

# Часть 1

Олимпиада: **Физика, 11 класс (1 часть)**

Шифр: **21201091**

ID профиля: **855506**

Вариант 8

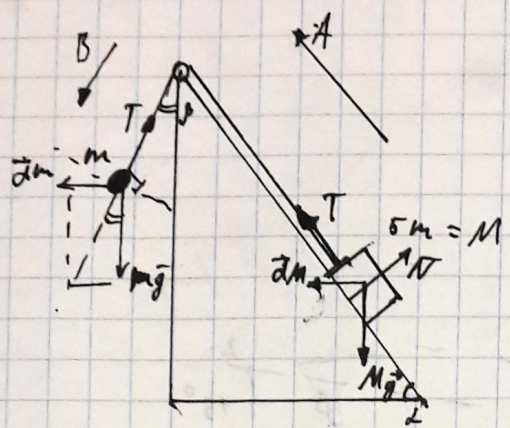
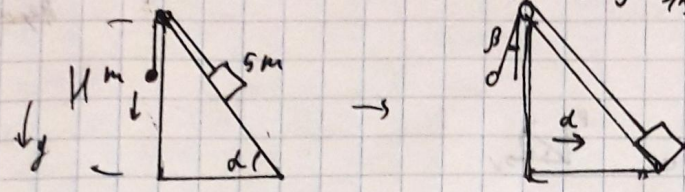
N1

$M, m, 5M, g, \beta$

$\cos \alpha = \frac{5}{13}$      $\sin \alpha = \frac{12}{13}$   
 $\cos \beta = \frac{5}{13}$      $\sin \beta = \frac{12}{13}$

$\frac{25}{765} \cdot \frac{25}{765} = 1$   
 $16\beta - 25 = 2^2$   
 145

$a_{ka} = ?$   
 $a_{km} = ?$   
 $T_m = ?$



$\frac{13}{12}$      $\frac{13}{12}$      $12 \cdot 33 = -27$

$-27 \cdot 12 + 5 \cdot 54$

$\sqrt{12}$	$\frac{54}{5}$
$\frac{12}{64}$	$\frac{35}{25}$
$22$	$285$
$324$	

33     $\frac{13}{92}$

23M:

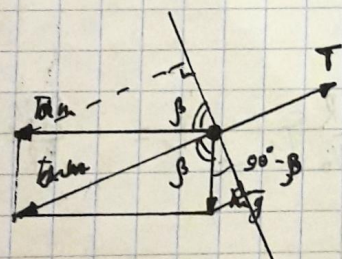
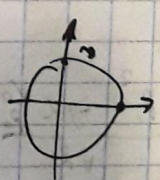
$\vec{F}_m = \vec{a}_m \cdot m + m \cdot \vec{g} = m(\vec{a} + \vec{g})$

$\tan \beta = \frac{12}{5} = \frac{d}{g}$

$d = \frac{12}{5} g$

$d_{km} = \frac{12}{5} g$

$\frac{12}{5} \cdot \left( \frac{12 - 13 \cdot 3}{13} \right) + \frac{5 + 13 \cdot 4}{13} =$   
 $= \frac{-12 \cdot 27}{13 \cdot 5} + \frac{57 \cdot 5}{13 \cdot 5}$



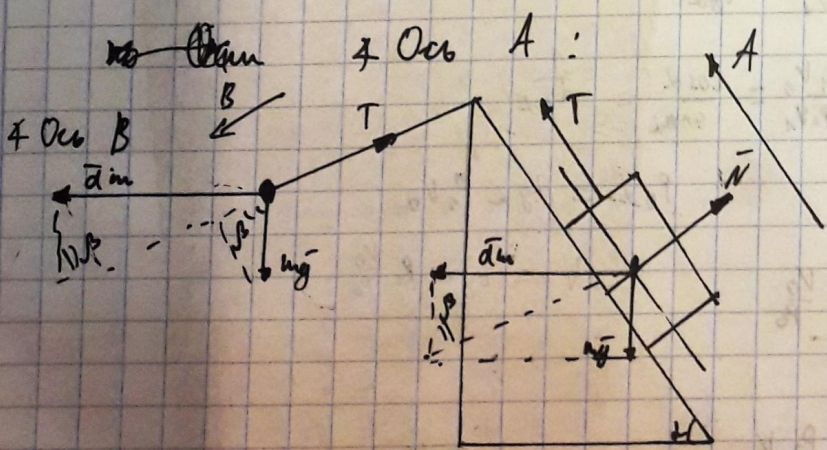
$\cos(90^\circ - \beta) \cdot m \cdot g = \cos \beta \cdot d_m$

$\sin \beta = \frac{12}{13}$      $\frac{5}{13}$

$\frac{12}{25} m g = \frac{5}{13} d_m$      $d = \frac{12}{5} g$

$\sin(\frac{\pi}{2} - x) = \cos(x)$

$\cos(\frac{\pi}{2} - x) = \sin(x)$



$d \delta M = d_{ka} \cdot M \cdot \cos \alpha - M g \cdot \sin \alpha + T$

$d_m m = d_{ka} \cdot m \cdot \sin \beta + m g \cdot \cos \beta - T$

for  $d \delta = d_m$   
 $d_{ka} \cdot M \cdot \cos \alpha - M g \cdot \sin \alpha + T =$   
 $= d_{ka} \cdot m \cdot \sin \beta + m g \cdot \cos \beta - T$

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$2T = d_{ka} (m \cdot \sin \beta - M \cdot \cos \alpha) + g (m \cdot \cos \beta + M \cdot \sin \alpha) =$   
 $= \frac{12}{25} d_{ka} \left( \frac{12}{5} - 5 \cdot \frac{5}{13} \right) + g \left( \frac{5}{13} + 5 \cdot \frac{12}{13} \right) =$

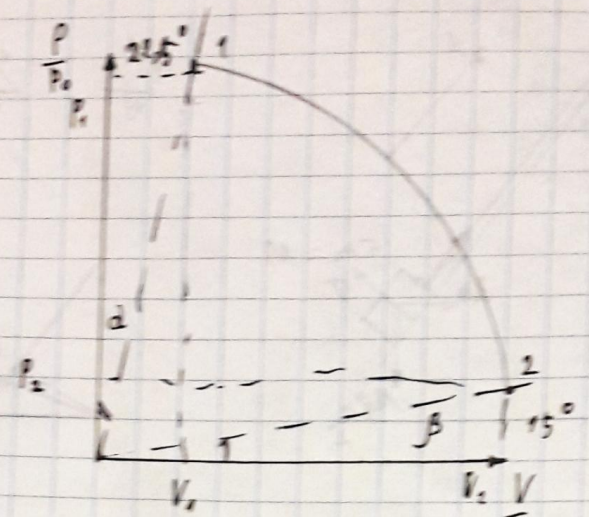


непостоянна, адиаб.

1)  $\frac{T_1 - T_2}{T_2} = ?$

2)  $d = ?$   $C_p = 0$

3)  $\beta = ?$



$PV = \nu RT$   $\left(\frac{P}{P_0}\right)^2 + \left(\frac{V}{V_0}\right)^2 = R^2$

$Q = \Delta U + A_2$

$\frac{P^2}{P_0^2} + \frac{V^2}{V_0^2} = R^2$   $V_0^2 P^2 + P_0^2 V^2 = R^2 V_0^2 P_0^2 = const$

$P_1 V_1 = \nu RT_1$   $\frac{P_1 V_1}{P_0 V_0} = \frac{\nu R}{P_0 V_0} T_1$   $T_1 = \frac{P_1 V_1}{\nu R} = \frac{P_1^2 \text{tg} \alpha \frac{V_0}{P_0}}{\nu R}$

$\left(\frac{P_1}{P_0}\right)^2 + \left(\frac{V_1}{V_0}\right)^2 = R^2$

$\frac{P_1}{P_0} = R \cdot \cos \alpha$   $\frac{V_1}{V_0} = \frac{1}{\text{tg} \alpha}$   $V_1 = \text{tg} \alpha P_1$

$\frac{V_1}{V_0} = R \cdot \sin \alpha$   $\frac{P_1 V_0}{P_1 V_1} = \frac{\cos \alpha}{\sin \alpha} = \frac{1}{\text{tg} \alpha}$

$P_0 V_1 = \text{tg} \alpha P_1 V_0$

$V_1 = \text{tg} \alpha P_1 \frac{V_0}{P_0}$

$T_2 = \frac{P_2 V_2}{\nu R} = \frac{P_2^2 \cdot \text{ctg} \beta \frac{V_0}{P_0}}{\nu R}$

$\frac{P_2}{P_0} = R \cdot \sin \beta$

$\frac{P_2 V_0}{P_0 V_2} = \text{tg} \beta$

$P_2 V_0 = \text{tg} \beta P_0 V_2$

$\frac{P_2}{V_0} = R \cdot \cos \beta$

$V_2 = \frac{P_2}{P_0} \frac{V_0}{\text{tg} \beta}$

$\frac{T_1 - T_2}{T_2} = \frac{\frac{P_1^2 \text{tg} \alpha \frac{V_0}{P_0}}{\nu R} - \frac{P_2^2 \text{ctg} \beta \frac{V_0}{P_0}}{\nu R}}{\frac{P_2^2 \text{ctg} \beta \frac{V_0}{P_0}}{\nu R}} = \frac{\text{tg} \alpha P_1^2}{\text{ctg} \beta P_2^2} - 1 = \text{tg} \alpha \cdot \text{tg} \beta \frac{P_1^2}{P_2^2} - 1$

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$$d_{\text{rel}} = d_{\text{rel}} \sin \beta + mg \cos \beta - \frac{T}{m}$$

$$d\vec{s} = d\vec{u}$$

$$\begin{aligned} \frac{T}{M} + \frac{T}{m} &= d_{\text{rel}} (\sin \beta - \cos \alpha) + g (\cos \beta + \sin \alpha) = \\ &= \frac{12}{5} g \left( \frac{12}{13} - \frac{3}{5} \right) + g \left( \frac{5}{13} + \frac{4}{5} \right) = \\ &= g \left( \frac{12}{5} \cdot \frac{12 \cdot 5 - 3 \cdot 13}{13 \cdot 5} + \frac{5 \cdot 5 + 4 \cdot 13}{13 \cdot 5} \right) = g \frac{2,9(12 \cdot 5 - 3 \cdot 13) + 25 + 4 \cdot 13}{13 \cdot 5} \\ & \quad 21 \quad 50,4 + \quad g \frac{127,5}{13,5} \quad g 1,96 \end{aligned}$$

$$T \left( \frac{1}{M} + \frac{1}{m} \right) = g 1,96$$

$$T \frac{m+M}{mM} = g 1,96$$

$$\begin{aligned} T &= \frac{g mM}{m+M} 1,96 = g \frac{5 \cdot 2}{5+2} 1,96 = \\ &= mg \frac{9,8}{6} = mg \frac{4,9}{3} \end{aligned}$$

$$T = mg \frac{4,9}{3}$$

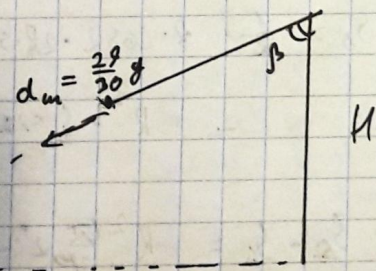
$$\begin{aligned} \boxed{d\vec{s}} &= d_{\text{rel}} \cdot \cos \alpha - g \cdot \sin \alpha + \frac{T}{m} = g \left( \frac{12}{5} \cdot \frac{3}{5} - \frac{4}{5} + \frac{4,9}{15} \right) = \\ &= g \frac{29}{30} \end{aligned}$$

$$\frac{12 \cdot 3 - 4 \cdot 5 + \frac{4,9}{3} \cdot 5}{25}$$

$$\frac{3 \cdot 16 + 4,9 \cdot 5}{25 \cdot 3}$$

$$\frac{72,5}{25,5}$$

$$\frac{72,5}{25,5} = \frac{145}{51} = \frac{29}{30}$$



$$S_{\text{rel}} \cdot \cos \beta = H \quad S_{\text{rel}} = \frac{H}{\cos \beta}$$

$$S_{\text{rel}} = \frac{d_{\text{rel}} t^2}{2} \quad t = \sqrt{\frac{2 S_{\text{rel}}}{d_{\text{rel}}}} = \sqrt{\frac{2H}{d_{\text{rel}} \cos \beta}}$$

$$t = \sqrt{\frac{2H}{\frac{29}{30} g \cdot \frac{5}{13}}} \approx 2,32 \sqrt{\frac{H}{g}}$$

$$t = \sqrt{\frac{H}{g} \cdot \frac{156}{29}}$$

$$2H \frac{H}{g} \cdot \frac{2}{29 \cdot 5} = \frac{H}{g} \cdot \frac{2 \cdot 30 \cdot 13}{29 \cdot 5} = \frac{H}{g} \frac{156}{29}$$



Reprobleme

$$d_s = d_{K1} \cdot \cos \alpha - g \sin \alpha + \frac{T}{M} \quad d_s = d_w$$

$$d_{w1} = d_{K1} \cdot \sin \beta + mg \cos \beta - \frac{T}{m}$$

$$\begin{aligned} \frac{T}{M} + \frac{T}{m} &= d_{K1} (\sin \beta - \cos \alpha) + g (\cos \beta + \sin \alpha) = \\ &= \frac{12}{5} g \left( \frac{12}{13} - \frac{3}{5} \right) + g \left( \frac{5}{13} + \frac{4}{5} \right) = \\ &= g \left( \frac{12}{5} \cdot \frac{12 \cdot 5 - 3 \cdot 13}{13 \cdot 5} + \frac{5 \cdot 5 + 4 \cdot 13}{13 \cdot 5} \right) = g \frac{2,5(12 \cdot 5 - 3 \cdot 13) + 25 + 4 \cdot 13}{13 \cdot 5} \\ & \quad 21 \quad 50,4 + \quad g \frac{122,5}{13 \cdot 5} \quad g 1,96 \end{aligned}$$

$$T \left( \frac{1}{M} + \frac{1}{m} \right) = g 1,96$$

$$T \frac{m+M}{mM} = g 1,96$$

$$\begin{aligned} T &= \frac{g m M}{m+M} 1,96 = g \frac{5 \cdot 12}{17} 1,96 = \\ &= mg \frac{9,8}{6} = mg \frac{4,9}{3} \end{aligned}$$

$$T = mg \frac{4,9}{3}$$

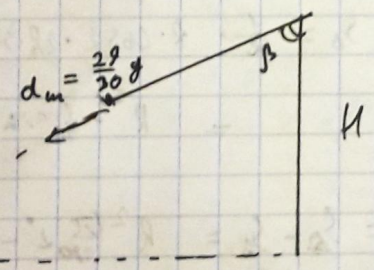
$$\begin{aligned} \boxed{d_s} &= d_{K1} \cdot \cos \alpha - g \cdot \sin \alpha + \frac{T}{M} = g \left( \frac{12 \cdot 3}{5 \cdot 5} - \frac{4}{5} + \frac{4,9}{15} \right) = \\ &= g \frac{29}{30} \end{aligned}$$

$$\frac{12 \cdot 3 - 4 \cdot 5 + \frac{4,9}{3} \cdot 5}{25}$$

$$\frac{3 \cdot 16 + 4,9 \cdot 5}{25 \cdot 3}$$

$$\frac{72,5}{25 \cdot 3}$$

$$\frac{72,5}{250} = \frac{145}{500} = \frac{29}{100}$$



$$S_m \cdot \cos \beta = H \quad S_m = \frac{H}{\cos \beta}$$

$$S_m = \frac{d_w t^2}{2}$$

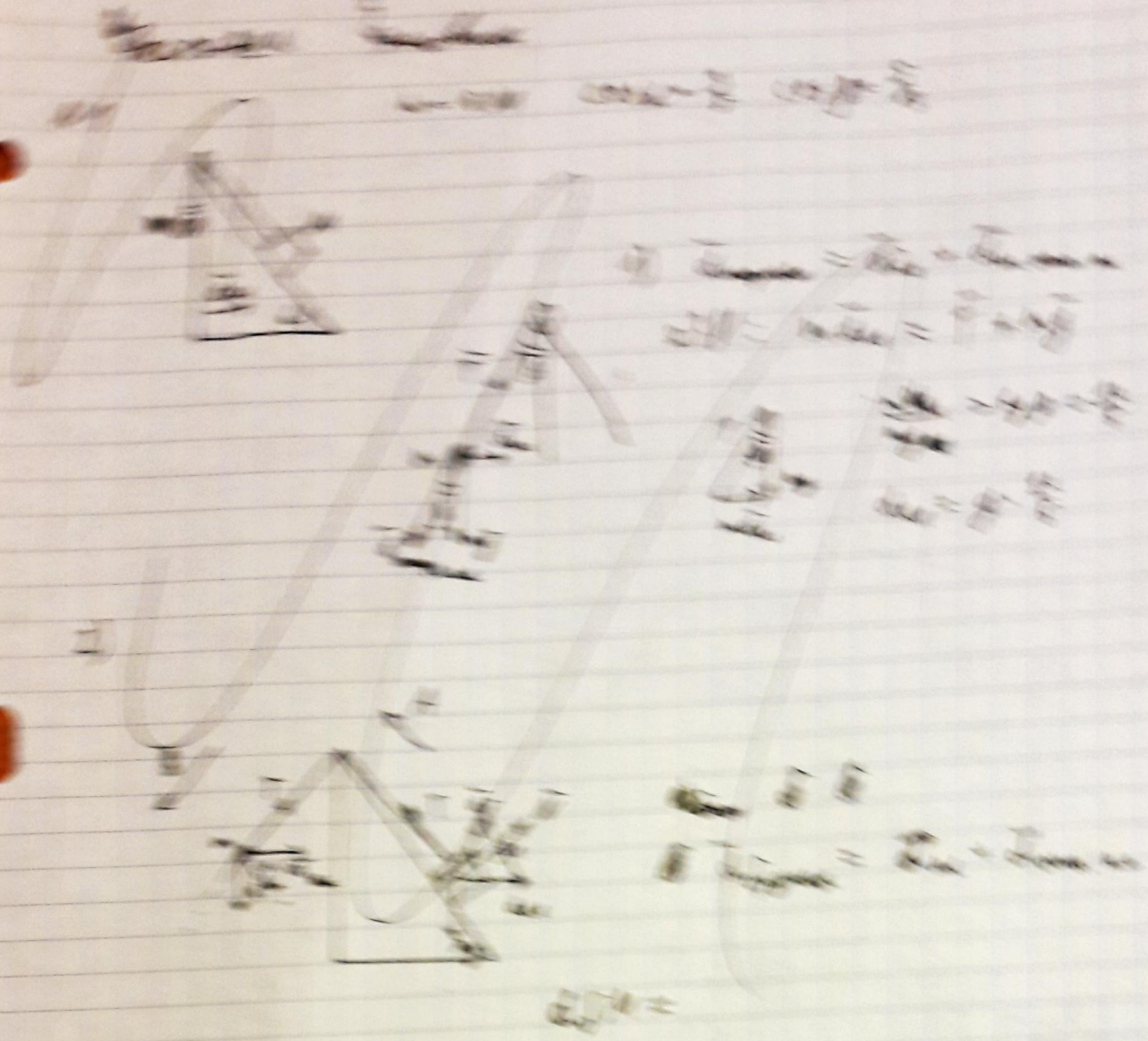
$$t = \sqrt{\frac{2 S_m}{d_w}} = \sqrt{\frac{2H}{d_w \cdot \cos \beta}}$$

$$t = \sqrt{\frac{2H}{\frac{29}{30} g \cdot \frac{5}{13}}} \approx 2,32 \sqrt{\frac{H}{g}}$$

$$t = \sqrt{\frac{H}{g} \cdot \frac{156}{29}}$$

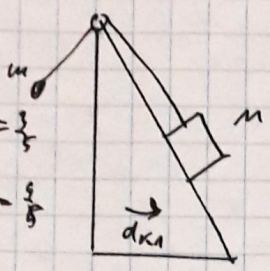
$$2H \frac{H}{g} \cdot \frac{2}{29 \cdot 5} = \frac{H}{g} \cdot \frac{2 \cdot 30 \cdot 13}{29 \cdot 5} = \frac{H}{g} \frac{156}{29}$$



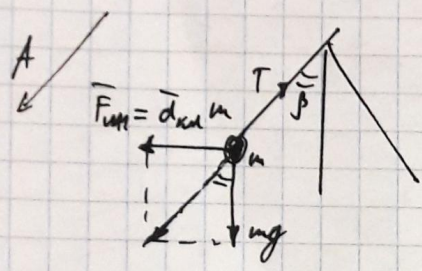




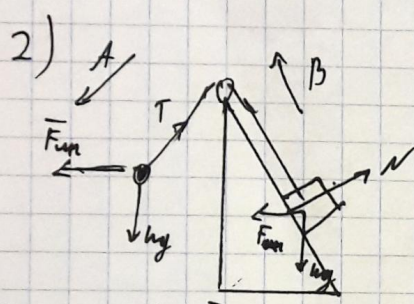
$\cos \beta = \frac{4}{5}$      $\cos \alpha = \frac{3}{5}$   
 $\sin \beta = \frac{3}{5}$      $\sin \alpha = \frac{4}{5}$



непругим б.с.о. кинем.,  
 на динам. и кинет.  
 систем гнущобавне и  
 инерцијум



1)  $\frac{F_{in}}{mg} = \frac{m d_{kl}}{mg} = \tan \beta = \frac{12}{5}$   
 $d_{kl} = \frac{12}{5} g$



2) 3M. no Ocu B:

$d_{dinam} \cdot M = d_{kl} \cdot M \cdot \cos \alpha - Mg \sin \alpha + T$

3M no Ocu A:

$d_{dinam} m = d_{kl} m \cdot \sin \beta + mg \cdot \cos \beta - T$

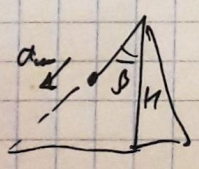
$F_{in} \text{ gub } m \text{ gub } a = m \cdot d_{kl}$   
 $F_{in} \text{ gub } M \text{ gub } a = M \cdot d_{kl}$

$d_{dinam} = d_{dinam}$   
 $T \left( \frac{1}{M} + \frac{1}{m} \right) = d_{kl} (g \sin \beta - \cos \alpha) + g (\cos \beta + \sin \alpha) =$   
 $= g \cdot 1,96$

$T = mg \cdot \frac{4,9}{3}$

$d_{dinam} = d_{kl} \cdot \cos \alpha - g \cdot \sin \alpha + \frac{T}{M} = \frac{2,9}{30} g$

3)



$d_{dinam} = d_{dinam} = \frac{2,9}{30} g$

$s_{dinam} = \frac{H}{\cos \beta} = d_{kl} \frac{t^2}{2}$

$t = \sqrt{\frac{2H}{d_{kl} \cos \beta}} = \sqrt{\frac{H}{g} \cdot \frac{156}{2,9}}$

Одговор: 1)  $d_{kl} = \frac{12}{5} g$

2)  $d_{dinam} \text{ ovcu } m \text{ kina} = \frac{2,9}{30} g$

3)  $t = \sqrt{\frac{H}{g} \cdot \frac{156}{2,9}}$



# Часть 2

Олимпиада: **Физика, 11 класс (2 часть)**

Шифр: **21201091**

ID профиля: **855506**

Вариант 8

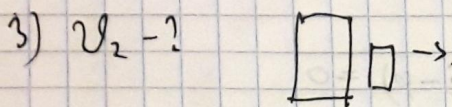
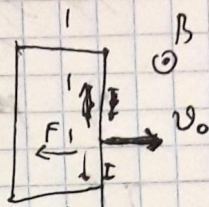
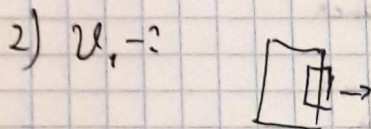
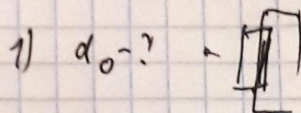
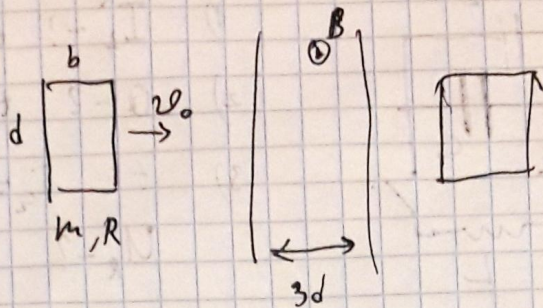


Задача №2

$d, b = \frac{2}{3}d, v_0, m, R,$

$B, H = 3d$

$$b = \frac{2}{3}d$$

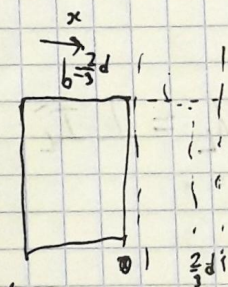
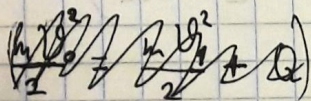


1)  $\mathcal{E} = v_0 B d \quad I = \frac{\mathcal{E}}{R} = \frac{v_0 B d}{R}$

$$F = I d \cdot B = \frac{v_0 B^2 d^2}{R} = m a_0$$

$$d_0 = \frac{v_0 B^2 d^2}{m R} \quad \checkmark$$

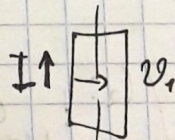
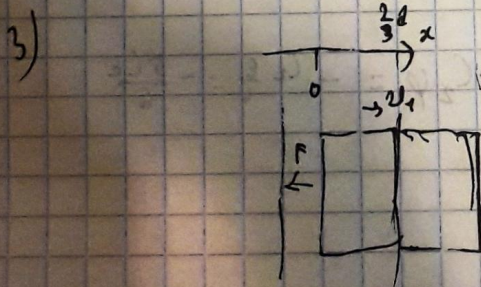
2)  $d(v) = -v \frac{B^2 d^2}{m R}$



$$\Delta \mathcal{V} = \int_{t_0}^{t_1} d dt = -\frac{B^2 d^2}{m R} \int_{t_0}^{t_1} v dt = -\frac{B^2 d^2}{m R} \int_{x_0}^{x_1} dx = -\frac{B^2 d^2}{m R} \left( \frac{2}{3}d - 0 \right) =$$

$$= -\frac{2}{3} \frac{B^2 d^3}{m R}$$

$$v_1 = v_0 - \frac{2}{3} \frac{B^2 d^3}{m R}$$



$$d = -v \frac{B^2 d^2}{m R}$$

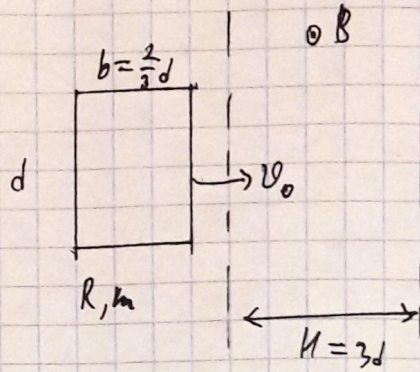
$$\Delta \mathcal{V} = \sum d dt = -\frac{B^2 d^2}{m R} \sum \frac{dx}{dt} dt = -\frac{B^2 d^2}{m R} \cdot \frac{2}{3}d$$

21201091 U85506 N3126767  $v_0 - \frac{4}{3} \frac{B^2 d^3}{m R}$



# УСТОЙКА (3)

№ 4

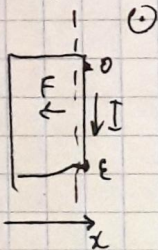


1)  $d_0$  - ?

2)  $v_1$  - ?

3)  $v_2$  - ?

1) равномерное движение проводника в поле



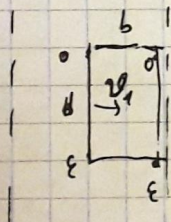
$$\mathcal{E} = v_0 B d \quad I = \frac{\mathcal{E}}{R} = \frac{v_0 B d}{R}$$

$$F = -I \cdot d \cdot B = -\frac{v_0 B^2 d^2}{R}$$

23H:  $F = m a$

$$a_0 = -\frac{v_0 B^2 d^2}{m R}$$

2) равномерное движение ~~опт~~ через ~~буксир~~ проводника



$I = 0 \quad F = 0 \Rightarrow v = \text{const}$ , когда ~~вектор~~ ~~параллельно~~ ~~в~~ ~~поле~~

$$\Rightarrow v_1 = v_0 + \Delta v$$

$$\Delta v = \sum a \cdot dt = \sum -v \frac{B^2 d^2}{m R} dt = -\frac{B^2 d^2}{m R} \sum \frac{\Delta x}{\Delta t} \Delta t =$$

$$= -\frac{B^2 d^2}{m R} \cdot \frac{2}{3} d = -\frac{2}{3} \frac{B^2 d^3}{m R}$$

$$v_1 = v_0 - \frac{2 B^2 d^3}{3 m R}$$

3) равномерное движение ~~параллельно~~ ~~в~~ ~~поле~~

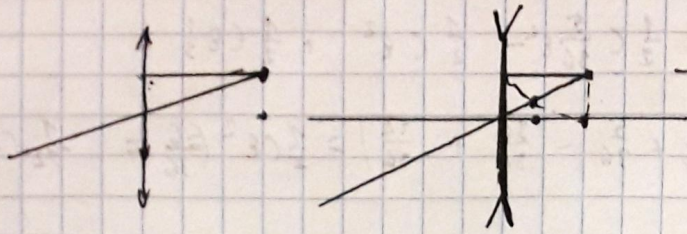
$$v_2 = v_1 + \Delta v = v_1 - \frac{2 B^2 d^3}{3 m R} = v_0 - \frac{4 B^2 d^3}{3 m R}$$



Черобук v3

$$f = x - ?$$

$$F_2 - ?$$



$$-\frac{1}{f} = \frac{1}{d} - \frac{1}{f}$$

$$\frac{1}{f} = \frac{1}{d} + \frac{1}{F} = \frac{F+d}{dF}$$

$$f = \frac{dF}{F+d_1}$$

$$r_1 = \frac{f}{d} = \frac{F}{F+d_1}$$

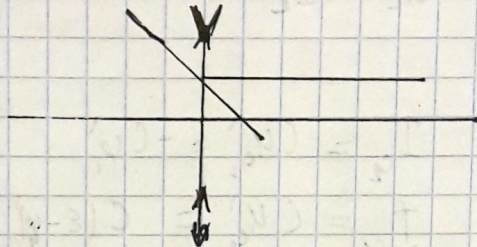
$$d_1 = 25 \text{ CM} = 0,25 \text{ M}$$

$$f = x$$

$$\frac{d_2}{d_1} = 5$$

$$\frac{1}{F_2} = \frac{5}{F_1}$$

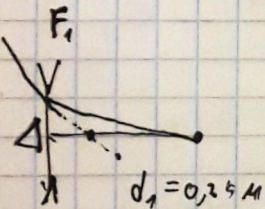
$$F_1 = 5F_2$$



$$-\frac{1}{f} = \frac{1}{d_2} - \frac{1}{f} \quad \text{and}$$

$$r_2$$

$$r_2 = \frac{f}{d_2} = \frac{F}{F+d_2}$$



$$\frac{F_2}{F_2+d_2} = \frac{x}{d_2}$$

$$\frac{5F_2}{5F_2+d_1} = \frac{x}{d_1}$$

$$F_1 = x \quad F_2 = x$$

$$\frac{x}{x+d_2} = \frac{x}{d_2}$$

$$x d_2 = x^2 + x d_2$$

$$x^2 = 0$$

$$\frac{-x}{-x+d_2} = \frac{x}{d_2}$$

$$\frac{5d_1 F_2}{5F_2+d_1} = \frac{d_2 F_2}{F_2+d_2}$$

$$-x d_2 = -x^2 + x d_2$$

$$5d_1 (F_2 + d_2) = d_2 (5F_2 + d_1)$$

$$x^2 + 2x d_2 = 0$$

$$5d_1 F_2 + 5d_1 d_2 = 5d_2 F_2 + d_1 d_2$$

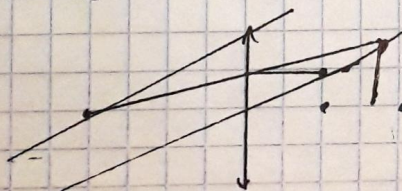
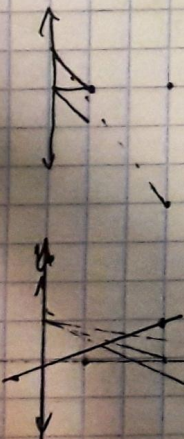
$$x(x + 2d_2) = 0$$

$$F_2(5d_1 - 5d_2) = -4d_1 d_2$$

$$2d_2 = -x$$

$$F_2 = \frac{4d_1 d_2}{5(d_2 - d_1)}$$

$$d_2 = +\frac{x}{2}$$

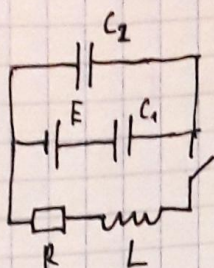




4 ИСТОКИ

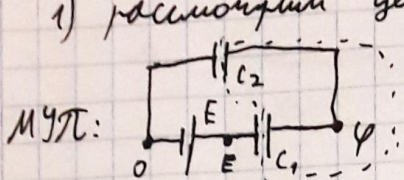
(1)

N3



- 1)  $I_L$  -? сразу после замыкания
- 2)  $Q$  -?
- 3)  $U_R$  -?, когда  $I_{C_2} = I_0$

1) рассмотрим сеть до замыкания



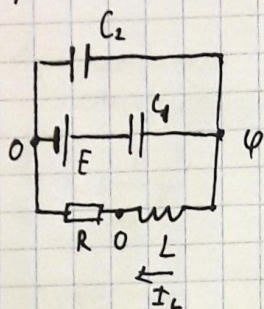
- узлы в обход,  $\sum q = const = 0$

$$0 = +C_2(\varphi - 0) - C_1(E - \varphi)$$

$$0 = 5C\varphi - CE + C\varphi$$

$$6C\varphi = CE \quad \varphi = \frac{1}{6}E$$

2) рассмотрим сеть сразу после замыкания



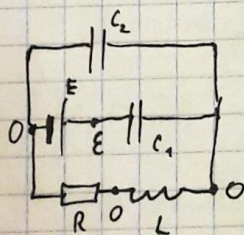
$U_C$  - скачком не меняется  $\Rightarrow \varphi = \frac{1}{6}E$

$I_L$  - скачком не меняется  $\Rightarrow I_L = 0$

$$I_L = I_R = 0 \Rightarrow U_R = 0 \Rightarrow U_L = \varphi = \frac{1}{6}E$$

$$U_L = LI_L' \quad I_L' = \frac{U_L}{L} = \frac{E}{6L}$$

3) рассмотрим сеть в уст. режиме.

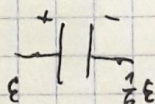


$$U_L = 0, \quad I_C = 0$$

$$U_{C_2} = 0, \quad U_{C_1} = E$$

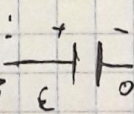
4 конденсатор  $C_1$ :

Итого:



$$q = C_1 U_{C_1} = C_1 (E - \frac{1}{6}E) = \frac{5}{6}CE$$

а также:



$$q = C_2 U_{C_2} = C_2 \cdot E = CE$$

$$\Delta q = CE - \frac{5}{6}CE = \frac{1}{6}CE$$

$$W_{C_1} = W_{C_2} + Q - A_{\text{ист}}, \quad A_{\text{ист}} = \Delta q \cdot E$$

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$$C_1 \left(\frac{5}{6}E\right)^2 + \frac{C_2 \left(\frac{1}{6}E\right)^2}{2} = \frac{C_1 E^2}{2} + 0 + Q - \frac{CE^2}{6}$$

$$Q = \frac{1}{2}CE^2 \left(\frac{25}{36} + \frac{1}{36} - \frac{36}{36} + \frac{12}{36}\right) = \frac{1}{12}CE^2$$



$$W_{C1} + W_{C2} = W_{C1}' + W_{C2}' + Q - A_J$$

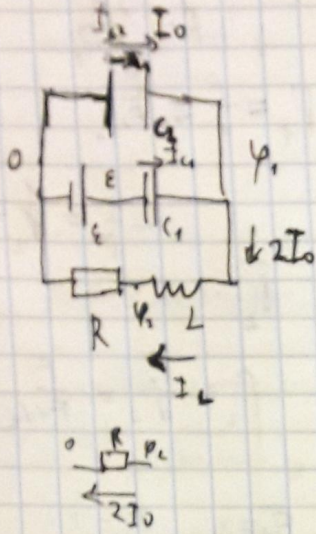
$$Q = W_{C1} + W_{C2} - W_{C1}' - W_{C2}' + A_J$$

$$= \frac{C_1(\varepsilon - \varphi)^2}{2} + \frac{C_2 \varphi^2}{2} - \frac{C_1 \varepsilon^2}{2} - 0 + dJ \cdot E =$$

$$= \frac{1}{2} C \frac{25}{36} \varepsilon^2 + \frac{1}{2} C \frac{5}{36} \varepsilon^2 - \frac{1}{2} C \varepsilon^2 + \frac{1}{2} C \varepsilon \frac{1}{3} =$$

$$= \frac{1}{2} C \varepsilon^2 \left( \frac{25}{36} + \frac{5}{36} - \frac{36}{36} + \frac{12}{36} \right) = \frac{1}{2} C \varepsilon^2 \left( \frac{6}{36} \right) = \frac{1}{12} C \varepsilon^2$$

g)



$$I_C = C U_C' = C \varphi_1'$$

$$U_C = C I_C'$$

$$I_{C2} = -C U_{C2}' = -C \varphi_1'$$

$$I_{C1} = C U_{C1}' = C(\varepsilon - \varphi_1)' = -C \varphi_1' = I_{C2} = I_0$$

$$\varphi_2 = 2I_0 R$$

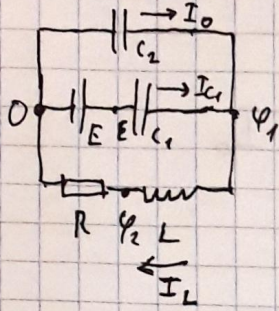
$$U_R = 2I_0 R$$



Устройство (2)

№3

4) рассчитать ток, когда  $I_{C2} = I_0$



$$I_C = C U_C'$$

$$I_{C2} = -C U_{C2}' = -C \varphi_1'$$

$$I_{C1} = C U_{C1}' = C(\varepsilon - \varphi_1)' = -C \varphi_1' = I_{C2} = I_0$$

$$I_L = I_{C1} + I_{C2} = 2I_0 = I_R$$

$$U_R = R I_R = 2I_0 R$$

Ответ: 1)  $I_C' = \frac{\varepsilon}{6L}$

2)  $Q = \frac{\varepsilon \varepsilon^2}{12}$

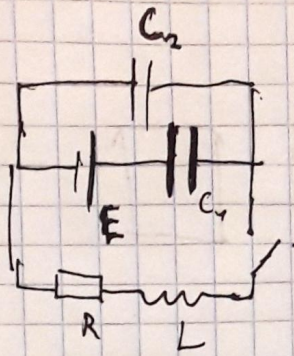
3)  $U_R = 2I_0 R$



# Упробна

$$C_1 = C$$

$$C_2 = 5C$$



1)  $I_L$  -?  $t=0$

2)  $Q$  -?  $t_0 \rightarrow \infty$

3)  $t$ :  $I_{C2} = I_0$

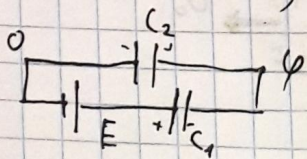
$U_R$  -?

$$I_C = C \dot{U}_C$$

$$U_L = L \dot{I}_L$$

~~Индукция не меняется~~  
~~Индукция не меняется~~

о) при каком положении переключателя ток равен 0



$$U = E$$

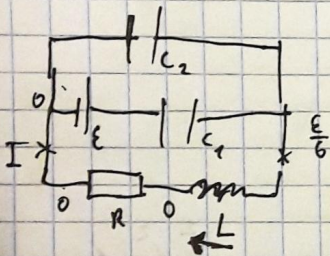
$$+C_2 \phi - C_1 (E - \phi) = 0$$

$$5C \phi = CE - C \phi$$

$$6C \phi = CE \quad 6\phi = E \quad \phi = \frac{E}{6}$$

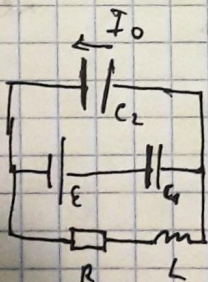
1)  $t=0$

$I_L$  индукция не меняет  
 $U_C$  индукция не меняет



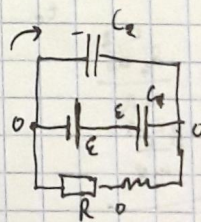
$$U_L = L \dot{I}_L \quad \left( \dot{I}_L = \frac{U_L}{L} = \frac{E}{6L} \right)$$

2)



$t \rightarrow \infty$

генератор переключ.



$$q_- = -C_2 \phi = -C_2 \frac{E}{6} = -\frac{5CE}{6}$$

$$q_+ = +C_1 (E - \phi) = \frac{5CE}{6}$$

$$q_+ = +C_1 E = CE$$

