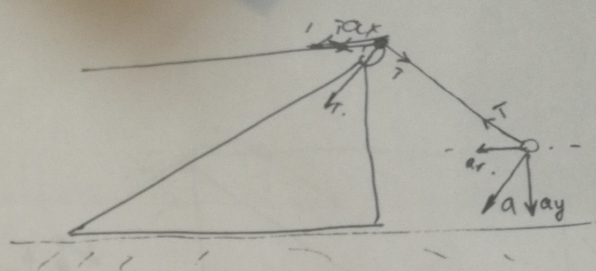
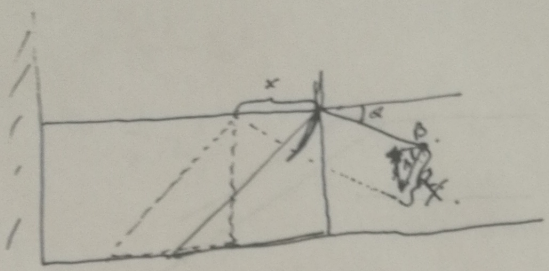
$$T \geq -\frac{1}{2}T_0$$

$$3DR(-2T^2 + 3T_0T - T_0^2) = A_T(T)$$

reproblem

$$3DR\left(-2 \cdot \frac{9T_0^2}{16} + \frac{9}{4} - 3\right) = A_T(T)$$

reproblem



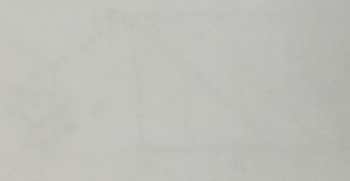
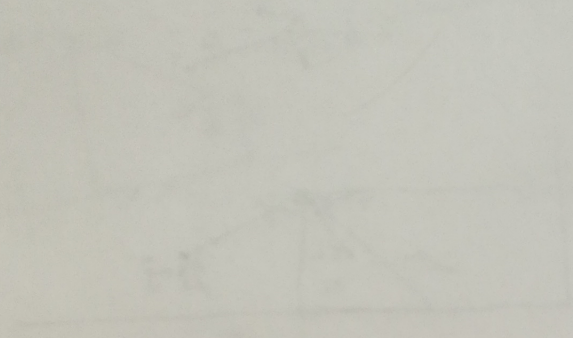
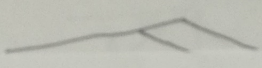
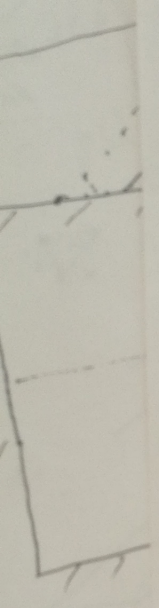
$$a_x = a \cdot \sin \alpha$$

$$x' = \sqrt{x^2 - 2x^2 \cdot \cos \alpha} = x \sqrt{2(1 - \cos \alpha)}$$

$$= x \cdot \sqrt{2 \cdot \frac{8}{15}} = \frac{4\sqrt{2}}{\sqrt{15}} x$$

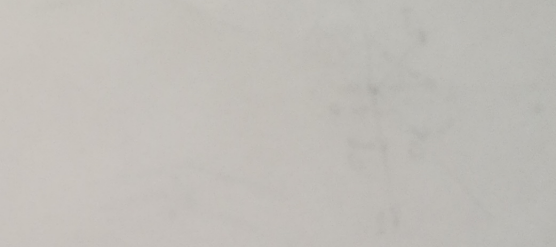
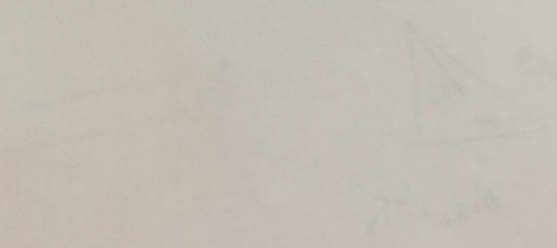
$$\frac{4}{\sqrt{15}} x$$

here.
nobue.



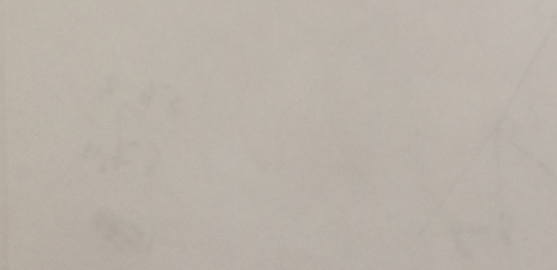
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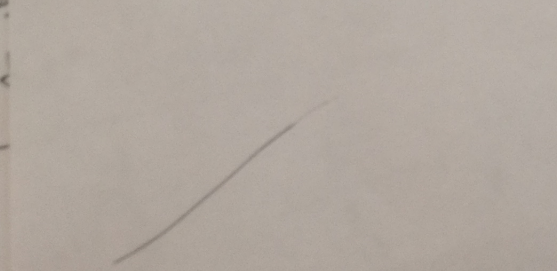


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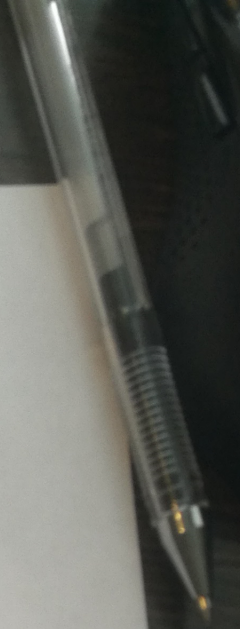
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3

$$3DR \left(-2T^2 + 3T_0T - T_0^2 \right) = Ar(T)$$

уравнение

$$3DR \left(-2 \cdot \frac{9T_0^2}{16} + \frac{9}{4} T_0T - T_0^2 \right) = Ar$$

$$3DR \left(\frac{9}{4} T_0^2 - \frac{9}{8} T_0^2 - T_0^2 \right) = Ar$$

$$3DR \left(\frac{9}{8} T_0 - T_0 \cdot \frac{1}{8} T_0^2 \right)$$

$$\frac{T(T_0 - T)}{T_0} = \frac{T_0 - T}{2} =$$

$$= T - \frac{T^2}{T_0} - \frac{T_0}{2} - \frac{T}{2}$$

Часть 2

Олимпиада: **Физика, 11 класс (2 часть)**

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Вариант 3

W3

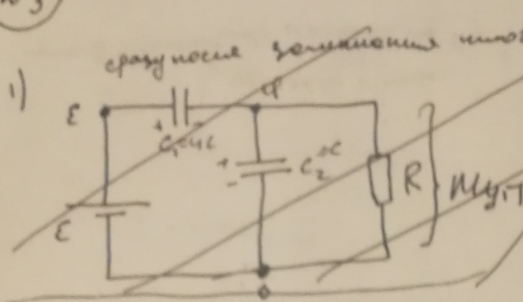
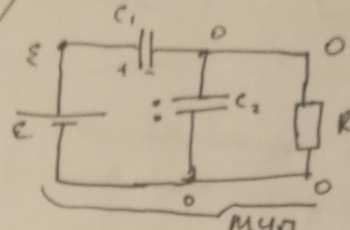
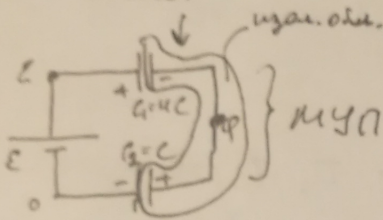


схема в установившемся состоянии 2:



$I_1(x) = 0$
 $I_2(x) = 0$, тогда R, C_1, C_2
 в установившемся режиме
 $2(x)$.

При размыкании ток

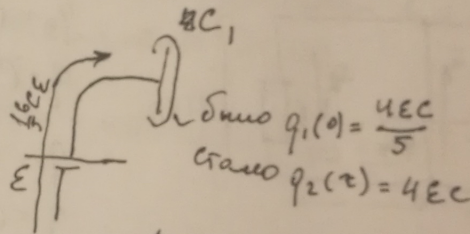


~~$C_1(x) = \dots$~~

$U_1(x) = E$
 $U_2(x) = 0$

$W(x) = \frac{4CE^2}{2} + 2CE^2$

Т.к конденсаторы в параллель
 друг не заменяет, и сейчас
 схема поворачивается в установившемся
 состоянии, то



ЗСЗ для изолированной области:

$A\delta = E \cdot \frac{16}{5} CE = \frac{16}{5} CE^2$

$-4C(E-\varphi) + C(\varphi-0) = 0$

$A\delta = \Delta W + Q \Rightarrow$

$-4E + 4\varphi + \varphi = 0$

$\Rightarrow Q = A\delta \frac{\Delta W}{\Delta W} = A\delta + W(0) - W(x)$
 $\Delta W = W(x) - W(0)$

$5\varphi = 4E$

$Q = \frac{16}{5} CE^2 + \frac{2}{5} CE^2 - 2CE^2$

$\varphi = \frac{4E}{5}$, тогда

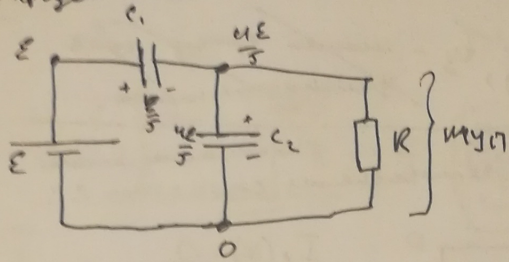
$Q = \frac{18}{5} CE^2 - 2CE^2 = \frac{8}{5} CE^2$

$U_1(0) = E - \varphi = \frac{E}{5}$ - напряжение на C_1 и C_2
 $U_2(0) = \varphi - 0 = \frac{4E}{5}$ бы в состоянии

Энергия в начале $W(0) = 4C \cdot \frac{E^2}{25} + C \cdot \frac{16E^2}{25} = \frac{10}{25} CE^2 = \frac{2}{5} CE^2$

Сразу после замыкания ключа:

прообраз

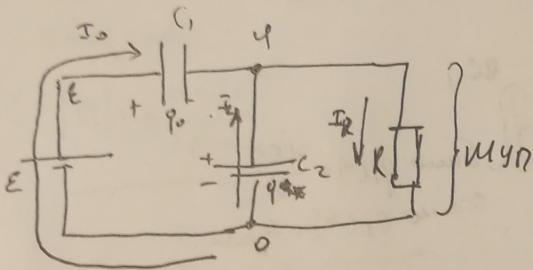


$$\begin{aligned} U_1(t_3) &= U_1(0) \\ U_2(t_3) &= U_2(0) \end{aligned} \quad t_3 \text{ — момент сразу после замыкания ключа}$$

$$U_R(t_3) = \frac{4E}{5}$$

$$I_R = \frac{U_R(t_3)}{R} = \frac{4E}{5R}$$

Тачно в момент времени T , $I_1(T) = I_0$.



$$q_0 = C_1 \cdot U_1$$

$$q = C_2 \cdot U_2$$

$$q_0 = 4C \cdot (\epsilon - \varphi) \Rightarrow q_0 = 4C\epsilon - 4q$$

$$q = C(\varphi - 0)$$

$$\varphi = \frac{q}{C}$$

Дифференцируем (*)

по времени:

$$q_0' = (4C\epsilon)' - 4q'$$

$$I_0 = 4I_2$$

$$I_1 = \frac{I_0}{4}$$

$$q' = -I_2$$

$$q_0' = I_0$$

$$(4C\epsilon)' = 0$$

$$\text{ЗСЗ: } I_0 + I_2 = I_R = \frac{5I_0}{4}$$

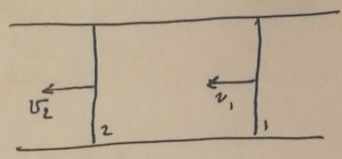
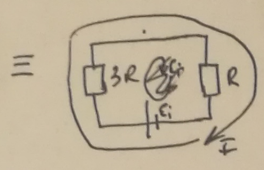
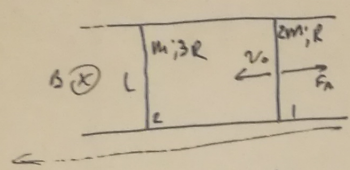
$$U_R(T) = \frac{5I_0}{4} \cdot R = \frac{5}{4} I_0 R$$

Отв: $\frac{4E}{5R}; \frac{8}{5} C\epsilon^2; \frac{5}{4} I_0 R.$

Тема: Справы 3 Физика 11-03.

(10)

$l = L$
(+)
через произвольное время:



$E_i = vBl \sin \alpha$

$I = \frac{E_i}{R+3R} = \frac{E_i}{4R} = \frac{vBl}{4R}$

$F_A = IBl \sin \alpha = \frac{vB^2 l^2}{4R}$

ЗЗН

$2mv_x = -FA$

$|a| = + \frac{vB^2 l^2}{4Rm}$

Скорость падает непрерывно через произвольное время $const \rightarrow a(t) = 0$.

$\Rightarrow FA(t) = 0 \Rightarrow I(t) = 0 \Rightarrow E_{i2} = E_{i1} \Rightarrow v_1 = v_2 = v$
 $E_i = vBl$

Далее будем непрерывно в системе массы изменять ЗЗН:

$2mv_0 = mv + 2mv \rightarrow v = \frac{2v_0}{3}$

ЗЗЭ где бери энергию:

$\frac{2mv_0^2}{2} = \frac{3mv^2}{2} + Q$; Q - выделенная теплота на resistorax.

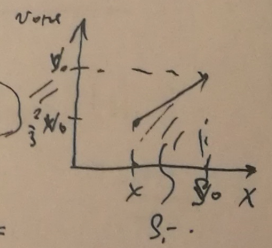
$mv_0^2 - \frac{3}{2}m \cdot \frac{4}{3}v_0^2 = Q$

$Q = \frac{1}{3}mv_0^2$

$Q = \frac{U(v)}{4R} \cdot dt = \int \frac{B^2 l^2}{4R} \cdot v_{отн}^2 \cdot dt = \frac{B^2 l^2}{4R} \cdot v_{отн} \cdot dx$ (*)

$U(v) = E_{i1}(v) - E_{i2}(v) = E_i - vBl$
 $= B l (v_1 - v_2) = B l \cdot v_{отн}$

$\int Q = Q = \frac{B^2 l^2}{4R} \int v_{отн} \cdot dx$



$\frac{1}{3}mv_0^2 = \frac{B^2 l^2}{4R} \cdot \frac{1}{2} (v_0 + \frac{2}{3}v_0) (S_0 - x)$

$\frac{1}{3}mv_0^2 = \frac{5B^2 l^2}{24R} \cdot v_0 \cdot (S_0 - x)$

$= \frac{B^2 l^2}{4R} \cdot \frac{5}{6} v_0 \cdot (S_0 - x)$

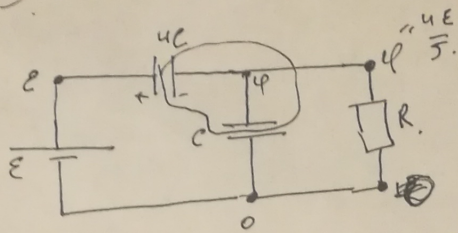
$\frac{24}{5 \cdot 3} \frac{mv_0 R}{B^2 l^2} = S_0 - x$

$x = S_0 - \frac{8}{5} \frac{mv_0 R}{B^2 l^2}$

Отсюда: $\frac{5B^2 l^2}{8R}, \frac{2v_0}{3}, S_0 - \frac{8}{5} \frac{mv_0 R}{B^2 l^2}, S_0 - \frac{8}{5} \frac{mv_0 R}{B^2 l^2}$

Зерновое:

(1)

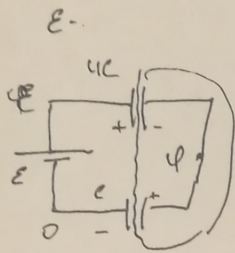


$$U_{uc}(0) = \frac{E}{5}$$

$$U_c(0) = \frac{4E}{5}$$

$$I_R(0) = \frac{4E}{5R}$$

$$A\delta = W + Q$$



3C3:

$$-4C(E-\varphi) + C(\varphi-0) = 0$$

$$4E - 4\varphi = \varphi$$

$$5\varphi = 4E$$

$$\varphi = \frac{4E}{5}$$

$$W(0) = \frac{4C \cdot \frac{E^2}{25}}{2} + \frac{C \cdot \frac{16E^2}{25}}{2} = \frac{2E^2}{25} + \frac{8E^2}{25} = \frac{10E^2}{25} = \frac{2}{5}CE^2$$

$$-4C(E-\varphi) + C(\varphi-0) = 0$$

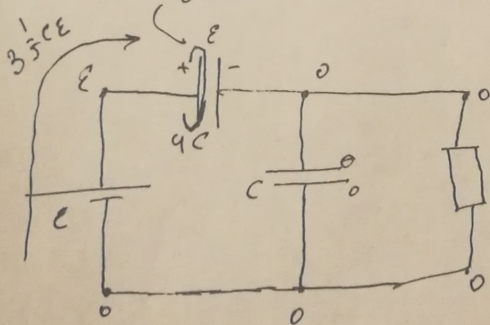
$$4(E-\varphi) = \varphi$$

$$4E - 4\varphi = \varphi$$

$$\varphi = \frac{4E}{5}$$

$$\delta_{\text{sum}} + 4C \cdot \frac{E}{5} = \frac{4}{5}CE$$

$$\text{Caus: } 4CE$$



$$A\delta = \frac{16}{5}CE^2$$

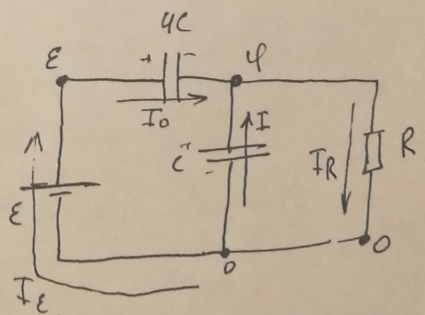
$$W(I_{\text{до}}) = \frac{4CE^2}{2} = 2CE^2$$

$$\frac{16}{5}CE^2 = 2CE^2 - \frac{2}{5}CE^2 + Q$$

$$\frac{16}{5}CE^2 - 2CE^2 + \frac{2}{5}CE^2 = Q$$

$$\frac{18}{5}CE^2 - 2CE^2 = Q$$

$$Q = \frac{8}{5}CE^2$$



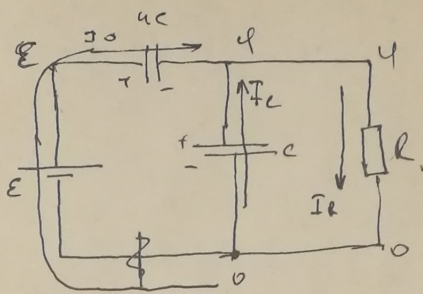
$$I_0 = 1CE^2$$

$$q_0 = 4Cu$$

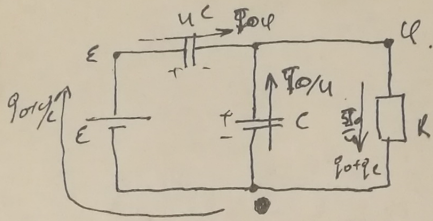
$$q = cu^2$$

$$U_{uc} = E - \varphi$$

$$U_c = \varphi$$



$$U_R = \frac{5I_0 R}{4R}$$



$$q_0 = C u$$

$$q_0 = 4C \cdot (E - u)$$

$$q = C(u)$$

$$u = \frac{q}{C}$$

$$q_0 = 4C \cdot E - 4C \cdot \frac{q}{C} =$$

$$q_0 = 4C E - 4q \quad |$$

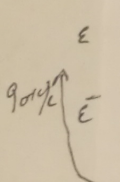
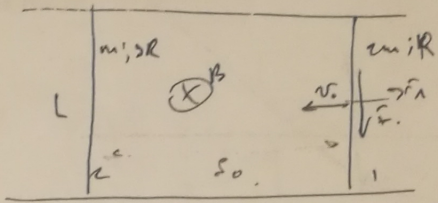
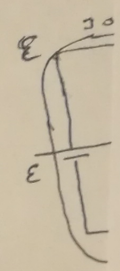
$$I_0 = 4I$$

$$I = \frac{I_0}{4}$$

M

W4

~~4) $v_1 = 0$~~



$$E = \epsilon_i = vB$$

$$I = \frac{vBe}{4R}$$

$$F_A = \frac{vBe}{4R} \cdot e \cdot B = \frac{vB^2 e^2}{4R}$$

$$2m\alpha = \frac{vB^2 e^2}{4R}$$

$$1) \alpha = \frac{vB^2 e^2}{8mR}$$

$$v_{\text{cm}} \cdot \Delta t$$

$$\frac{B^2 L^2}{4R} \cdot (\Delta x \cdot v_{\text{cm}})$$

$$Q = U \cdot q$$

$$E_i = -\phi'$$

$$E_i = \phi' =$$

$$= B \cdot x \cdot \cos \alpha'$$

$$E_{i1} - E_{i2} = U(t)$$

$$(v_1 - v_2) B e = U(t)$$

$$Q = \frac{U^2(t)}{R} \Delta t =$$

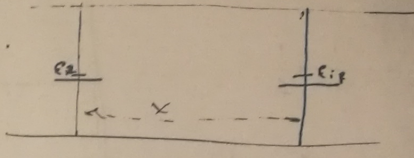
$$\frac{B^2 e^2}{4R}$$

$$= \frac{B^2 e^2}{4R} (v_1 - v_2)^2 \Delta t =$$

$$\frac{1}{3} m v_0^2 = \frac{B^2 e^2}{4R}$$

$$CO 2: \frac{dX}{dt} = \frac{B^2 e^2}{4R} \cdot \sum v_{\text{cm}} \Delta t =$$

$$= \frac{B^2 e^2}{4R} \cdot \left(\frac{v_1^2}{2} - \frac{v_0^2}{2} \right)$$



3)

$$E_{i1} = v_1 B e$$

$$E_{i2} = v_2 B e$$

$$v_1 = v_2$$

$$3CU: 2m v_0 = 3m v_1 =$$

$$\Rightarrow v_1 = \frac{2v_0}{3}$$

$$3CO: \frac{2m v_0^2}{2} = \frac{3m v_1^2}{2} + Q$$

$$v_0^2 = \frac{3}{2} v_1^2$$

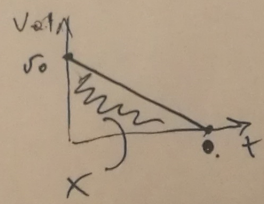
$$\frac{2m v_0^2}{2} - \frac{3}{2} m v_1^2 = Q$$

$$m v_0^2 - \frac{3}{2} m \frac{4}{9} v_0^2 = Q$$

$$m v_0^2 - \frac{2}{3} m v_0^2 = Q$$

$$\frac{1}{3} m v_0^2 = Q$$

$$v_{\text{cm}} = X(t)$$



2. problem

WS

$$\frac{1}{F} = \frac{1}{4F} + \frac{1}{f}$$

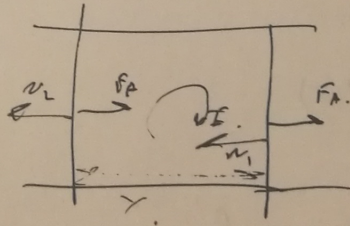
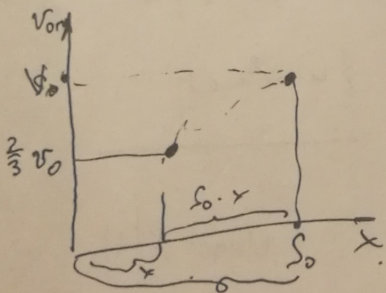
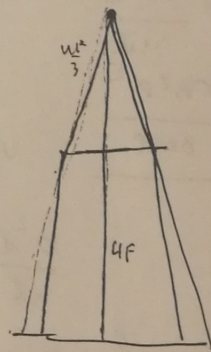
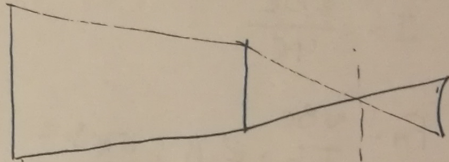
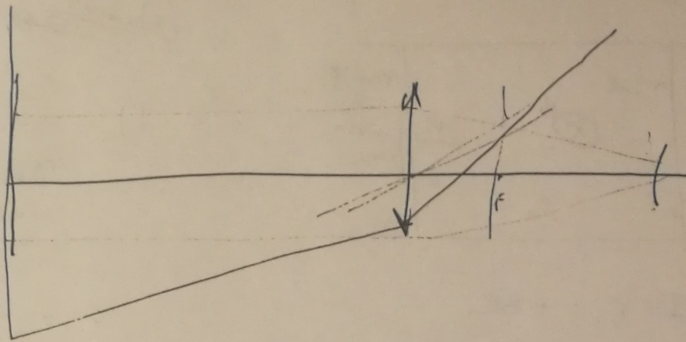
$$\frac{1}{f} = \frac{1}{F} - \frac{1}{4F} = \frac{3}{4F}$$

$$f = \frac{4F}{3}$$

$$\frac{1}{F} = \frac{1}{4F} + \frac{1}{f}$$

$$\frac{1}{f} = \frac{1}{F} - \frac{1}{4F} = \frac{3}{4F}$$

$$f = \frac{4F}{3} = 2 \text{ cm}$$



$$v_1 - v_2 = v_{\text{max}}$$

$$\Delta x = x_1 - x_2$$