

Часть 1

Олимпиада: **Физика, 11 класс (1 часть)**

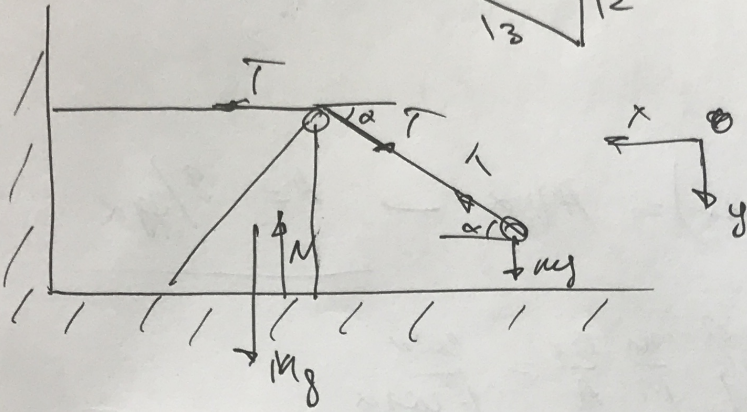
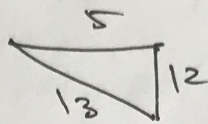
Шифр: **21202459**

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Вариант 3

#1.

Умови



УП (N1)

же маємо на ОА:

$$T \cos \alpha = M_A \quad (1)$$

Оу:

$$M_y - T \sin \alpha = M_A y \quad (2)$$

же маємо на ОХ:

$$T - T \cos \alpha = M_A \quad (3)$$

Після проміжних ст.,
ми знайдемо вибуток
на Δz.

x, маємо:

$$x_1 = p + \Delta z + l_1 \cos \alpha$$

$$x_2 = p + (l_1 + \Delta z) \cos \alpha$$

$$|\Delta x| = p + \Delta z + l_1 \cos \alpha - p - l_1 \cos \alpha - \Delta z \cos \alpha$$

$$|\Delta x| = \Delta z (1 - \cos \alpha)$$

y, маємо:

$$y_1 = l_1 \sin \alpha$$

$$y_2 = (l_1 + \Delta z) \sin \alpha$$

$$y_2 - y_1 = \Delta z \sin \alpha$$

$$\Delta z = \frac{A(\Delta t)^2}{2} \rightarrow \Delta z \sim A$$

$$\Delta x \sim a_x$$

$$\Delta y \sim a_y \quad (\text{аналогічно})$$

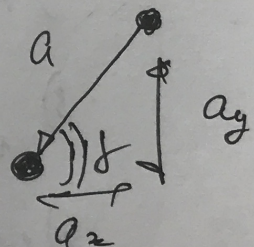
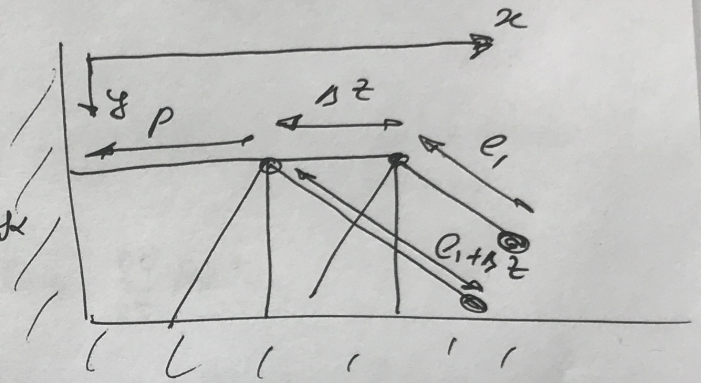
$$a_x = A(1 - \cos \alpha)$$

$$a_y = A \sin \alpha$$

$$\frac{a_y}{a_x} = \frac{\sin \alpha}{1 - \cos \alpha} = \frac{\frac{12}{13}}{1 - \frac{5}{13}} = \frac{12}{8} = \frac{3}{2}$$

у (1) $T = \frac{M_A}{\cos \alpha} \rightarrow \text{бо (2):}$

$$M_y - \max f_{y2} = M_A y$$



#1 Прогонимые шаровики CTP $\left(\frac{1}{2}\right)$

$$g - ax \text{ tg } \alpha = ay$$

$$g - A(1 - \cos \alpha) \text{ tg } \alpha = A \sin \alpha$$

$$g = A \left(\sin \alpha + \frac{\sin \alpha}{\cos \alpha} - \frac{\sin \alpha \cos \alpha}{\cos \alpha} \right) = A \text{ tg } \alpha \rightarrow \underline{A = g / \text{tg } \alpha}$$

$$\text{ay (3)} \quad MA = T(1 - \cos \alpha) \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \frac{m}{M} \frac{ax}{A} = \frac{\cos \alpha}{1 - \cos \alpha}$$

$$\text{ay (1)} \quad m ax = T \cos \alpha$$

$$\frac{m}{M} \cdot \frac{\cancel{A}(1 - \cos \alpha)}{\cancel{A}} = \frac{\cos \alpha}{1 - \cos \alpha}$$

$$\frac{m}{M} = \frac{\cos \alpha}{(1 - \cos \alpha)^2} = \frac{5}{13} = \frac{5}{\left(1 - \frac{5}{13}\right)^2} =$$

$$= \frac{\frac{5}{13} \cdot 13 \cdot 13}{64} = \frac{65}{64}$$

$$ay = A \sin \alpha = \frac{g}{\frac{\sin \alpha}{\cos \alpha}} \sin \alpha = g \cos \alpha$$

$$H = \frac{(\Delta t)^2 ay}{2} \rightarrow \Delta t = \sqrt{\frac{2H}{ay}} = \sqrt{\frac{2H}{g \cos \alpha}} = \sqrt{\frac{2H}{g \cdot \frac{5}{13}}} = \sqrt{\frac{26}{5} \frac{H}{g}}$$

Ответ: 1) $\text{tg } \alpha = \frac{3}{2}$

$$2) A = \frac{g}{\text{tg } \alpha} = g \cdot \frac{5}{12}$$

$$3) \frac{m}{M} = \frac{65}{64}$$

$$4) \Delta t = \sqrt{\frac{26}{5} \frac{H}{g}}$$

Задача

#2.

$T_0 \xrightarrow{\text{окл.}}$
 $C(T) = 3R \frac{T}{T_0}$

1) $C dT = p dV + \frac{3}{2} DR dT$ (100 war Temp)

$dT = pV$
 $dR dT = p dV + V dp \neq p dV$

$\delta Q = C dT$

$\int_0^Q \delta Q = \int_{T_0}^{\frac{3}{5}T_0} 3R \frac{T}{T_0} dT \cdot T$

$Q = \frac{3RV}{T_0} \frac{T^2}{2} \Big|_{T_0}^{\frac{3}{5}T_0} = \frac{3DR}{T_0} \cdot \frac{1}{2} T_0^2 \left(\frac{9}{25} - 1 \right) =$

$= -\frac{3}{2} DR T_0 \cdot \frac{16}{25} = -\frac{24}{25} DR T_0$ — *выбегенное тепло*

$\rightarrow Q_1 = -Q = \frac{24}{25} DR T_0$

2) $C dT = p dV + V dp + \frac{3}{2} DR dT$ *конец A мин dV=0*

~~$dT = pV$ $DR dT = p dV + V dp$~~

~~$3R \frac{T}{T_0} dT = p dV + \frac{3}{2} (p dV + V dp)$~~

~~$3 \frac{T}{T_0} \cdot (p dV + V dp) = p dV + \frac{3}{2} p dV + \frac{3}{2} V dp$~~

$C dT = dA + \frac{3}{2} DR dT$

$dA = C dT - \frac{3}{2} DR dT = 3R \frac{T}{T_0} dT - \frac{3}{2} DR dT$

мин A мин dA=0

$\rightarrow 3R \frac{T}{T_0} dT - \frac{3}{2} DR dT = 0$

$21202459 (1314991141263907) \frac{T}{T_0} = \frac{1}{2} \rightarrow \left(\frac{T}{T_0} = \frac{1}{2} \right)$

2 продолжение.

$$\int_0^A dA = \int_{T_0}^{T_0/2} 3R \frac{T}{T_0} dT - \int_{T_0}^{T_0/2} \frac{3}{2} DR dT$$

$$-\frac{3}{4} T_0^2$$

$$A = \frac{3RD}{T_0} \frac{T^2}{2} \Big|_{T_0}^{T_0/2} - \frac{3}{2} DR \left(\frac{T_0}{2} - T_0 \right) = \frac{3RD}{T_0} \cdot \frac{1}{2} \left(\frac{T_0^2}{4} - T_0^2 \right) + \frac{3}{2} DR \cdot \frac{T_0}{2} =$$

$$= -\frac{3}{4} T_0^2 \cdot \frac{3DR}{2T_0} + \frac{3}{4} DR T_0 = DR T_0 \left(\frac{3}{4} - \frac{9}{8} \right) = \underline{\underline{-\frac{3}{8} DR T_0}}$$

Ответ: 1) $Q_1 = \frac{24}{25} DR T_0$

2) $T_0/2$

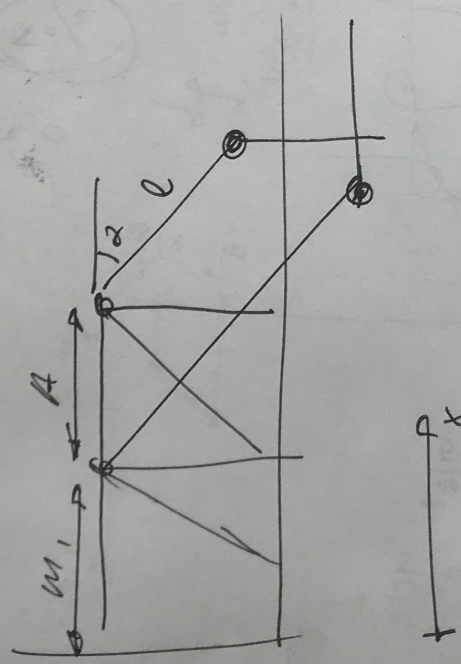
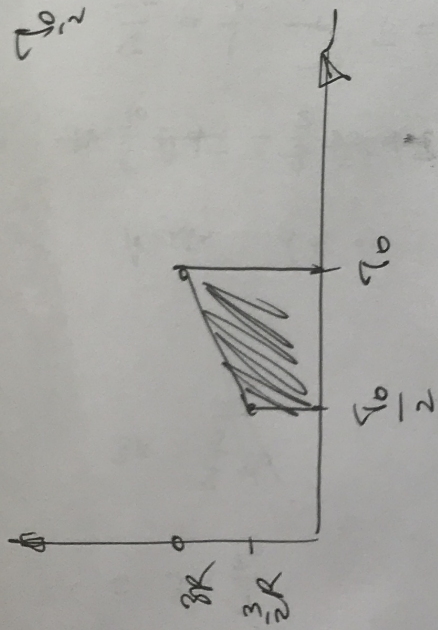
3) $A = -\frac{3}{8} DR T_0$

$$\frac{1}{2} \cdot 200 \cdot \frac{1}{2} (3 + 1.5) = \frac{9}{8} \cdot 200 \Rightarrow \frac{9}{8} \cdot 200$$

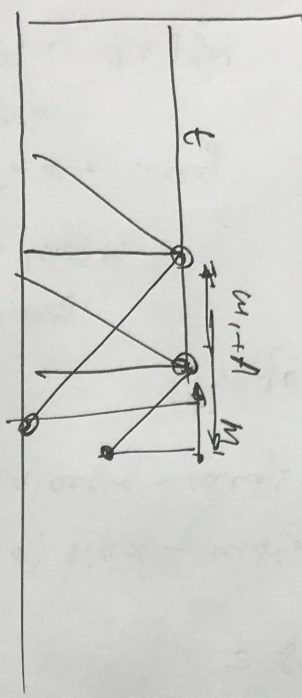
↑

$$+ \frac{3}{2} \cdot 200 \cdot \frac{10}{2} = \frac{3}{2} \cdot 2000 - \frac{9}{8} \cdot 200$$

$$\frac{6-3}{8} = -\frac{3}{8} \cdot 200$$



rechner

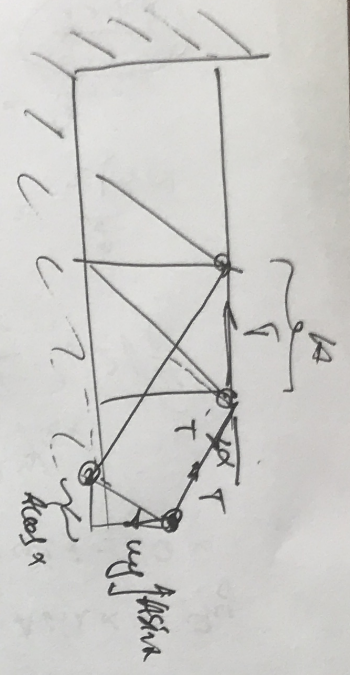


$$A + t + u_1 -$$

$$Ax =$$

$$\Delta X = A + A + \cos \alpha - (l + A) \cos \alpha$$

$$\Delta X = A + \cos \alpha - \cos \alpha - A \cos \alpha$$



$$\text{Max} = T \cos \alpha$$

$$\text{Weg} - T \sin \alpha = \text{Weg}$$

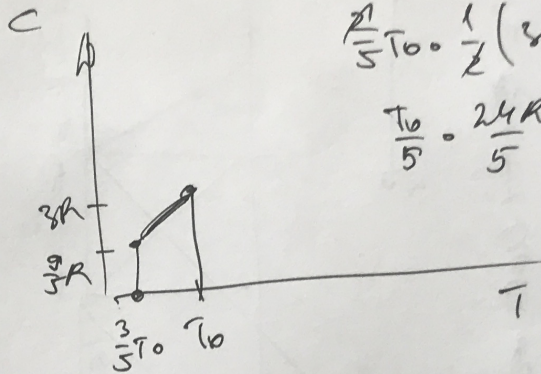
$$M_H = T (1 - \cos \alpha)$$

D. T_0

Упрощение

$$C = 3R \frac{T}{T_0}$$

$$3R \frac{3}{5} \frac{T_0}{T_0}$$



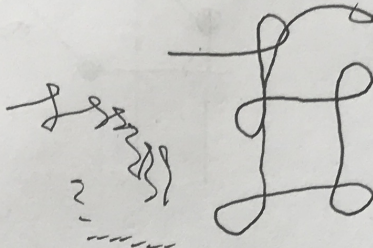
$$\frac{1}{5} T_0 = \frac{1}{2} (3R + \frac{3}{5} R)$$

$$\frac{T_0}{5} = \frac{24R}{5} = \frac{24}{25} T_0$$

$A_{min} \Delta A = 0$

$$3R \frac{T}{T_0} dT - \frac{3}{2} dR dT = 0$$

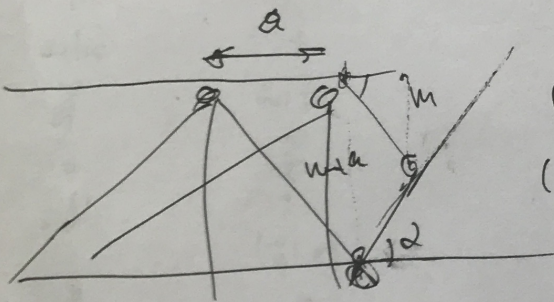
$$\frac{T}{T_0} = \frac{1}{2} \rightarrow T = \frac{T_0}{2}$$



$$dA = 3R \frac{T}{T_0} dT - \frac{3}{2} dR dT = 3 dR \left(\frac{T}{T_0} dT - \frac{dT}{2} \right) =$$

$$= 3 dR \left(\frac{1}{T_0} \left(-\frac{3}{8} T_0 dT \right) + \frac{T_0}{4} \right) = \cancel{3 dR T_0} \cdot 3 dR T_0 \left(\frac{1}{4} - \frac{3}{8} \right)$$

$$= 3 dR T_0 \cdot -\frac{1}{8} = -\frac{3}{8} dR T_0$$



$$(m+a) \sin \alpha - m \sin \alpha = A \sin \alpha = ay$$

$$(m+a) \cos \alpha - m \cos \alpha = A \cos \alpha = ax$$

$$\tan \alpha = \frac{ay}{ax}$$

$$ay - T \sin \alpha = may$$

$$T \cos \alpha = max$$

$$\sqrt{\frac{24}{5/2}} = 2\sqrt{\frac{24}{5}}$$

$$\frac{1 - \cos \alpha}{\cos \alpha} = \frac{may}{max}$$

$$ay - \frac{may}{\cos \alpha} \sin \alpha = may$$

$$ax = \frac{F}{2 \sin \alpha}$$

$$m - M = \frac{1}{1 - \cos \alpha} = \frac{1}{\frac{1}{3}} = 3$$

$$ay = \frac{F}{2}$$

$$A = \frac{F}{2 \sin \alpha}$$

$$T - T \cos \alpha = K \frac{F}{2 \sin \alpha}$$

$$T \cos \alpha = \frac{mg}{2 \sin \alpha}$$

#2.

$$\delta Q = C V dT$$

$$\frac{25}{16}$$

$D_0 D$

$$\delta Q = 3R \frac{T}{T_0} dT$$

$$T_0 \rightarrow \frac{3}{5} T_0$$

$$\int_0^Q \delta Q = \int_{T_0}^{\frac{3}{5} T_0} 3R \frac{T}{T_0} dT$$

$$Q = \frac{3RD}{T_0} \frac{T^2}{2} \Big|_{T_0}^{\frac{3}{5} T_0} = \frac{3DR}{T_0} \frac{1}{2} \left(\frac{9}{25} - 1 \right) T_0^2 =$$

$$= \frac{3}{2} DR \cdot T_0 \cdot \left(-\frac{16}{25} \right) = -\frac{24}{25} DR T_0$$

$$C V dT = p dV + \frac{3}{2} D R dT$$

$$A \text{ min } \text{yo } p dV = dA = 0$$

$$C = \frac{3}{2} R$$

$$3R \frac{T}{T_0} = \frac{3}{2} R$$

$$T = T_0/2$$

$$\int_0^A dA = \int_{T_0}^{T_0/2} C V dT - \frac{3}{2} D R dT$$

$$A = \frac{3RD}{T_0} \frac{T^2}{2} \Big|_{T_0}^{T_0/2} + \frac{3}{2} DR \cdot \frac{T_0}{2} = \frac{3DR}{2T_0} \cdot T_0^2 \left(\frac{1}{4} - 1 \right) + \frac{3}{4} DR T_0$$

$$= \frac{3}{2} DR T_0 \cdot \left(-\frac{3}{4} \right) + \frac{3}{4} DR T_0 = \frac{3}{4} DR T_0 \left(1 - \frac{3}{2} \right) = -\frac{3}{8} DR T_0$$

\rightarrow A empyamenent

результирующая

$$g - a_x \sin \alpha = g - \frac{g}{2} = \frac{g}{2}$$

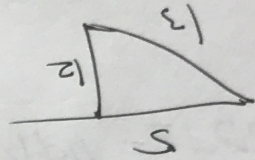
$$a_x \sin \alpha = g - a_x \sin \alpha$$

$$\frac{1}{1 - \cos \alpha} = \frac{1}{\frac{2}{3}} = 1.5$$

$$\frac{M}{m} \cos \alpha = \frac{1}{1 - \cos \alpha}$$

$$\frac{2\sqrt{14}}{8}$$

$$\frac{M}{m} \cos \alpha \sin \alpha = \frac{g}{1 - \cos \alpha}$$



$$M_A = T(1 - \cos \alpha)$$

$$M_{AK} = T \cos \alpha$$

$$\frac{1}{2} = \frac{1}{2}$$

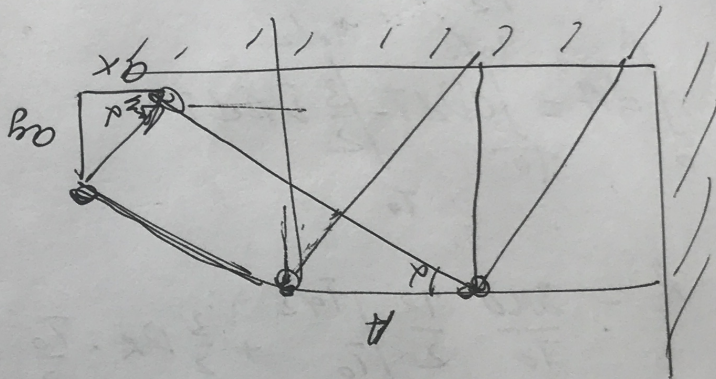
$$A = \frac{a_{gx}}{a_g} = \frac{2 \sin \alpha}{2} = \sin \alpha = \frac{12}{13}$$

$$a_{gx} = \frac{2}{13} g$$

$$a_{gy} = \frac{2}{13} g$$

$$a_x = \frac{2}{13} g$$

$$2 a_x \sin \alpha = g$$



$$a_{gx} = a_x$$

$$a_{gy} = a_y$$

$$a_{\text{ind}x} = a_x$$

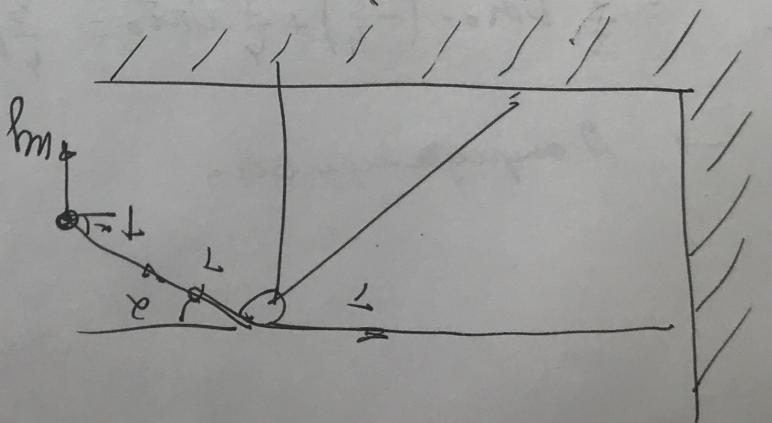
$$a_{gy} = g - a_y \sin \alpha$$

$$M_{Agy} = m y - T \sin \alpha$$

$$M_{Ax} = T \cos \alpha$$

$$M_{Ay} = m y - T \sin \alpha$$

$$M_A = T(1 - \cos \alpha)$$



Зрновик

$$\int_{T_0}^{\frac{3}{5}T_0} 3R \frac{T}{T_0} dT = \frac{3RD}{T_0} \left[\frac{9}{25}T_0^2 - T_0^2 \right] = -\frac{16}{25}T_0^2 \frac{3DR}{2T_0} = -\frac{24}{25}DR T_0$$

$$3R \frac{T}{T_0} dT = 0 + \frac{3}{2} dT$$

$$\frac{T}{T_0} = \frac{1}{2} \rightarrow T = T_0/2$$

$$\int_{T_0}^{T_0/2} 3R \frac{T}{T_0} dT = \int_{T_0}^{T_0/2} \frac{3}{2} DR dT = \frac{3RD}{T_0} \cdot \frac{1}{2} \left(\frac{T^2}{4} - T_0^2 \right) = \frac{3}{24} DR T_0 - \frac{3}{8} DR T_0 + \frac{3}{4} DR T_0 = -\frac{3}{8} DR T_0$$

$$-\frac{3}{8} DR T_0 + \frac{3}{4} DR T_0 = -\frac{9}{8} DR T_0$$

Упроблем

$$h = \sqrt{\frac{2M}{5g}}$$

$$g \frac{5}{2} t^2 = h$$

$$A = B / \sin \alpha$$

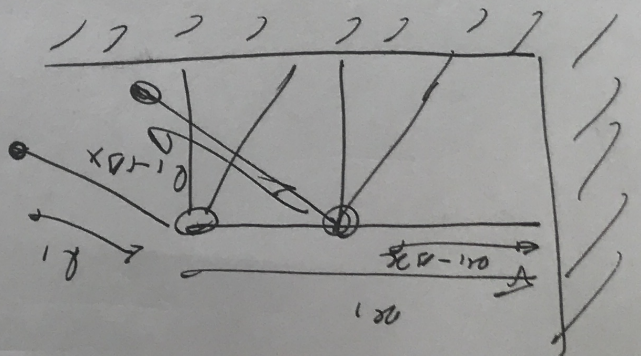
$$g - A \sin \alpha + A \cos \alpha = \text{шрих}$$

$$m g - m A (1 - \cos \alpha) \sin \alpha = m A \sin \alpha$$

$$m g - m a x \sin \alpha = m a y$$

$$g \cos \alpha = m a x$$

$$m g - T \sin \alpha = m a y$$



$$\left(\frac{39}{65} \right) =$$

$$\frac{65}{5} =$$

$$M \sin \alpha = \frac{M}{5} (1 - \cos \alpha)$$

$$\frac{\cos \alpha}{(1 - \cos \alpha)} = M \sin \alpha$$

$$\frac{9}{5} =$$

$$g \sin \alpha = \frac{9}{5} \sin \alpha = \frac{9}{5} \sin \alpha = g \sin \alpha$$

$$(g + 5x) \sin \alpha = 1.8 g x$$

$$g x^2 A (1 - \cos \alpha)$$

$$= 3x (5 \cos \alpha)$$

$$g x^2 A (1 - \cos \alpha) = 3x (5 \cos \alpha)$$

#1 Прямые

~~Угловые~~

N27

Объемные (4) и (5)

$$2ax \sin \alpha = g \quad ax = \frac{g}{2 \sin \alpha} ; \quad ay = ax + bx = g/2$$

$$\rightarrow T = \frac{m \cdot g}{\cos \alpha} = \frac{m \cdot g}{2 \sin \alpha \cos \alpha} = \frac{mg}{2 \sin \alpha}$$

у (6) и (8) с учетом малости α

~~$\frac{u}{ay} = \frac{A}{ay}$~~

$$\frac{x}{\Delta x} = \frac{A}{ax} = \frac{1}{\cos \alpha} \rightarrow A = \frac{ax}{\cos \alpha} = \frac{g}{2 \sin \alpha \cos \alpha} = \frac{g}{2 \sin \alpha}$$

$$M = \frac{T(1 - \cos \alpha)}{A}$$

$$m = \frac{T \cos \alpha}{ax}$$

$$\rightarrow \frac{M}{m} = \frac{1(1 - \cos \alpha)}{A} \cdot \frac{ax}{\cos \alpha} = \frac{\cos \alpha (1 - \cos \alpha)}{\cos \alpha} =$$

$$= 1 - \frac{5}{13} = \frac{8}{13}$$

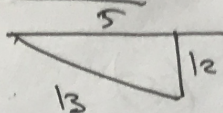
$$\Delta y' = H = \frac{ay t^2}{2} \Rightarrow t = \sqrt{\frac{2H}{ay}} = \sqrt{\frac{2H}{g} \cdot 2} = 2\sqrt{\frac{H}{g}}$$

Ответ: 1) най угол α ($\cos \alpha = 5/13$).

$$2) A = \frac{g}{2 \sin \alpha} = \frac{g}{2 \cdot \frac{12}{13}} = \frac{13}{24} g$$

$$3) \frac{m}{M} = \frac{13}{8}$$

$$4) t = 2\sqrt{H/g}$$

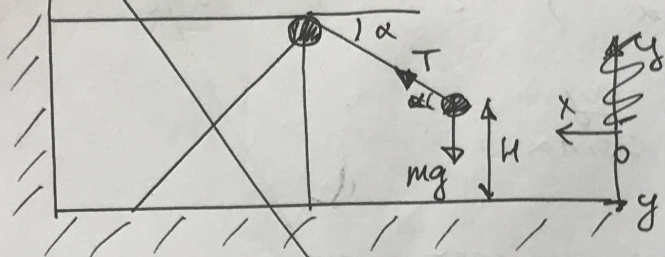


$$\cos \alpha = \frac{5}{13}$$

$$\sin \alpha = \frac{12}{13}$$

#1.

A - ускорение
кишки (горизонтальное)



Для шара на OK:

$$T \cos \alpha = m a_x \quad (1)$$

$$m g - T \sin \alpha = m a_y \quad (2)$$

Для кишки на OK:

$$M A_x = T - T \cos \alpha \quad (3)$$

$$\text{из (1)} \quad T = \frac{m a_x}{\cos \alpha}$$

из (2):

$$m g - \frac{m a_x}{\cos \alpha} \sin \alpha = m a_y$$

$$g = a_x \tan \alpha + a_y$$

$$a_y = g - a_x \tan \alpha \quad (4)$$

из условия нерастяжимости
нити

$$\Delta x + x + m_1 = \Delta x + m_2$$

$$x = m_2 - m_1 \quad (6)$$

Для шарика нах. поком. по

$$Oy: m_1 \sin \alpha$$

$$\text{корректировка: } m_2 \sin \alpha$$

$$\Delta y = (m_2 - m_1) \sin \alpha \quad (7)$$

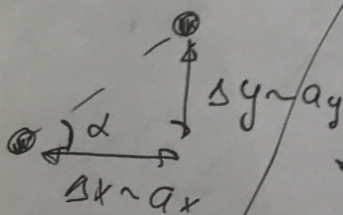
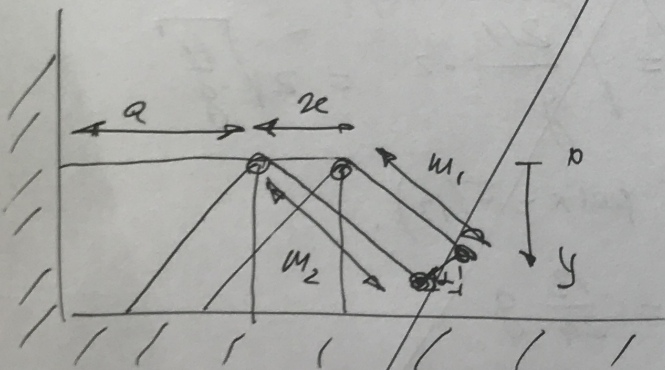
$$\Delta x = (m_2 - m_1) \cos \alpha \quad (8)$$

в нар. мом. (через ст-то): $\frac{\Delta y}{\Delta x} = \frac{a_y}{a_x} = \tan \alpha$

$$a_y = a_x \tan \alpha$$

$$\frac{a_y}{a_x} = \tan \alpha = \frac{12}{5} \quad (5)$$

Пусть промис ст:
киш свинется влево на x.



→ ускорение напр. нар
уши α.

Часть 2

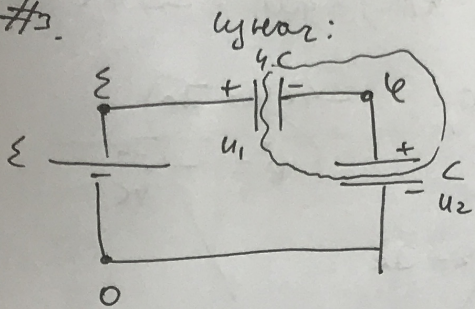
Олимпиада: **Физика, 11 класс (2 часть)**

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Вариант 3

#3.



решим уем $\rightarrow \sum = 0$
 выберем цгол. обл.
~~здесь все~~ верно: (по 3-му закону Кирхгофа)

$$0 = -4C(\varepsilon - \varphi) + C\varphi$$

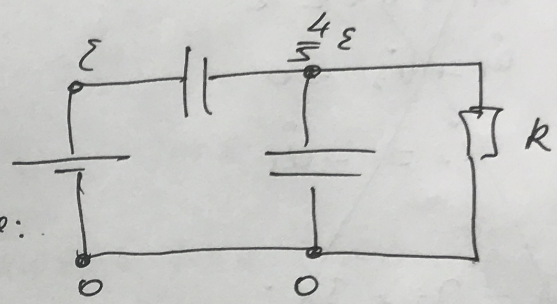
$$-4\varepsilon + 4\varphi + \varphi = 0$$

При замыкании ключа

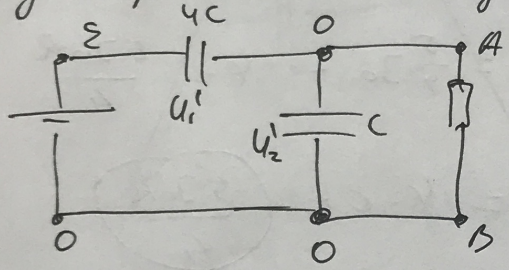
$$5\varphi = 4\varepsilon \rightarrow \varphi = \frac{4}{5}\varepsilon$$

и конденсаторов не изменится скачком:

$$I_R = \frac{\frac{4}{5}\varepsilon - 0}{R} = \frac{4\varepsilon}{5R}$$



Пусть решим снова установившееся:



$$I_R = 0 \rightarrow \varphi_A = \varphi_B = 0$$

$$\rightarrow u_1' = \varepsilon$$

$u_2' = 0$ разн. левого обкладки C_1 .

$$q(0) = u_1 \cdot 4C = (\varepsilon - \varphi)4C = \frac{\varepsilon}{5} \cdot 4C$$

$$q' = u_1' \cdot 4C = \varepsilon \cdot 4C$$

по ЗКЗ:

$$\Delta q = C\varepsilon \left(4 - \frac{4}{5} \right) = C\varepsilon \cdot \frac{16}{5}$$

~~W(t) = Q~~ $A\varepsilon = \Delta W + Q$

$$Q = A\varepsilon - \Delta W = C\varepsilon \cdot \frac{16}{5} \cdot \varepsilon - \left(\frac{4Cu_1'^2}{2} + \frac{Cu_2'^2}{2} - \frac{4Cu_1^2}{2} - \frac{Cu_2^2}{2} \right)$$

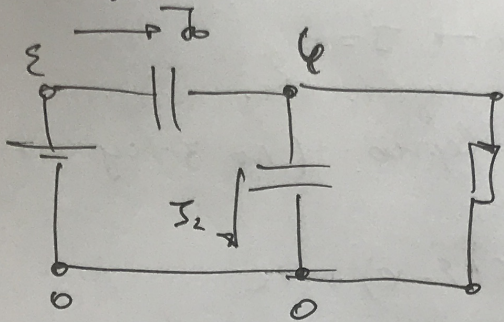
$$= \frac{16}{5}C\varepsilon^2 - \left(\frac{4C}{2} \cdot \varepsilon^2 + 0 - \frac{4C}{2} \cdot \frac{\varepsilon^2}{25} - \frac{16}{25} \frac{C}{2} \varepsilon^2 \right) =$$

$$= C\varepsilon^2 \left(\frac{16}{5} - 2 + \frac{2}{25} + \frac{8}{25} \right) = C\varepsilon^2 \left(\frac{16}{5} - 2 + \frac{10}{25} \right) = C\varepsilon^2 \left(\frac{16}{5} - 2 + \frac{2}{5} \right) = \frac{8}{5}C\varepsilon^2$$

#3 Программирование.

Задачник

У2



$$J_0 = ((\varepsilon - \varphi)4C) = 4C\dot{u}_1 = -4\dot{\varphi}C$$

$$J_2 = \dot{\varphi}C$$

$$J_R = \frac{\varphi}{R}$$

$$J_0 = J_2 + J_R$$

$$-4C\dot{\varphi} = \dot{\varphi}C + J_R$$

$$J_R = -5\dot{\varphi}C = \frac{\varphi}{R}$$

$$\frac{\varphi}{R} + 5\dot{\varphi}C = 0$$

$$\frac{\varphi}{R} = 5C \cdot \frac{J_0}{4C} = 0$$

$$\frac{\varphi}{R} = \frac{5}{4}J_0 \rightarrow \varphi = \frac{5J_0R}{4}$$

$$U_R = \varphi - 0 = \frac{5J_0R}{4}$$

~~$$J_2 = C\dot{u}_2$$~~

~~$$u_1 + u_2 = \varepsilon$$~~

~~$$\dot{u}_1 + \dot{u}_2 = 0$$~~

~~$$u_2 = -u_1$$~~

~~$$J_0 = J_2 + J_R:$$~~

~~$$4C\dot{u}_1$$~~

~~$$J_2 = -\dot{\varphi}C$$~~

~~$$J_0 \neq J_2 + J_R$$~~

~~$$4\dot{\varphi}C = -\dot{\varphi}C + J_R \rightarrow J_R = \frac{\varphi}{R} = -3\dot{\varphi}C = +3 \cdot \frac{J_0}{4}$$~~

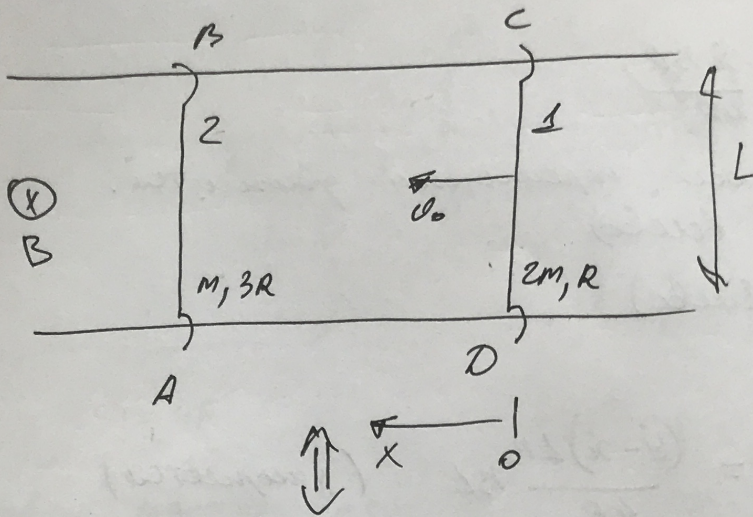
~~$$\varphi = \frac{3R J_0}{4}$$~~

~~$$U_R = \varphi - 0 = \frac{3R J_0}{4}$$~~

#4.

индукция

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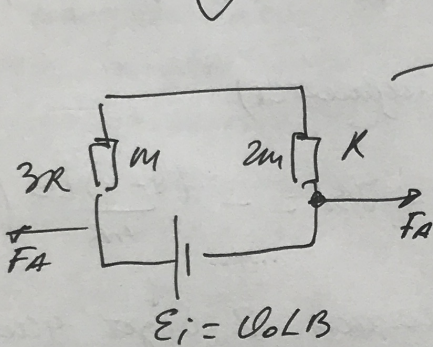


$$\Phi_{ABCD} = AD \cdot L \cdot B$$

$$\dot{\Phi}_{ABCD} = \dot{AD} \cdot L \cdot B$$

$$\dot{\Phi}(0) = -v_0 L B$$

$$\mathcal{E}_i = -\dot{\Phi} = v_0 L B$$



$$I(0) = \frac{v_0 L B}{4R}$$

$$F_{FA} = 2m I(0)$$

$$I(0) B L = 2m a \rightarrow a = \frac{I(0) B L}{2m}$$

$$= \frac{v_0 L B}{4R} \cdot B \cdot L = \frac{v_0 (BL)^2}{8mR}$$

~~В процессе движения |E_i| = 2v_0 L B~~

~~Δ ток в цепи на скорости не действует. Линейные силы (в гориз. плоскости), кроме F_A. В нач. мом. времени ~~не~~ нет разн. в разн. направлениях, равны по модулю.~~

→ сокращается ширина на OX:

$$2v_0 \omega = 2v_0 \omega' + 2m \omega u'$$

$$2(v_0 - v_0 \omega') = u'$$

Аналогично $A_1 = F_A A_1$
 $A_2 =$

$$2v_0 = u' + 2v_0 \omega' \rightarrow u' = \frac{2}{3} v_0 = \omega'$$

Через большой промежуток времени

$$\dot{\Phi} = 0 \Rightarrow \omega' = u'$$

(ω снова становится const)

#4. Прогонимые. $\ddot{x} = \ddot{y}$ (y - коорд. левой перемычки)

Искать перемещения:

$$2m\ddot{x} = -TBL = -BL \frac{\varepsilon_i}{4R} = -BL \frac{x BL}{4R}$$

Пусть в прогн. масс перемычки зафиксируем.
 масса. Слева $= \dot{y}$ (влево)
 справа $= \dot{x}$ (влево)

$$\dot{\varphi} = (\dot{y} - \dot{x}) LB$$

$$m\ddot{\varphi} = TBL = \frac{\varepsilon_i}{4R} BL = \frac{(\dot{y} - \dot{x}) LB}{4R} BL \quad (\text{ускоряется})$$

$$2m\ddot{x} = -TBL = -\frac{(\dot{y} - \dot{x}) LB}{4R} BL \quad (\text{замедляется})$$

$$2m\ddot{x} = -TBL = -\frac{(\dot{y} - \dot{x}) LB}{4R} BL \quad (\text{замедл.})$$

$$\rightarrow \dot{x}\dot{y} + 2x\dot{x} = 0$$

$$a_{лев} + 2a_{пр} = 0$$

$$|a_{лев}| = 2|a_{пр}| = 2a$$

~~и~~ ~~домк~~

~~и~~

Перемычка 2 будет ускоряться,
 1 - тормозиться. В отр. моменты
 их скорости станут равны,
 тогда $\dot{\varphi} = 0 \rightarrow \varepsilon_i = 0 \rightarrow T = 0$
 $\rightarrow FA = 0 \rightarrow a = 0 \rightarrow$ скорости
 перемычек сравняются и
 перестанут меняться.

$$t = \frac{1}{a} = \frac{1}{2a} = \frac{1}{3a} = \frac{1}{3a}$$

через это время перестанет
 меняться

$$2ma = \frac{(\dot{y} - \dot{x}) (LB)^2}{4R}$$

$$S = S_0 - \frac{8mU_0R}{3(LB)^2}$$

$$\int_0^{2/3 U_0} 2ma dt = \left(\frac{d\dot{y}}{dt} dt - \frac{d\dot{x}}{dt} dt \right) \frac{(LB)^2}{4R}$$

$$\Delta y = y - S_0$$

$$\Delta x = x$$

$$\Delta y - \Delta x = y - x - S_0$$

$$2m \left(\frac{2}{3} U_0 - U_0 \right) = (\Delta y - \Delta x) \frac{(LB)^2}{4R}$$

$$S - S_0 = -\frac{8mU_0R}{3(LB)^2}$$

$$-\frac{2mU_0}{3} = (S - S_0) \frac{(LB)^2}{4R}$$

$$S - S_0 = -\frac{8mU_0R}{3(LB)^2}$$

$$S = S_0 - \frac{8mU_0R}{3(LB)^2}$$

#5.

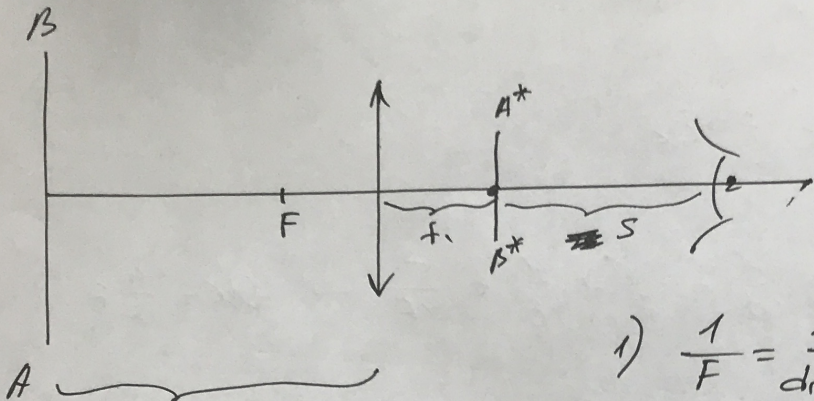
Шестовик (N5)

$AB = H = 9 \text{ м}$

$d_1 = 72 \text{ см}$

$F = 18 \text{ см}$

~~$x = 24 \text{ см}$~~



$d_1 = 4F$

1) $\frac{1}{F} = \frac{1}{d_1} + \frac{1}{f_1}$

$f_1 = \frac{d_1 F}{d_1 - F} = \frac{72 \cdot 18}{72 - 18} = 24 \text{ см}$

$\Gamma = \frac{24 \text{ см}}{72 \text{ см}} = \frac{1}{3}$ - узор АВ в мизе уменьшенный

Шестовик настраиваем так, чтоб видеть четкое изображение, которое будет находиться на расстоянии f_1 от мизы.

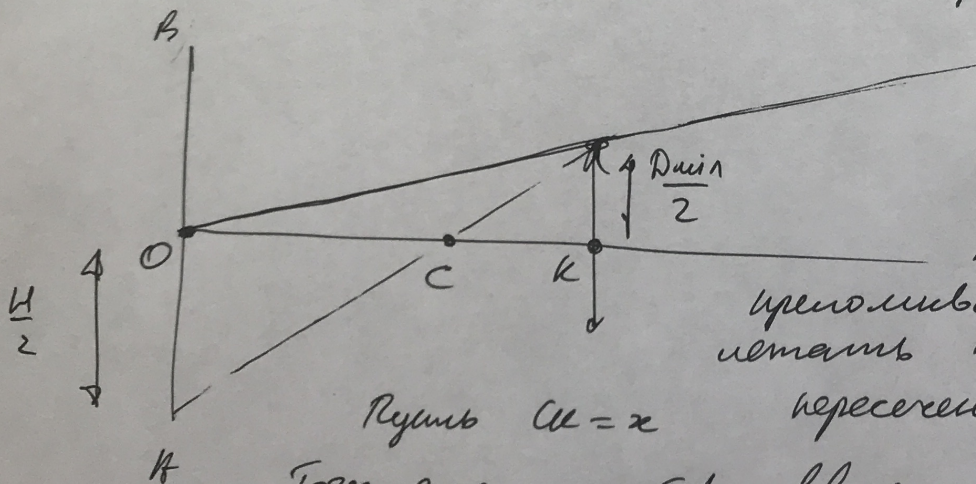
~~тогда~~ $\Rightarrow S = 24 \text{ см}$
 $f_1 = 24 \text{ см}$ } $\rightarrow X = S + f_1 = 48 \text{ см}$

2) ~~Чтобы увидеть все узор - изображение~~

Если будет видно крайние точки картины, то тем более будет видно все.

Рассм. Длин: рассмотрим луч из т. А.

он пройдет в мизе.



Тогда в крайнем случае, чтобы было видно картину, изображение этого прямоугольного луча должно летать не ниже т. O (его пересечение с OOO).

Пусть $OK = x$

Тогда где расклетов введем предмет в т. С.

Для него верно, что: $\frac{1}{F} = \frac{1}{OK} - \frac{1}{OC}$

#5 Прогнозание.

Этатовин (26)

У подобия Δ -нов:

$$\frac{OC}{H/2} = \frac{CK}{\frac{D_{min}}{2}} \Rightarrow \frac{H}{D} = \frac{OC}{CK}$$

$$\frac{1}{F} = \frac{1}{CK} - \frac{1}{4F} \Rightarrow \frac{1}{CK} = \frac{1}{F} + \frac{1}{4F} = \frac{5}{4F} \rightarrow CK = \frac{4}{5} F$$

$$D \Rightarrow \frac{H \cdot CK}{OC} = \frac{H \cdot \frac{4}{5} F}{4F - \frac{4}{5} F} = \frac{4F}{5} \cdot \frac{5}{4F} = \frac{H}{4}$$

$$D = \frac{9}{4} \text{ см} = \underline{2,25 \text{ см}}$$

3) А точка С.

$$CK = \frac{4}{5} F = \frac{4}{5} \cdot 18 = \underline{14,4 \text{ см}}$$

$$2 \mu v_0 = U \cdot 3 \mu$$

$$v = \frac{2 v_0}{3}$$

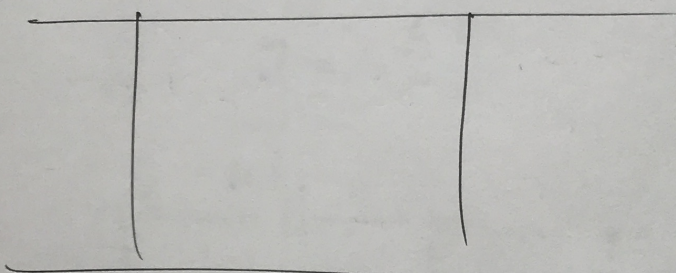
$$\cancel{S - S_0} = \frac{8 \mu v_0 R}{3 (BL)^2}$$

$$S_0 - S =$$

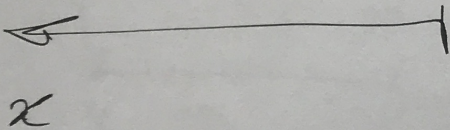
$$2 m a = JBL = \frac{U BL BL}{4R} = \frac{U (BL)^2}{4R}$$

$$a = \frac{U (BL)^2}{8 \mu R}$$

$$F = \frac{(\ddot{y} - \ddot{x}) BL}{4R} BL = 2 m a$$



$$\int_0^{\frac{2 v_0}{3}} a dt \quad 2m = \int (\ddot{y} dt - \ddot{x} dt) \frac{(BL)^2}{4R}$$



$$-\frac{v_0}{3} \cdot 2m = (\Delta y - \Delta x) \frac{(BL)^2}{4R}$$

$$8 \mu \frac{v_0}{3} \cdot 0.5m$$

$$\mu \cdot Ta$$

$$\Delta y = y - S_0$$

$$\Delta x = x$$

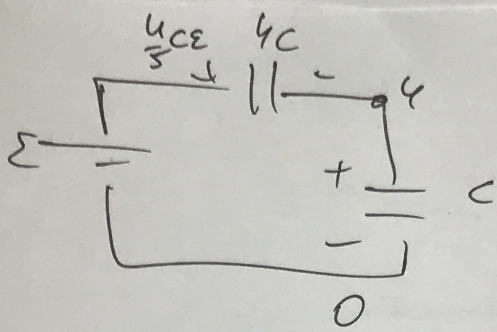
$$U BL = B$$

$$\Delta y - \Delta x = y - S_0 - x = S' - S_0$$

$$\cancel{\Delta x = B}$$

$$-\frac{v_0}{3} 2m = (S' - S_0) \frac{(BL)^2}{4R}$$

$$\cancel{S'} \quad S_0 - S' = \frac{2.4 R m v_0}{3 (BL)^2}$$



$$4\phi - 4\phi(\epsilon - \phi) = 0$$

$$\phi - 4\epsilon + 4\phi = 0$$

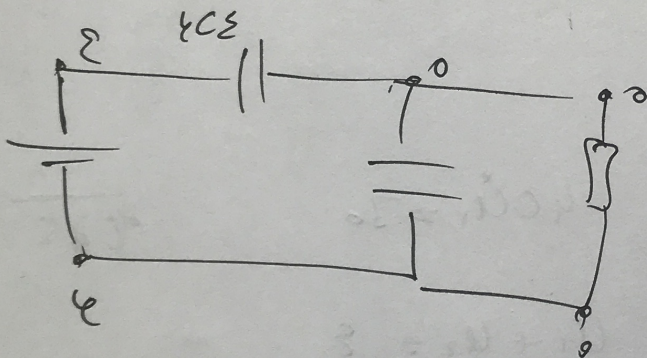
$$\phi = \frac{4}{5}\epsilon$$

$$W_1 = 4C \cdot \frac{\epsilon^2}{25}$$

$$C \cdot \frac{\frac{16}{25}\epsilon^2}{2} = \frac{2}{5}C\epsilon^2$$

$$\rightarrow J = \frac{4}{5} \frac{\epsilon}{R}$$

$$\left(4C\epsilon - \frac{4}{5}C\epsilon\right)\epsilon - \Delta W = 0$$



$$\frac{16}{5}C\epsilon^2 - \left(4C\frac{\epsilon^2}{2} - \frac{2}{5}C\epsilon^2\right) = Q$$

$$C\epsilon^2 \left(\frac{16}{5} - 2 + \frac{2}{5}\right) = Q$$

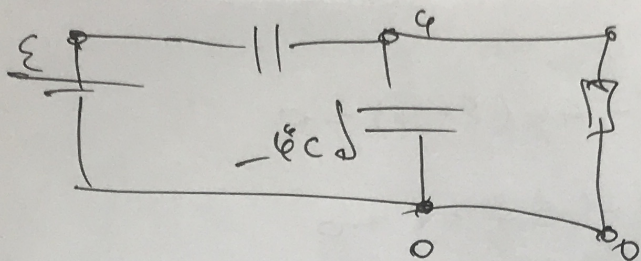
$$C\epsilon^2 \left(\frac{10}{5} - 2\right) = Q$$

$$\frac{16}{5} - \left(2 - \frac{2}{5}\right)$$

$$\frac{8}{5}C\epsilon^2$$

$$\frac{16}{5} - 2 + \frac{2}{5}$$

$$\frac{10}{5} - 2 = \frac{8}{5}$$



$$J_0 = 4(\varepsilon - u_c)C = -4\dot{u}_c C \quad u_c = \frac{-J_0}{4C}$$

$$-4\dot{u}_c C = -\dot{u}_c C + J_R$$



$$(\varepsilon - u_c)4C = J_0$$

$$-u_c 4C = J_0$$

$$4C\dot{u}_1 = J_0$$

$$\frac{4}{3R} = \dots$$

$$J_2 = \dot{u}_c$$

$$= 200 \mu$$

$$u_1 + u_2 = \frac{\varepsilon}{2} \Rightarrow u_1 + u_2 = 0$$

$$u_2 = -u_1$$

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 $u_1 + u_2 = 0$
 $u_2 = -u_1$

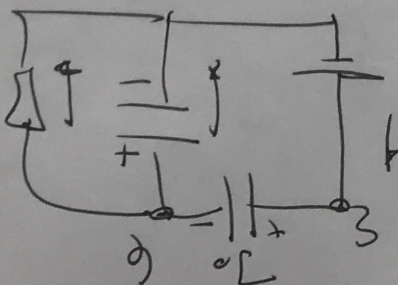
$$J_2 = -\dot{u}_1 C$$

$$4C\dot{u}_1 = J_R - \dot{u}_1 C$$

$$J \frac{u}{R} = 5\dot{u}_1 C = \frac{5}{4} J_0$$

$$\dots$$

$$J_2 = 200 \mu$$



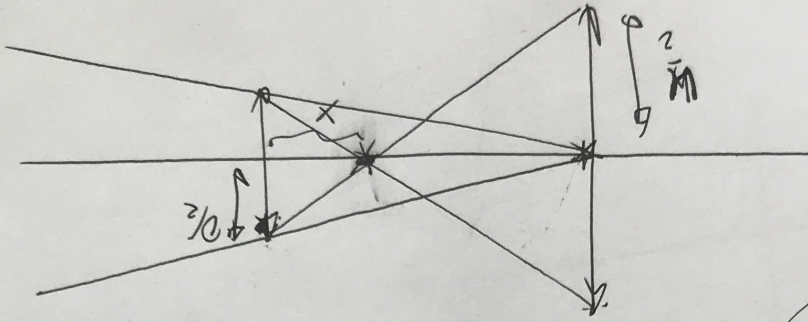
$$10 + 3 - 20 - 3$$

$$J_2 = 200 \mu$$

$$x = \frac{5}{4}$$

$$\frac{1}{x} = \frac{4}{5}$$

$$\frac{1}{2} = \frac{1}{4} = \frac{1}{1}$$

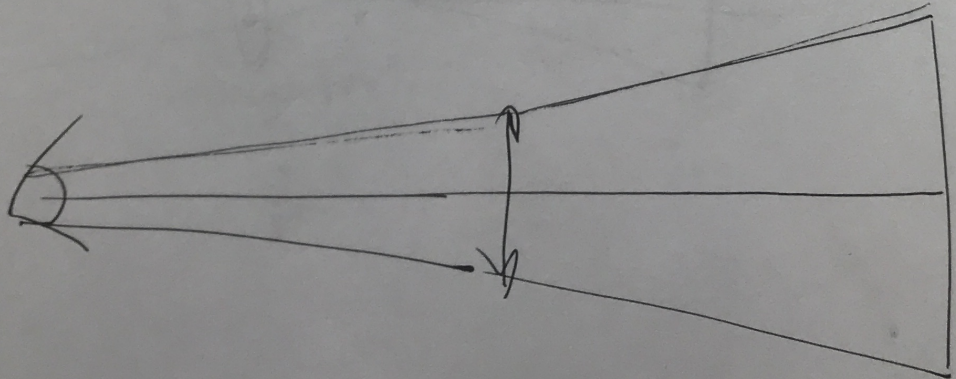
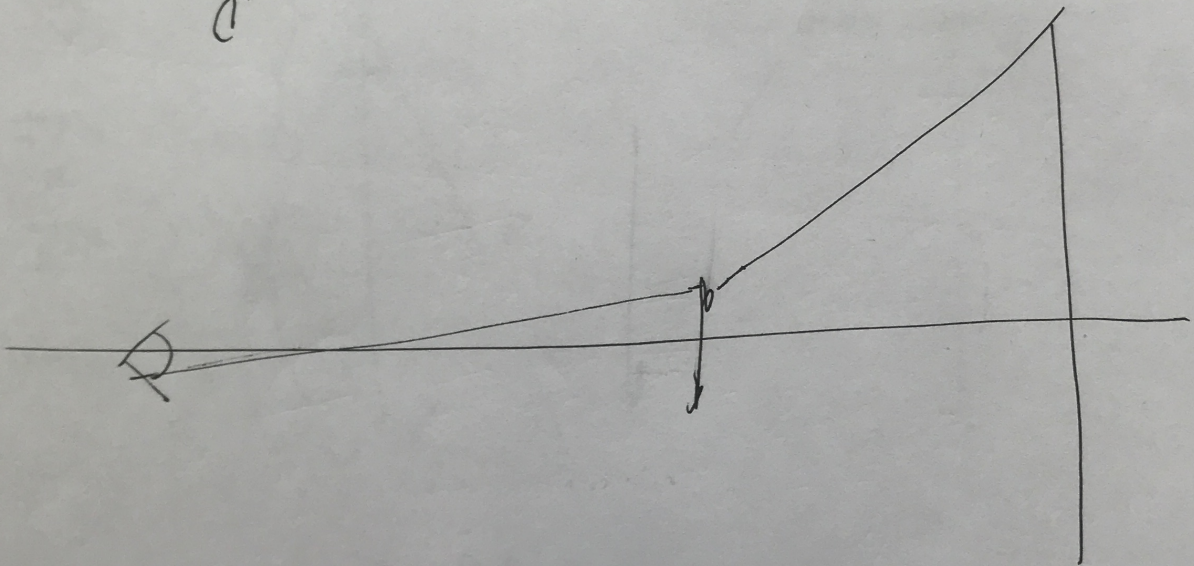
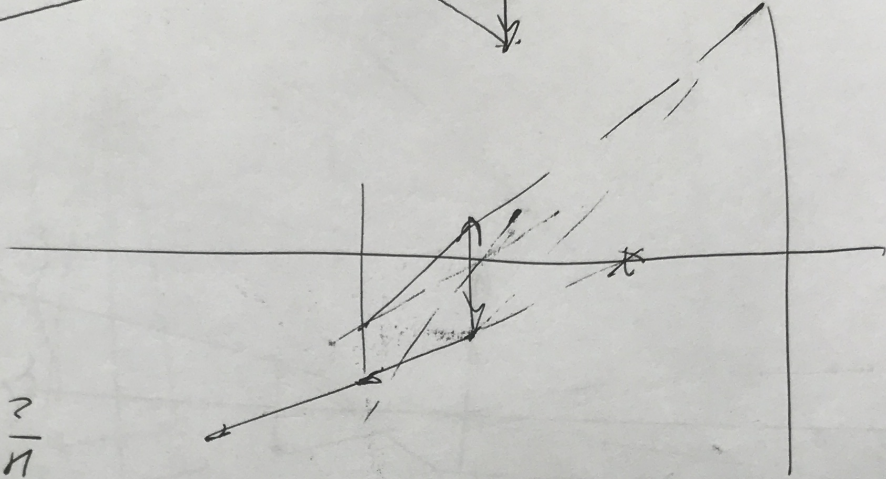


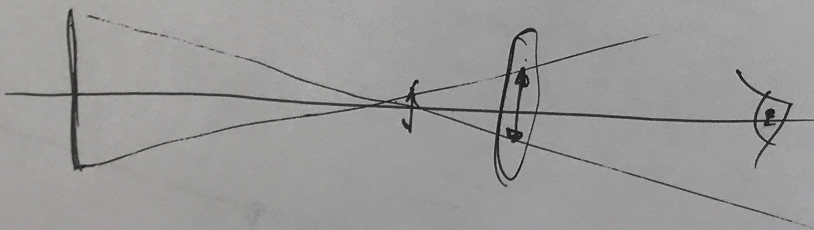
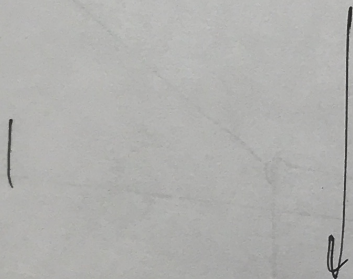
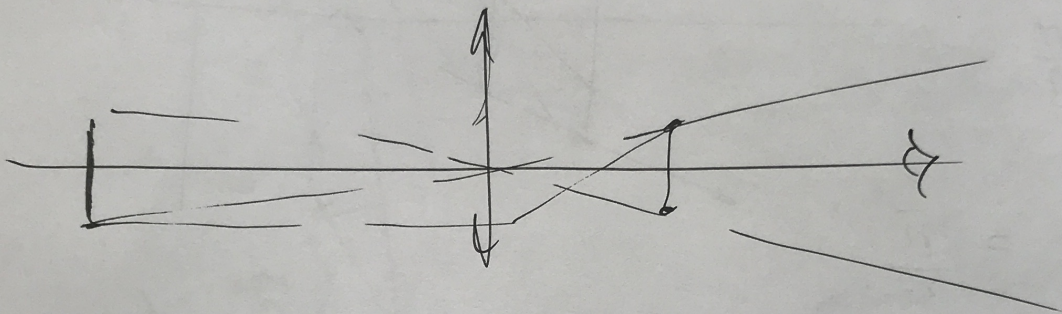
$$\frac{4}{H} = 2$$

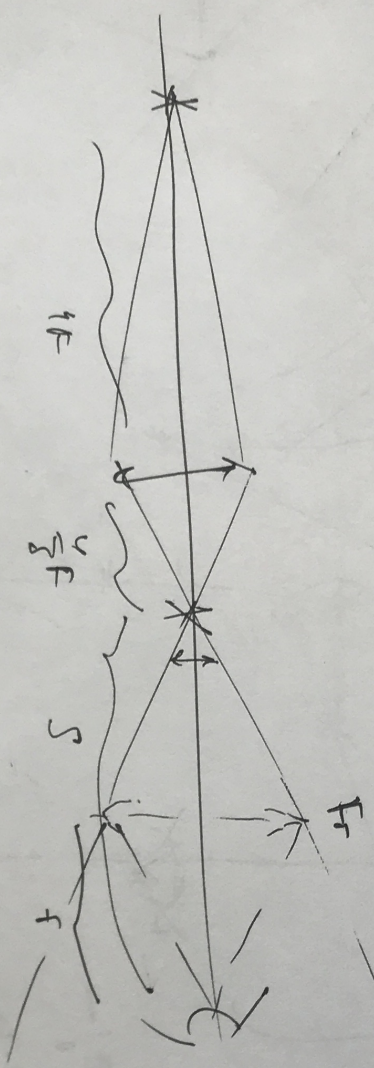
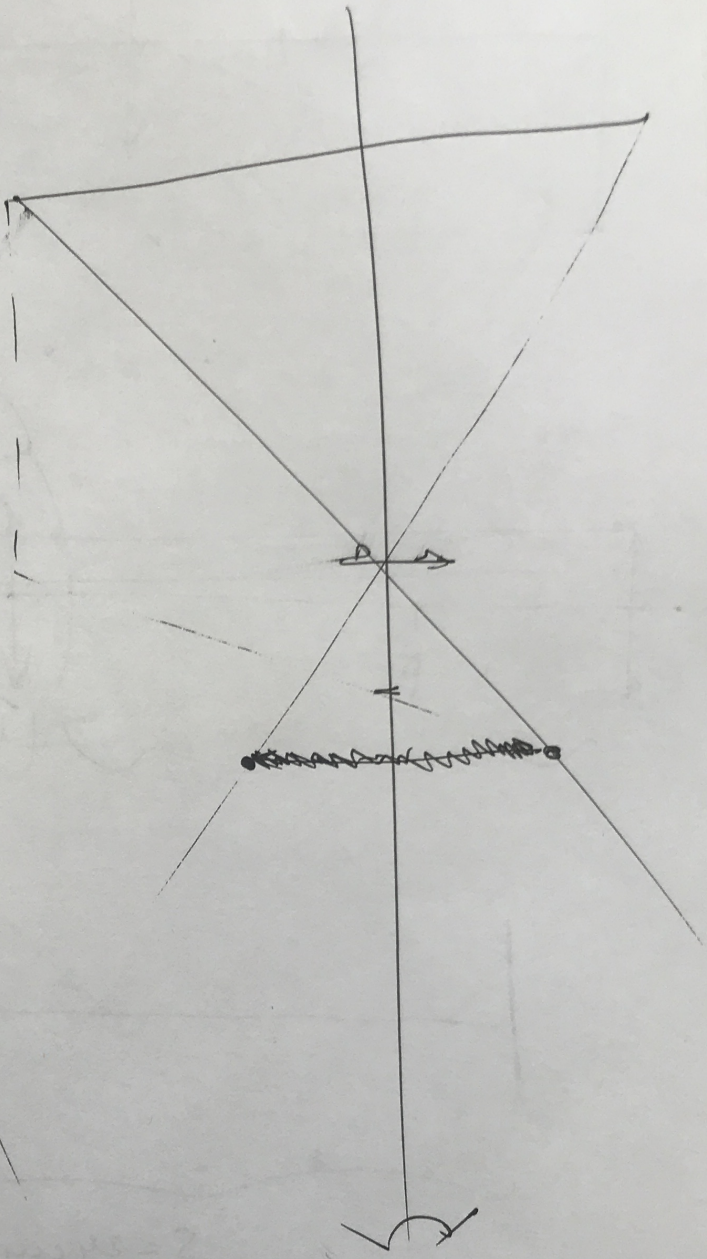
$$\frac{4}{H} = \frac{16}{4} = \frac{H}{1}$$

$$\frac{H}{1} = \frac{4}{4} = \frac{3}{4}$$

$$\frac{H}{2} = \frac{1}{2} = \frac{4}{4}$$



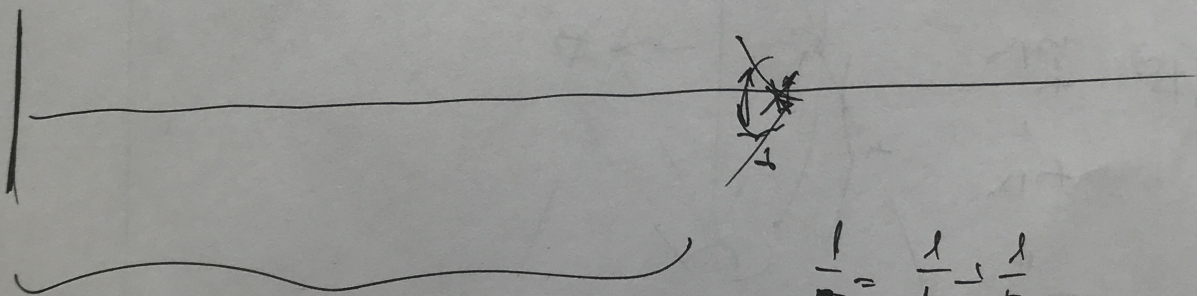
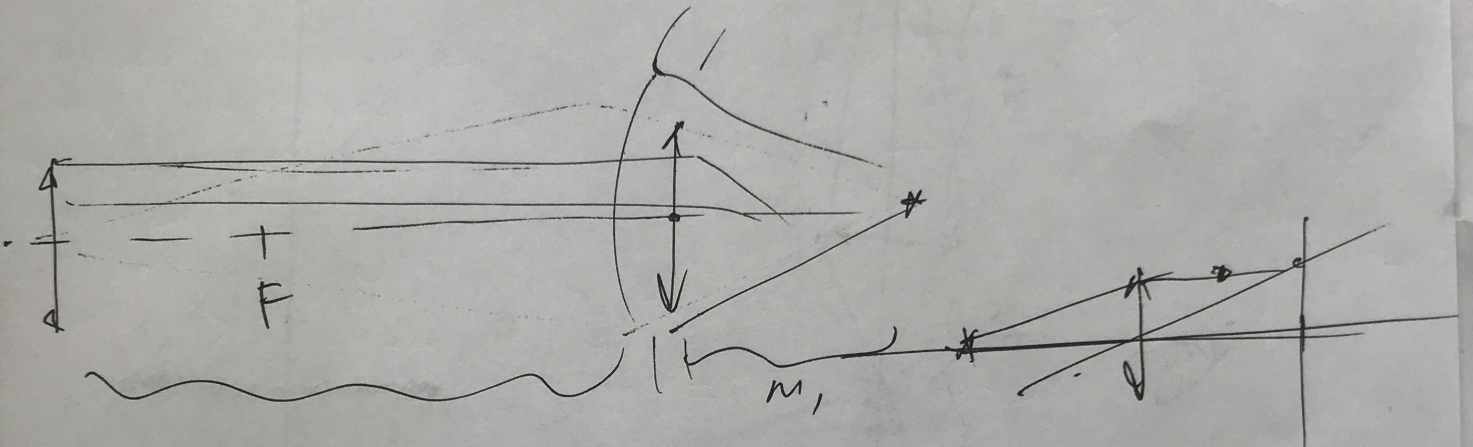
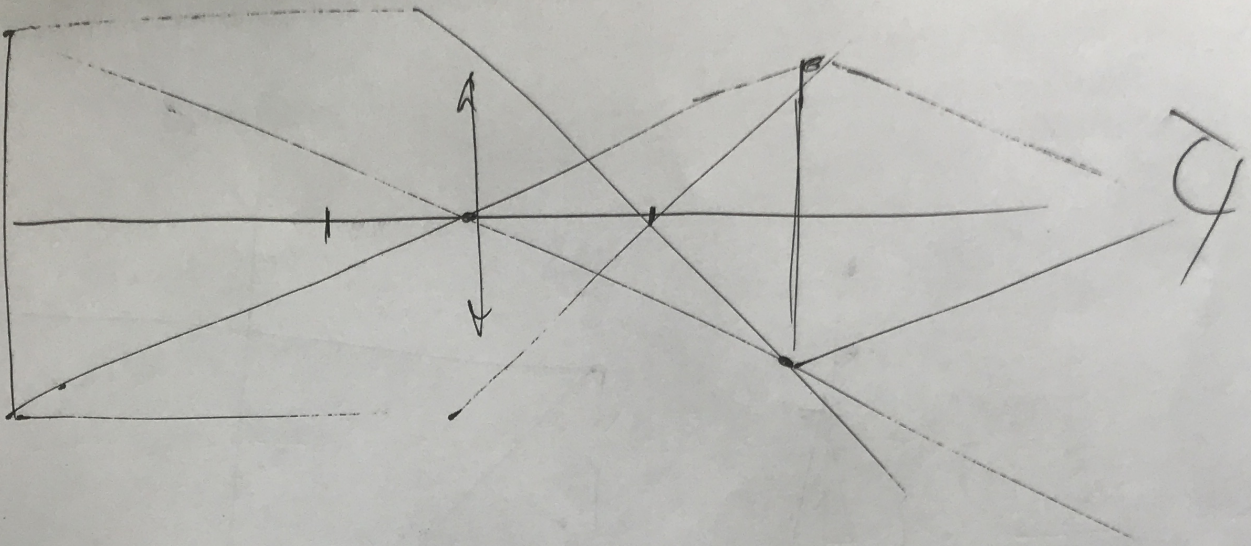




$$\frac{1}{f_e} = \frac{1}{s_e} + \frac{1}{s_i}$$

$$\frac{1}{f_o} = \frac{1}{s} + \frac{1}{s_i}$$

$$\frac{1}{s} = \frac{1}{f_o} - \frac{1}{s_i}$$



$$S = 24 \text{ cm}$$

$$r \rightarrow 0$$

$$\frac{f}{d} \rightarrow 0$$

$$\frac{1}{F} = \frac{1}{d} + \frac{1}{f_m}$$

$$\frac{1}{F} \rightarrow 0$$

$$\frac{1}{S} = \frac{1}{F} + 0$$

$$\frac{1}{S}$$

Умови

$$u' = u'$$

$$2(u_0 - u) = 4$$

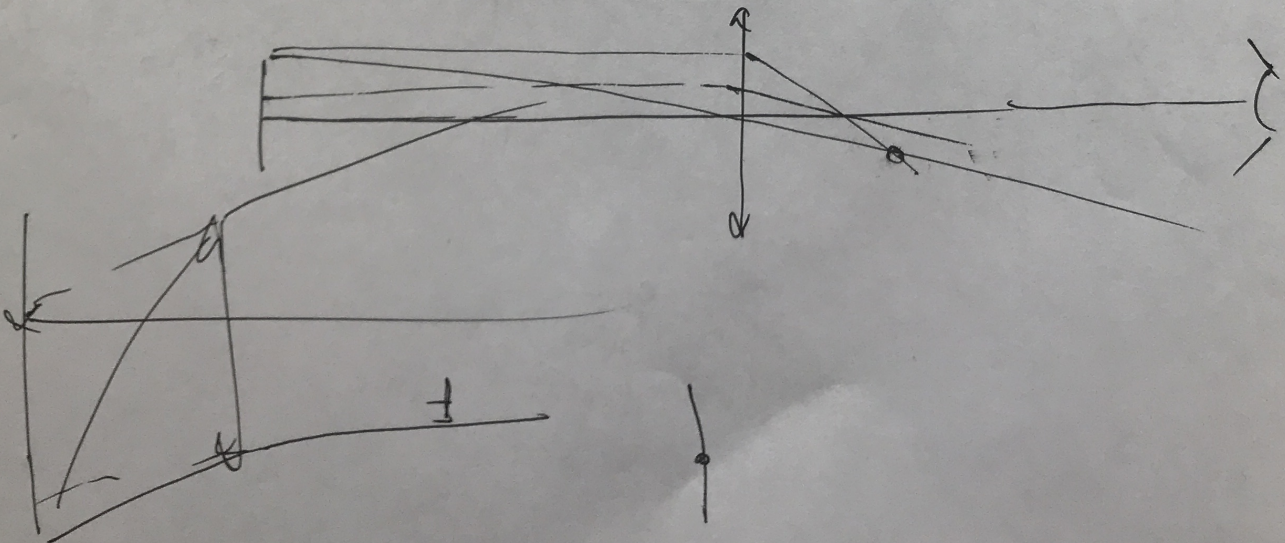
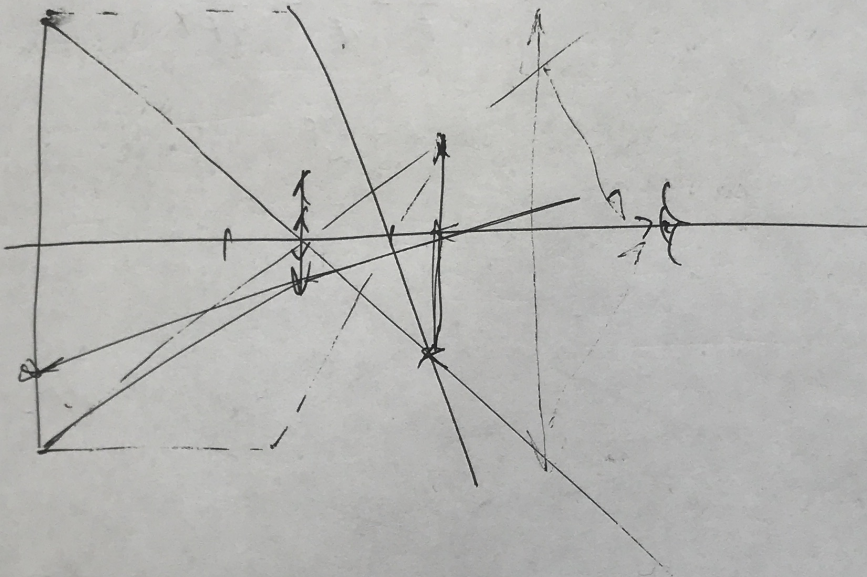
$$2u_0 = 4$$

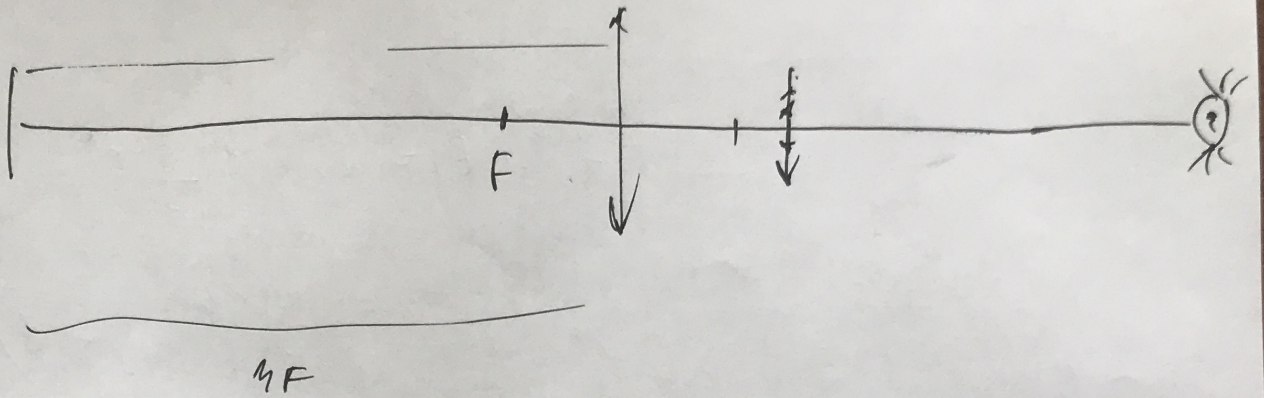
$$u = \frac{2}{3}u_0$$

$$\frac{2Mu_0^2}{2} + E_1 = E_2 + \frac{3m \frac{4}{9} u_0^2}{2}$$

$$E_1 - E_2 = \frac{mu_0^2}{2} \left(\frac{4}{3} - 1 \right)$$

$$E_1 - E_2 = \frac{mu_0^2}{2} \cdot \frac{1}{3}$$

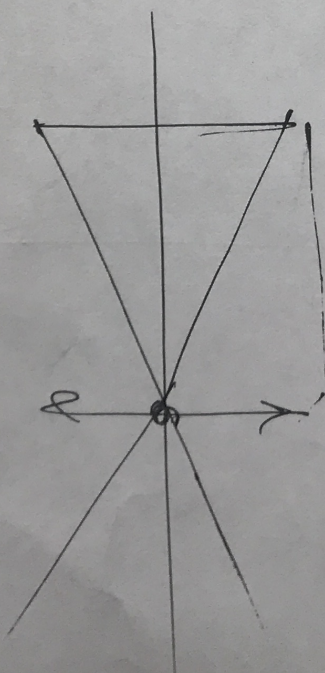
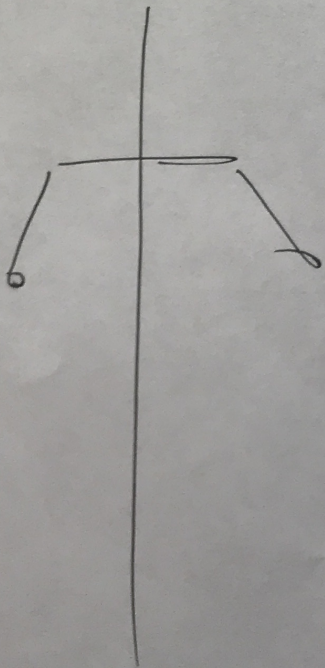
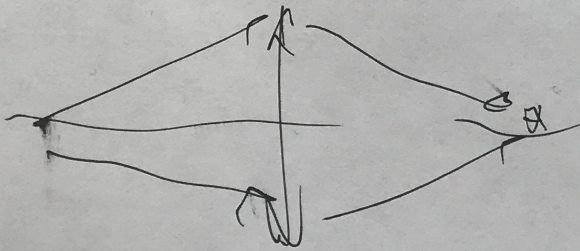




$$\frac{1}{4F} + \frac{1}{f} = \frac{1}{F}$$

$$\frac{1}{f} = \frac{1}{F} - \frac{1}{4F} = \frac{3}{4F}$$

$$f = \frac{4}{3}F = \frac{4}{3} \cdot 28$$



$$\frac{1}{s} + \frac{1}{s-f} = \frac{1}{f}$$

$$\frac{1}{s-f} + \frac{1}{f} = \frac{1}{f}$$